

Suppose that  $\mathbf{a} = \mathbf{0}$ .

- (a) If  $\mathbf{a} \cdot \mathbf{b} = \mathbf{a} \cdot \mathbf{c}$ , does it follow that  $\mathbf{b} = \mathbf{c}$ ?  
 (b) If  $\mathbf{a} \times \mathbf{b} = \mathbf{a} \times \mathbf{c}$ , does it follow that  $\mathbf{b} = \mathbf{c}$ ?  
 (c) If  $\mathbf{a} \cdot \mathbf{b} = \mathbf{a} \cdot \mathbf{c}$  and  $\mathbf{a} \times \mathbf{b} = \mathbf{a} \times \mathbf{c}$ , does it follow that  $\mathbf{b} = \mathbf{c}$ ?

54. If  $\mathbf{v}_1, \mathbf{v}_2,$  and  $\mathbf{v}_3$  are noncoplanar vectors, let

$$\mathbf{k}_1 = \frac{\mathbf{v}_2 \times \mathbf{v}_3}{\mathbf{v}_1 \cdot (\mathbf{v}_2 \times \mathbf{v}_3)} \quad \mathbf{k}_2 = \frac{\mathbf{v}_3 \times \mathbf{v}_1}{\mathbf{v}_1 \cdot (\mathbf{v}_2 \times \mathbf{v}_3)}$$

$$\mathbf{k}_3 = \frac{\mathbf{v}_1 \times \mathbf{v}_2}{\mathbf{v}_1 \cdot (\mathbf{v}_2 \times \mathbf{v}_3)}$$

(These vectors occur in the study of crystallography. Vectors of the form  $n_1\mathbf{v}_1 + n_2\mathbf{v}_2 + n_3\mathbf{v}_3$ , where each  $n_i$  is an integer, form a *lattice* for a crystal. Vectors written similarly in terms of  $\mathbf{k}_1, \mathbf{k}_2,$  and  $\mathbf{k}_3$  form the *reciprocal lattice*.)

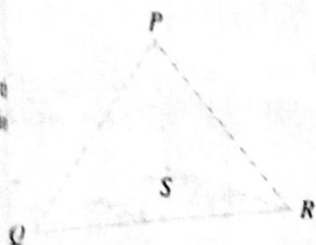
- (a) Show that  $\mathbf{k}_i$  is perpendicular to  $\mathbf{v}_j$  if  $i \neq j$ .  
 (b) Show that  $\mathbf{k}_i \cdot \mathbf{v}_i = 1$  for  $i = 1, 2, 3$ .

(c) Show that  $\mathbf{k}_1 \cdot (\mathbf{k}_2 \times \mathbf{k}_3) = \frac{1}{\mathbf{v}_1 \cdot (\mathbf{v}_2 \times \mathbf{v}_3)}$ .

## DISCOVERY PROJECT

## THE GEOMETRY OF A TETRAHEDRON

A tetrahedron is a solid with four vertices,  $P, Q, R,$  and  $S$ , and four triangular faces, as shown in the figure.



1. Let  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3,$  and  $\mathbf{v}_4$  be vectors with lengths equal to the areas of the faces opposite the vertices  $P, Q, R,$  and  $S$ , respectively, and directions perpendicular to the respective faces and pointing outward. Show that

$$\mathbf{v}_1 + \mathbf{v}_2 + \mathbf{v}_3 + \mathbf{v}_4 = \mathbf{0}$$

2. The volume  $V$  of a tetrahedron is one-third the distance from a vertex to the opposite face, times the area of that face.  
 (a) Find a formula for the volume of a tetrahedron in terms of the coordinates of its vertices  $P, Q, R,$  and  $S$ .  
 (b) Find the volume of the tetrahedron whose vertices are  $P(1, 1, 1), Q(1, 2, 3), R(1, 1, 2),$  and  $S(3, -1, 2)$ .

3. Suppose the tetrahedron in the figure has a trirectangular vertex  $S$ . (This means that the three angles at  $S$  are all right angles.) Let  $A, B,$  and  $C$  be the areas of the three faces that meet at  $S$ , and let  $D$  be the area of the opposite face  $PQR$ . Using the result of Problem 1, or otherwise, show that

$$D^2 = A^2 + B^2 + C^2$$

(This is a three-dimensional version of the Pythagorean Theorem.)

## 12.5 Equations of Lines and Planes

### Lines

A line in the  $xy$ -plane is determined when a point on the line and the direction of the line (its slope or angle of inclination) are given. The equation of the line can then be written using the point-slope form.

Likewise, a line  $L$  in three-dimensional space is determined when we know a point  $P_0(x_0, y_0, z_0)$  on  $L$  and the direction of  $L$ . In three dimensions the direction of a line is conveniently described by a vector, so we let  $\mathbf{v}$  be a vector parallel to  $L$ . Let  $P(x, y, z)$  be an arbitrary point on  $L$  and let  $\mathbf{r}_0$  and  $\mathbf{r}$  be the position vectors of  $P_0$  and  $P$  (that is, they have representations  $\overrightarrow{OP_0}$  and  $\overrightarrow{OP}$ ). If  $\mathbf{a}$  is the vector with representation  $\overrightarrow{P_0P}$ , as in Figure 1, then the Triangle Law for vector addition gives  $\mathbf{r} = \mathbf{r}_0 + \mathbf{a}$ . But, since  $\mathbf{a}$  and  $\mathbf{v}$  are parallel vectors, there is a scalar  $t$  such that  $\mathbf{a} = t\mathbf{v}$ . Thus

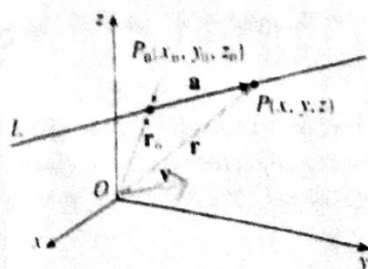


FIGURE 1

$$\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}$$

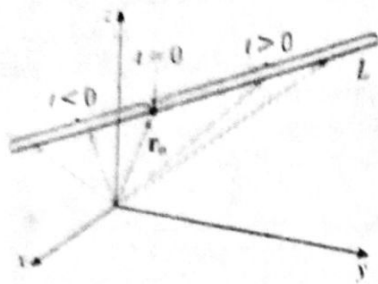


FIGURE 2

which is a **vector equation** of  $L$ . Each value of the **parameter**  $t$  gives the position of a point on  $L$ . In other words, as  $t$  varies, the line is traced out by the tip of the vector  $\mathbf{r}$ . Figure 2 indicates, positive values of  $t$  correspond to points on  $L$  that lie on the same side of  $P_0$ , whereas negative values of  $t$  correspond to points that lie on the other side.

If the vector  $\mathbf{v}$  that gives the direction of the line  $L$  is written in component form  $\mathbf{v} = \langle a, b, c \rangle$ , then we have  $t\mathbf{v} = \langle ta, tb, tc \rangle$ . We can also write  $\mathbf{r} = \langle x, y, z \rangle$  and  $\mathbf{r}_0 = \langle x_0, y_0, z_0 \rangle$ , so the vector equation (1) becomes

$$\langle x, y, z \rangle = \langle x_0 + ta, y_0 + tb, z_0 + tc \rangle$$

Two vectors are equal if and only if corresponding components are equal. Therefore, we have the three scalar equations:

$$x = x_0 + at \quad y = y_0 + bt \quad z = z_0 + ct$$

where  $t \in \mathbb{R}$ . These equations are called **parametric equations** of the line  $L$  through point  $P_0(x_0, y_0, z_0)$  and parallel to the vector  $\mathbf{v} = \langle a, b, c \rangle$ . Each value of the parameter  $t$  gives a point  $(x, y, z)$  on  $L$ .

**2** Parametric equations for a line through the point  $(x_0, y_0, z_0)$  and parallel to the direction vector  $\langle a, b, c \rangle$  are

$$x = x_0 + at \quad y = y_0 + bt \quad z = z_0 + ct$$

Figure 3 shows the line  $L$  in Example 1 and its relation to the given point and to the vector that gives its direction.

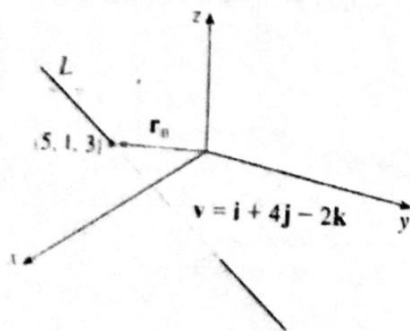


FIGURE 3

**EXAMPLE 1**

- (a) Find a vector equation and parametric equations for the line that passes through point  $(5, 1, 3)$  and is parallel to the vector  $\mathbf{i} + 4\mathbf{j} - 2\mathbf{k}$ .  
 (b) Find two other points on the line.

**SOLUTION**

(a) Here  $\mathbf{r}_0 = \langle 5, 1, 3 \rangle = 5\mathbf{i} + \mathbf{j} + 3\mathbf{k}$  and  $\mathbf{v} = \mathbf{i} + 4\mathbf{j} - 2\mathbf{k}$ , so the vector equation (1) becomes

$$\mathbf{r} = (5\mathbf{i} + \mathbf{j} + 3\mathbf{k}) + t(\mathbf{i} + 4\mathbf{j} - 2\mathbf{k})$$

or

$$\mathbf{r} = (5 + t)\mathbf{i} + (1 + 4t)\mathbf{j} + (3 - 2t)\mathbf{k}$$

Parametric equations are

$$x = 5 + t \quad y = 1 + 4t \quad z = 3 - 2t$$

- (b) Choosing the parameter value  $t = 1$  gives  $x = 6$ ,  $y = 5$ , and  $z = 1$ , so  $(6, 5, 1)$  is a point on the line. Similarly,  $t = -1$  gives the point  $(4, -3, 5)$ .

The vector equation and parametric equations of a line are not unique. If we change the point or the parameter or choose a different parallel vector, then the equations change. For instance, if, instead of  $(5, 1, 3)$ , we choose the point  $(6, 5, 1)$  in Example 1, the parametric equations of the line become

$$x = 6 + t \quad y = 5 + 4t \quad z = 1 - 2t$$

Or, if we stay with the point  $(5, 1, 3)$  but choose the parallel vector  $2\mathbf{i} + 8\mathbf{j} - 4\mathbf{k}$ , we arrive at the equations

$$x = 5 + 2t \quad y = 1 + 8t \quad z = 3 - 4t$$

In general, if a vector  $\mathbf{v} = \langle a, b, c \rangle$  is used to describe the direction of a line  $L$ , then the numbers  $a$ ,  $b$ , and  $c$  are called **direction numbers** of  $L$ . Since any vector parallel to  $\mathbf{v}$  could also be used, we see that any three numbers proportional to  $a$ ,  $b$ , and  $c$  could also be used as a set of direction numbers for  $L$ .

Another way of describing a line  $L$  is to eliminate the parameter  $t$  from Equations 2. If none of  $a$ ,  $b$ , or  $c$  is 0, we can solve each of these equations for  $t$ :

$$t = \frac{x - x_0}{a} \quad t = \frac{y - y_0}{b} \quad t = \frac{z - z_0}{c}$$

Equating the results, we obtain

3

$$\frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c}$$

These equations are called **symmetric equations** of  $L$ . Notice that the numbers  $a$ ,  $b$ , and  $c$  that appear in the denominators of Equations 3 are direction numbers of  $L$ , that is, components of a vector parallel to  $L$ . If one of  $a$ ,  $b$ , or  $c$  is 0, we can still eliminate  $t$ . For instance, if  $a = 0$ , we could write the equations of  $L$  as

$$x = x_0 \quad \frac{y - y_0}{b} = \frac{z - z_0}{c}$$

This means that  $L$  lies in the vertical plane  $x = x_0$ .

### EXAMPLE 2

- (a) Find parametric equations and symmetric equations of the line that passes through the points  $A(2, 4, -3)$  and  $B(3, -1, 1)$ .  
 (b) At what point does this line intersect the  $xy$ -plane?

#### SOLUTION

- (a) We are not explicitly given a vector parallel to the line, but observe that the vector  $\mathbf{v}$  with representation  $\overrightarrow{AB}$  is parallel to the line and

$$\mathbf{v} = \langle 3 - 2, -1 - 4, 1 - (-3) \rangle = \langle 1, -5, 4 \rangle$$

Thus direction numbers are  $a = 1$ ,  $b = -5$ , and  $c = 4$ . Taking the point  $(2, 4, -3)$  as  $P_0$ , we see that parametric equations (2) are

$$x = 2 + t \quad y = 4 - 5t \quad z = -3 + 4t$$

and symmetric equations (3) are

$$\frac{x - 2}{1} = \frac{y - 4}{-5} = \frac{z + 3}{4}$$

- (b) The line intersects the  $xy$ -plane when  $z = 0$ , so we put  $z = 0$  in the symmetric equations and obtain

$$\frac{x - 2}{1} = \frac{y - 4}{-5} = \frac{3}{4}$$

This gives  $x = \frac{11}{4}$  and  $y = \frac{1}{4}$ , so the line intersects the  $xy$ -plane at the point  $(\frac{11}{4}, \frac{1}{4}, 0)$ . ■

Figure 4 shows the line  $L$  in Example 2 and the point  $P$  where it intersects the  $xy$ -plane.

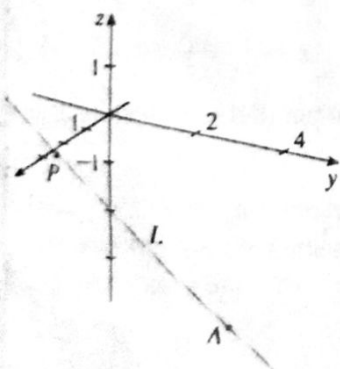


FIGURE 4

In general, the procedure of Example 2 shows that direction numbers of a line through the points  $P_0(x_0, y_0, z_0)$  and  $P_1(x_1, y_1, z_1)$  are  $x_1 - x_0$ ,  $y_1 - y_0$ , and  $z_1 - z_0$ . The symmetric equations of  $L$  are

$$\frac{x - x_0}{x_1 - x_0} = \frac{y - y_0}{y_1 - y_0} = \frac{z - z_0}{z_1 - z_0}$$

Often, we need a description, not of an entire line, but of just a line segment. For instance, could we describe the line segment  $AB$  in Example 2? If we put  $t = 1$  in the parametric equations in Example 2(a), we get the point  $(2, 4, -3)$  and if we put  $t = 0$ , we get  $(3, -1, 1)$ . So the line segment  $AB$  is described by the parametric equations

$$x = 2 + t \quad y = 4 - 5t \quad z = -3 + 4t \quad 0 \leq t \leq 1$$

or by the corresponding vector equation

$$\mathbf{r}(t) = \langle 2 + t, 4 - 5t, -3 + 4t \rangle \quad 0 \leq t \leq 1$$

In general, we know from Equation 1 that the vector equation of a line through the point  $\mathbf{r}_0$  in the direction of a vector  $\mathbf{v}$  is  $\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}$ . If the line also passes through the point  $\mathbf{r}_1$ , then we can take  $\mathbf{v} = \mathbf{r}_1 - \mathbf{r}_0$  and so its vector equation is

$$\mathbf{r} = \mathbf{r}_0 + t(\mathbf{r}_1 - \mathbf{r}_0) = (1 - t)\mathbf{r}_0 + t\mathbf{r}_1$$

The line segment from  $\mathbf{r}_0$  to  $\mathbf{r}_1$  is given by the parameter interval  $0 \leq t \leq 1$ .

**4** The line segment from  $\mathbf{r}_0$  to  $\mathbf{r}_1$  is given by the vector equation

$$\mathbf{r}(t) = (1 - t)\mathbf{r}_0 + t\mathbf{r}_1 \quad 0 \leq t \leq 1$$

**EXAMPLE 3** Show that the lines  $L_1$  and  $L_2$  with parametric equations

$$L_1: \quad x = 1 + t \quad y = -2 + 3t \quad z = 4 - t$$

$$L_2: \quad x = 2s \quad y = 3 + s \quad z = -3 + 4s$$

are **skew lines**; that is, they do not intersect and are not parallel (and therefore do not lie in the same plane).

**SOLUTION** The lines are not parallel because the corresponding direction vectors  $\langle 1, 3, -1 \rangle$  and  $\langle 2, 1, 4 \rangle$  are not parallel. (Their components are not proportional.) If the lines had a point of intersection, there would be values of  $t$  and  $s$  such that

$$1 + t = 2s$$

$$-2 + 3t = 3 + s$$

$$4 - t = -3 + 4s$$

But if we solve the first two equations, we get  $t = \frac{11}{5}$  and  $s = \frac{8}{5}$ , and these values do not satisfy the third equation. Therefore there are no values of  $t$  and  $s$  that satisfy all three equations, so  $L_1$  and  $L_2$  do not intersect. Thus  $L_1$  and  $L_2$  are skew lines.

## ■ Planes

Although a line in space is determined by a point and a direction, a plane is more difficult to describe. A single vector parallel to a plane is not enough to

"direction" of the plane, but a vector perpendicular to the plane does completely specify its direction. Thus a plane in space is determined by a point  $P_0(x_0, y_0, z_0)$  in the plane and a vector  $\mathbf{n}$  that is orthogonal to the plane. This orthogonal vector  $\mathbf{n}$  is called a **normal vector**. Let  $P(x, y, z)$  be an arbitrary point in the plane, and let  $\mathbf{r}_0$  and  $\mathbf{r}$  be the position vectors of  $P_0$  and  $P$ . Then the vector  $\mathbf{r} - \mathbf{r}_0$  is represented by  $\overrightarrow{P_0P}$ . (See Figure 6.) The normal vector  $\mathbf{n}$  is orthogonal to every vector in the given plane. In particular,  $\mathbf{n}$  is orthogonal to  $\mathbf{r} - \mathbf{r}_0$  and so we have

5

$$\mathbf{n} \cdot (\mathbf{r} - \mathbf{r}_0) = 0$$

which can be rewritten as

6

$$\mathbf{n} \cdot \mathbf{r} = \mathbf{n} \cdot \mathbf{r}_0$$

Either Equation 5 or Equation 6 is called a **vector equation of the plane**.

To obtain a scalar equation for the plane, we write  $\mathbf{n} = \langle a, b, c \rangle$ ,  $\mathbf{r} = \langle x, y, z \rangle$ , and  $\mathbf{r}_0 = \langle x_0, y_0, z_0 \rangle$ . Then the vector equation (5) becomes

$$\langle a, b, c \rangle \cdot \langle x - x_0, y - y_0, z - z_0 \rangle = 0$$

or

$$a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$$

**7** A scalar equation of the plane through point  $P_0(x_0, y_0, z_0)$  with normal vector  $\mathbf{n} = \langle a, b, c \rangle$  is

$$a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$$

**EXAMPLE 4** Find an equation of the plane through the point  $(2, 4, -1)$  with normal vector  $\mathbf{n} = \langle 2, 3, 4 \rangle$ . Find the intercepts and sketch the plane.

**SOLUTION** Putting  $a = 2$ ,  $b = 3$ ,  $c = 4$ ,  $x_0 = 2$ ,  $y_0 = 4$ , and  $z_0 = -1$  in Equation 7, we see that an equation of the plane is

$$2(x - 2) + 3(y - 4) + 4(z + 1) = 0$$

or

$$2x + 3y + 4z = 12$$

To find the  $x$ -intercept we set  $y = z = 0$  in this equation and obtain  $x = 6$ . Similarly, the  $y$ -intercept is 4 and the  $z$ -intercept is 3. This enables us to sketch the portion of the plane that lies in the first octant (see Figure 7). ■

By collecting terms in Equation 7 as we did in Example 4, we can rewrite the equation of a plane as

8

$$ax + by + cz + d = 0$$

where  $d = -(ax_0 + by_0 + cz_0)$ . Equation 8 is called a **linear equation** in  $x$ ,  $y$ , and  $z$ . Conversely, it can be shown that if  $a$ ,  $b$ , and  $c$  are not all 0, then the linear equation (8) represents a plane with normal vector  $\langle a, b, c \rangle$ . (See Exercise 83.)

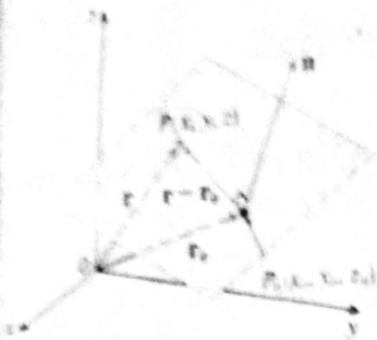


FIGURE 6

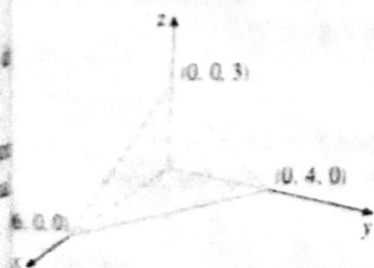


FIGURE 7

Figure 8 shows the portion of the plane in Example 5 that is enclosed by triangle  $PQR$ .

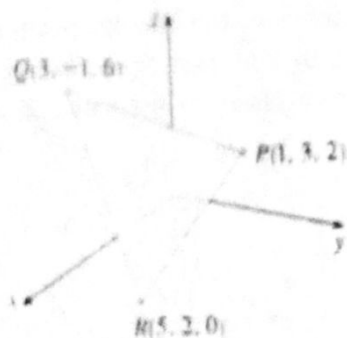


FIGURE 8

**EXAMPLE 5** Find an equation of the plane that passes through the points  $P(1, 3, 2)$ ,  $Q(3, -1, 6)$ , and  $R(5, 2, 0)$ .

**SOLUTION** The vectors  $\mathbf{a}$  and  $\mathbf{b}$  corresponding to  $\vec{PQ}$  and  $\vec{PR}$  are

$$\mathbf{a} = \langle 2, -4, 4 \rangle \quad \mathbf{b} = \langle 4, -1, -2 \rangle$$

Since both  $\mathbf{a}$  and  $\mathbf{b}$  lie in the plane, their cross product  $\mathbf{a} \times \mathbf{b}$  is orthogonal to the plane and can be taken as the normal vector. Thus

$$\mathbf{n} = \mathbf{a} \times \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 2 & -4 & 4 \\ 4 & -1 & -2 \end{vmatrix} = 12\mathbf{i} + 20\mathbf{j} + 14\mathbf{k}$$

With the point  $P(1, 3, 2)$  and the normal vector  $\mathbf{n}$ , an equation of the plane is

$$12(x - 1) + 20(y - 3) + 14(z - 2) = 0$$

or

$$6x + 10y + 7z = 50$$

**EXAMPLE 6** Find the point at which the line with parametric equations  $x = 2 + 3t$ ,  $y = -4t$ ,  $z = 5 + t$  intersects the plane  $4x + 5y - 2z = 18$ .

**SOLUTION** We substitute the expressions for  $x$ ,  $y$ , and  $z$  from the parametric equations into the equation of the plane:

$$4(2 + 3t) + 5(-4t) - 2(5 + t) = 18$$

This simplifies to  $-10t = 20$ , so  $t = -2$ . Therefore the point of intersection occurs when the parameter value is  $t = -2$ . Then  $x = 2 + 3(-2) = -4$ ,  $y = -4(-2) = 8$ ,  $z = 5 - 2 = 3$  and so the point of intersection is  $(-4, 8, 3)$ .

Two planes are **parallel** if their normal vectors are parallel. For instance, the planes  $x + 2y - 3z = 4$  and  $2x + 4y - 6z = 3$  are parallel because their normal vectors  $\mathbf{n}_1 = \langle 1, 2, -3 \rangle$  and  $\mathbf{n}_2 = \langle 2, 4, -6 \rangle$  and  $\mathbf{n}_2 = 2\mathbf{n}_1$ . If two planes are not parallel, they intersect in a straight line and the angle between the two planes is defined as the acute angle between their normal vectors (see angle  $\theta$  in Figure 9).

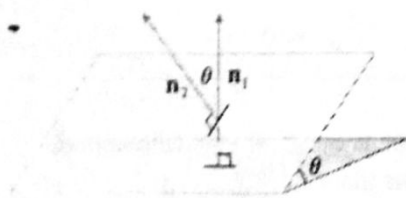


FIGURE 9

Figure 10 shows the planes in Example 7 and their line of intersection  $L$ .

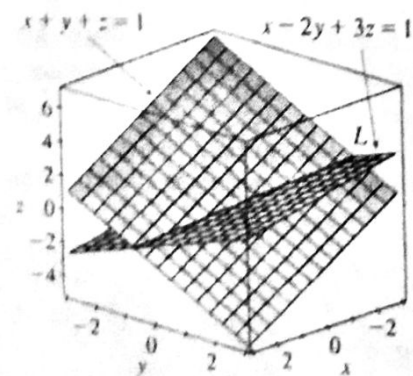


FIGURE 10

**EXAMPLE 7**

- Find the angle between the planes  $x + y + z = 1$  and  $x - 2y + 3z = 1$ .
- Find symmetric equations for the line of intersection  $L$  of these two planes.

**SOLUTION**

- The normal vectors of these planes are

$$\mathbf{n}_1 = \langle 1, 1, 1 \rangle \quad \mathbf{n}_2 = \langle 1, -2, 3 \rangle$$

and so, if  $\theta$  is the angle between the planes, Corollary 12.3.6 gives

$$\cos \theta = \frac{\mathbf{n}_1 \cdot \mathbf{n}_2}{\|\mathbf{n}_1\| \|\mathbf{n}_2\|} = \frac{1(1) + 1(-2) + 1(3)}{\sqrt{1+1+1} \sqrt{1+4+9}} = \frac{2}{\sqrt{42}}$$

$$\theta = \cos^{-1}\left(\frac{2}{\sqrt{42}}\right) \approx 72^\circ$$

- We first need to find a point on  $L$ . For instance, we can find the point where the line intersects the  $xy$ -plane by setting  $z = 0$  in the equations of both planes. This gives