

Simple Harmonic Motion (SHM)

Overview
(Ref p368)

Terminology for Periodic Motion

- **Period (T)**
 - The time, in seconds, it takes for a vibrating object to repeat its motion – seconds per vibration, oscillation or cycle
- **Frequency (f)**
 - The number of vibrations made per unit time – vibration, oscillation or cycles per second (Hz)
- **$T = 1/f$**
 - The relationship is **reciprocal**
- **Amplitude (A or x)**
 - The displacement from rest position

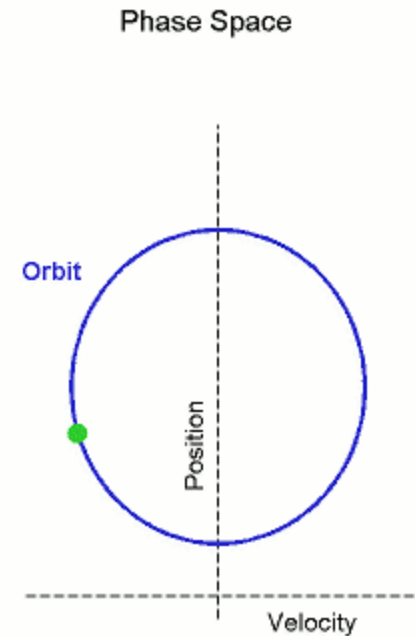
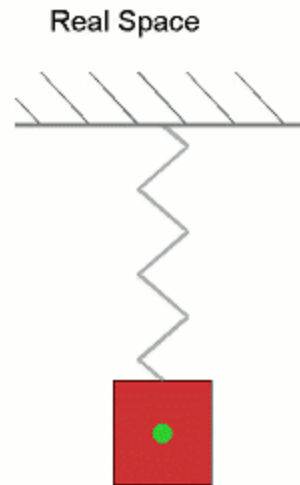
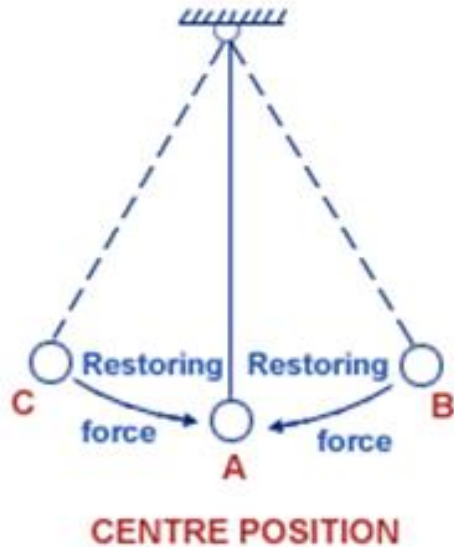
SHM - Description

- An object is said to be in simple harmonic motion if the following occurs:
 - It moves in a uniform path.
 - A variable force acts on it.
 - The magnitude of force is proportional to the displacement of the mass.
 - The force is always opposite in direction to the displacement direction.
 - The motion is repetitive and a round trip, back and forth, is always made in equal time periods.

SHM Visually

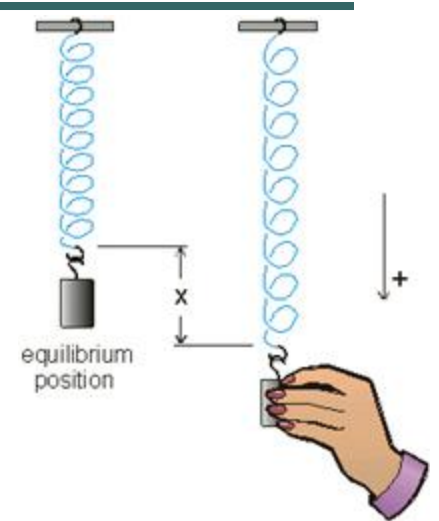
- Examples

- Spring
- Pendulum



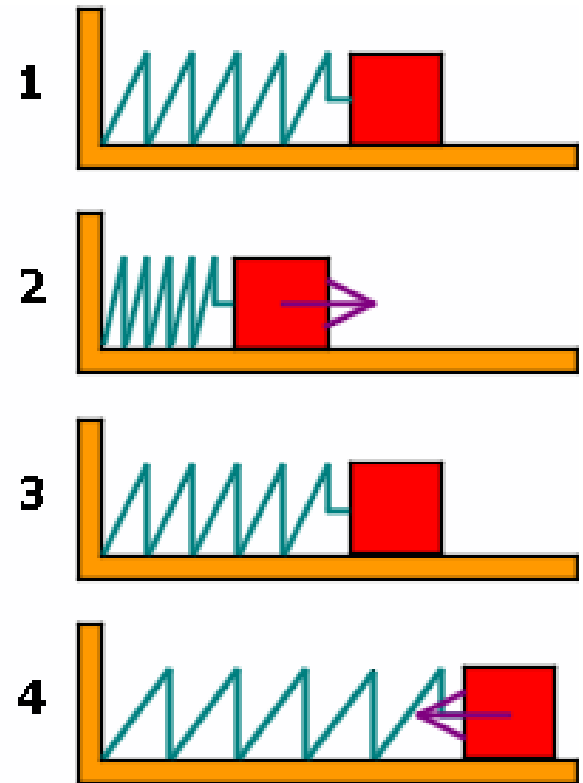
SHM – Hooke's Law

- SHM describes any **periodic** motion that results from a **restoring** force (F) that is proportional to the **displacement** (x) of an object from its equilibrium position.
- $F_{\text{rest}} = -kx$, where k = spring constant
- **Note:**
 - **Elastic limit** – if exceeded, the spring does **not** return to its original shape
- Law applies equally to horizontal and vertical models



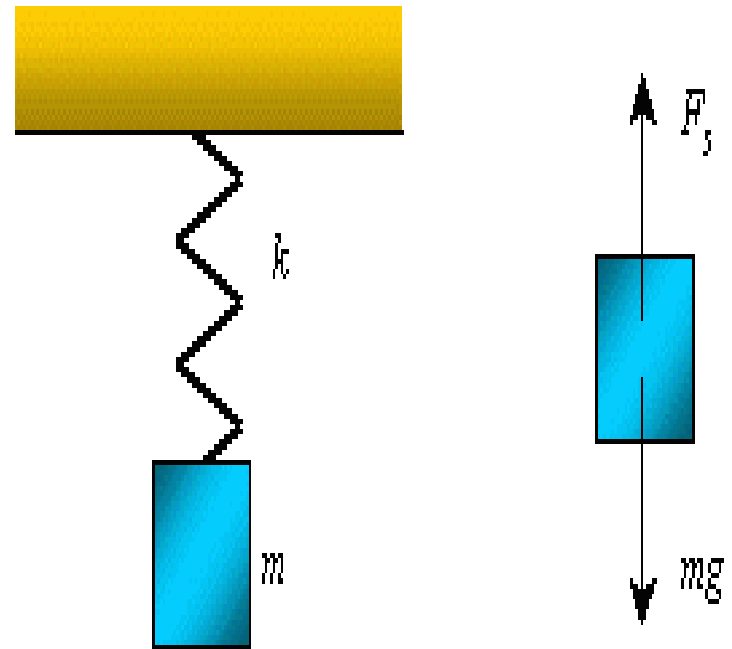
Hooke's Law – Horizontal Springs

- At max displacement (2 & 4), spring **force** and **acceleration** reach a maximum and velocity (thus KE) is zero.
- At zero displacement (1 & 3) PE is zero, thus KE and velocity are maximum
- The **larger** the k value the **stiffer** the spring
- **Negative** sign indicates the restoring force is opposite the displacement



Hooke's Law – Vertical Springs

- Hooke's Law applies equally to a **vertical** model of spring motion, in which the weight of the mass provides a force.
- @ Equilibrium position with no motion:
 - Spring force \uparrow = weight \downarrow



Practice

- A load of 50 N stretches a vertical spring by 0.15 m. What is the spring constant?
- Solve $F = -kx$ for k
 - $50 = -k \cdot 0.15$
 - $k = -50/0.15 = 333.3$ N/m (drop the – sign)

Mass-Spring System - Period

- The **period** of a mass-spring can be calculated as follows:

$$T = 2\pi \sqrt{\frac{\text{mass}}{\text{spring const}}}$$

$$T = 2\pi \sqrt{\frac{m}{k}}$$

Practice

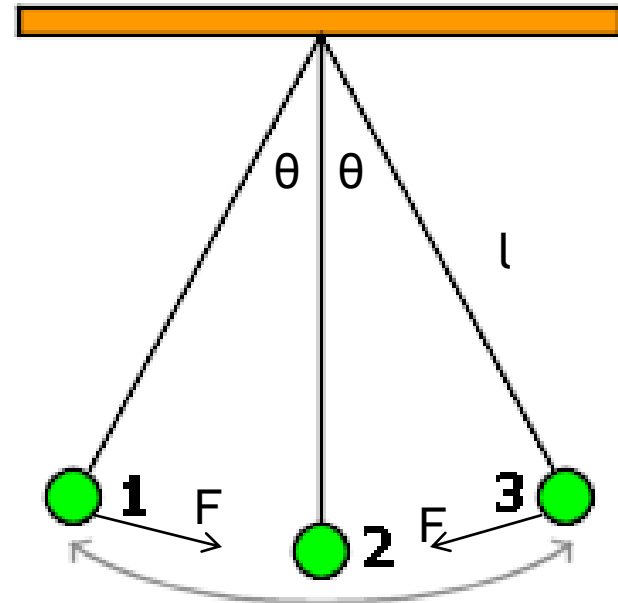
- What is the spring constant of a mass-spring system that has a mass of 0.40 kg and oscillates with a period of 0.2 secs?
- Solve $T = 2\pi\sqrt{\frac{m}{k}}$ for k
 - $0.2 = 2\pi\sqrt{(0.4/k)}$
 - $k = 394.8$ N/m

Practice

- If a mass of 0.55 kg stretches a vertical spring 2 cm from its rest position, what is the spring constant (k)?
- Solve $F = -kx$ for k (or $\Delta F = -k\Delta x$)
 - $k = F/x$, where $F = \text{weight (mg) of the mass}$
 - $k = mg/x = 0.55 \times 9.8/0.02$
 - $k = 269.5 \text{ N/m}$

SHM - Simple Pendulum

- If a pendulum of length l is disturbed through an angle θ (1 or 3), the restoring **force** (F) component drives the bob back (and through) the rest (2) position



$$Period(T) = 2\pi \sqrt{\frac{\text{length}}{\text{grav acc}}} = 2\pi \sqrt{\frac{l}{g}}$$

Practice - pendulum

- What period would you expect from a pendulum of length 0.5 m on the moon where $g = 1.6 \text{ m/s}^2$?
- Solve $T = 2\pi \sqrt{\frac{l}{g}}$
 - $T = 2\pi \sqrt{(0.5/1.6)}$
 - $T = 3.51$ seconds

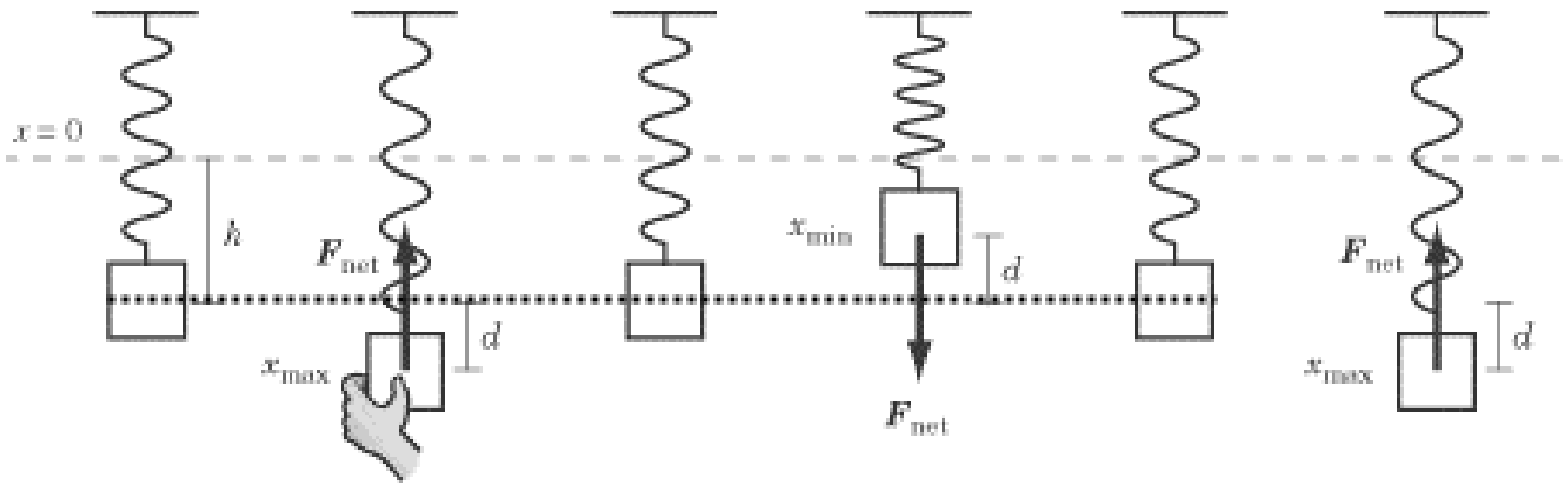
Practice - pendulum

- What is the frequency (f) of a 3 m (l) swing at the North Pole, where $g = 9.83$ m/s²?
- Solve $T = 2\pi\sqrt{l/g}$
 - $T = 2\pi\sqrt{3/9.83}$
 - $T = 3.47$ sec, therefore...
 - $f = 1/T = 0.29$ Hz

Energy Considerations for SHM

- Springs
 - **PE max** at maximum displacement
 - **KE max** while passing through the rest position

Spring Energy Summary



$$v = 0$$

$$F_{\text{net}} = 0$$

$$v = 0$$

$$F_{\text{net}} = \text{max up}$$

$$KE = 0$$

$$PE = \text{max}$$

$$v = \text{max}$$

$$F_{\text{net}} = 0$$

$$KE = \text{max}$$

$$PE = 0$$

$$v = 0$$

$$F_{\text{net}} = \text{max down}$$

$$KE = 0$$

$$PE = \text{max}$$

$$v = \text{max}$$

$$F_{\text{net}} = 0$$

$$KE = \text{max}$$

$$PE = 0$$

$$v = 0$$

$$F_{\text{net}} = \text{max up}$$

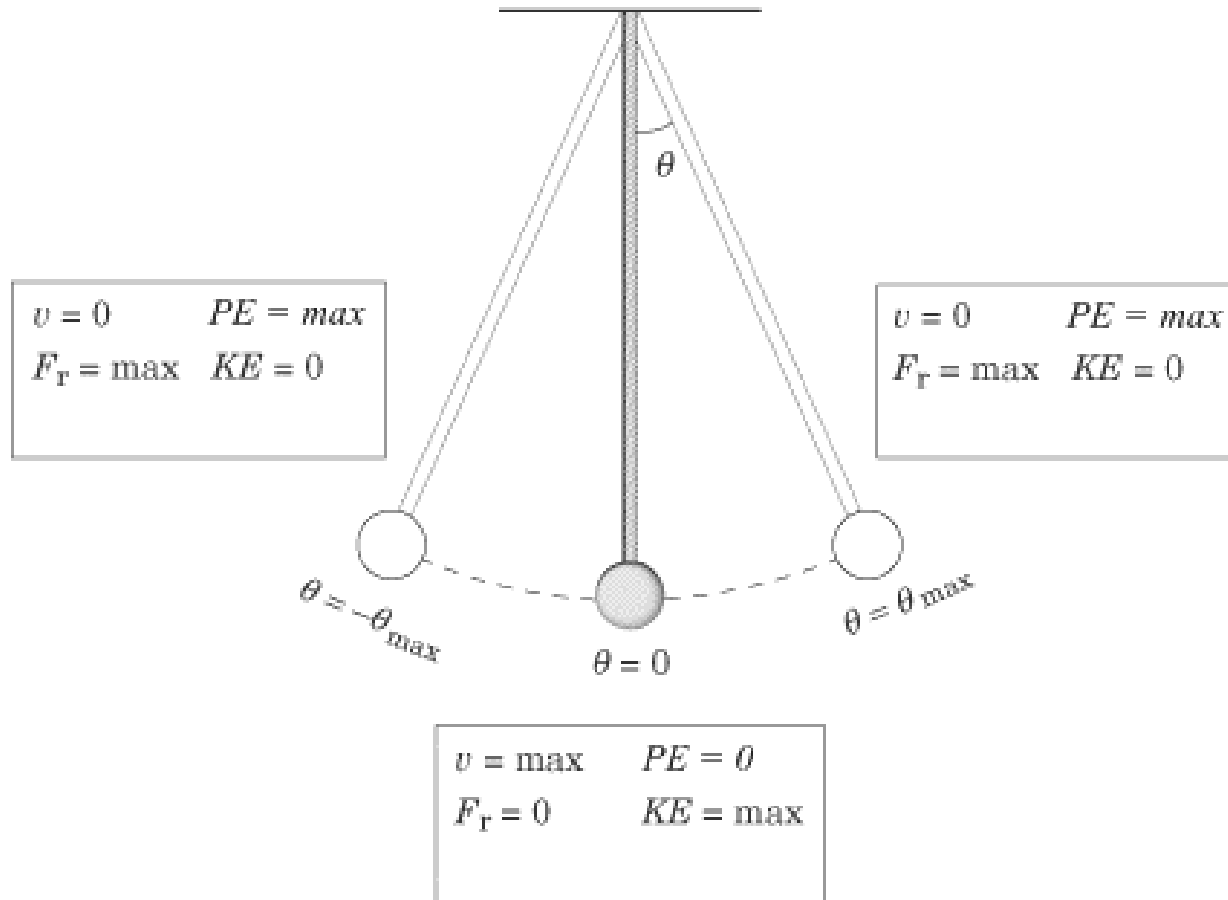
$$KE = 0$$

$$PE = \text{max}$$

- Pendulums

- PE max at maximum disturbance angle
- KE max at bottom of arc

Pendulum Energy summary



Summary formulas

- Period (T) = 1/frequency (f)
 - $T = 1/f$
- Hooke's Law
 - Force = spring const x displacement
 - $F = kx$ (*drop negative sign*)
- Spring period
 - $T = 2\pi\sqrt{(m/k)}$
- Pendulum
 - $T = 2\pi\sqrt{(l/g)}$