

According to 1st eq of motion

$$\frac{dx}{dt} = at + u$$

$$dx = (at + u) dt$$

$$dx = at dt + u dt$$

Now integrate

$$\int dx = \int at dt + \int u dt$$

$$x = \frac{at^2}{2} + ut + B \rightarrow (3)$$

According to boundary condition
At $t=0$ $x=0$

Now eq (3) becomes

$$0 = 0 + 0 + B$$

$$B = 0$$

$$x = \frac{at^2}{2} + ut + 0$$

$$x = ut + \frac{at^2}{2}$$

$$s = v_i t$$

$$s = v_i t + \frac{1}{2} at^2$$

$$\int a dx = \int v dv$$

$$ax = \frac{v^2}{2} + c \rightarrow (4)$$

at b.c $t=0$ $x=0$
 $v=U$ $v^2=U^2$

$$0 = \frac{U^2}{2} + c$$

$$c = -\frac{U^2}{2}$$

Third eq of motion

$$a = \frac{dv}{dt}$$

∴ and 'y' by dx

$$a = \frac{dv}{dt} \times \frac{dx}{dx}$$

$$\vec{a} = \frac{dv}{dx} \cdot \frac{dx}{dt}$$

$$\vec{a} = \frac{dv}{dx} \cdot \vec{v}$$

$$a dx = v dv$$

$$ax = \frac{v^2}{2} - \frac{U^2}{2}$$

$$ax = \frac{v^2}{2} - \frac{U^2}{2}$$

$$ax = \frac{v^2 - U^2}{2}$$

$$2ax = v^2 - U^2$$

$$2as = v_f^2 - v_i^2$$

① First Eq of motion :-
 ⇒ Consider an object is moving with initial velocity "U" After certain velocity becomes "V" by definition of acceleration.

$$\vec{a} = \frac{d\vec{v}}{dt} \Rightarrow \frac{d}{dt} \left(\frac{dx}{dt} \right)$$

$$\vec{a} dt = d \left(\frac{dx}{dt} \right)$$

⇒ Now integrated both sides

$$\int a dt = \int d \left(\frac{dx}{dt} \right)$$

$$at + A = \frac{dx}{dt} \Rightarrow$$

↓
constant of integration

⇒ $\frac{dx}{dt} = at + A \rightarrow (1)$
 according to boundary condition

⇒ at $t=0$ $\frac{dx}{dt} = U$

$$\frac{dx}{dt} = at + A$$

$$U = 0 + A \Rightarrow U = A \rightarrow (2)$$

$$\frac{dx}{dt} = at + U \rightarrow (2)$$

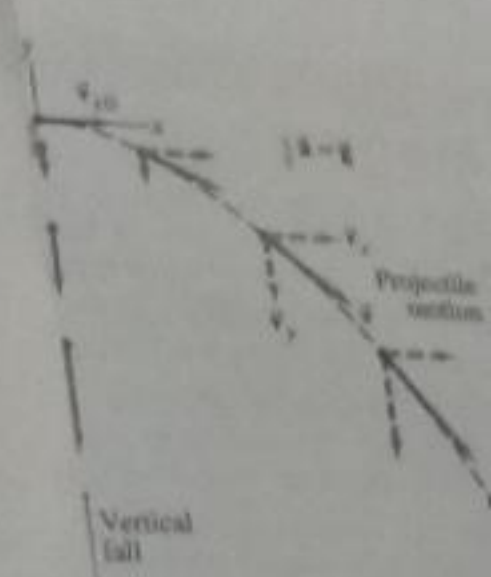
⇒ At any time 't'

$$\frac{dx}{dt} = V$$

$$V = at + U$$

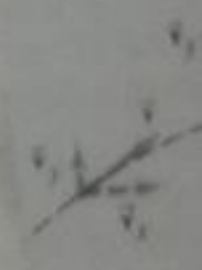
$$V = U + at$$

Final initial



... table (at $t = 0$), it expe...
 ... ion due to gravity. Thus...
 ... the downward direction...
 ... upward. Then $a_x = -g$...
 ... $v_{y0} = 0$. The vertical di...
 ... horizontal direction, on t...
 ... distance). With $a_x = 0$,...
 ... al to its initial value,...
 ... path. The horizontal d...
 ... ments, v_x and v_y , can...
 ... that time (that is, for...
 ... all of this analysis, w...
 ... rizontally will reach...
 ... is because the...
 ... 3-20. Figure 3-21...
 ... nfirm this.

Return to the Chap...
 ... why you may have...
 ... ect is projected...
 ... pt that now the...
 ... the downward...
 ... radially decrease...
 ... at which point...
 ... and v_y increas...
 ... (are negative). A



Projectile Motion:

(2)

• Projectile:-

A body or ball which make an angle with the horizontal is know as projectile.
• Since angle with the horizontal may be above or may be below.

• Projectile Motion:

The motion of body along two perpendicular axes at the same time is know a projectile motion.

• Trajectory:-

The path followed by the projectile in its flight is know as trajectory.

• Types of Projectile motion:-

- (i) Linear projectile (ii) Oblique projectile

• In linear projectile angle is 'Zero'

• In oblique projectile $\theta > 0$

Example of linear projectile

• ball through at zero angle that is linear projectile

Foot ball through its angle $\theta > 0$ is oblique projectile.

Motion in one dimension:-

(1)

- The motion of a body along horizontal or vertical, that is along x-axis or along y-axis is known as one dimensional motion.
- Motion of a car along straight road
- The motion of a ball along ground either Cartesian co-ordinate axis, x or y axes.

Motion in two dimension:-

The motion of a body along two perpendicular axes at the same time that is along two perpendicular axes 'x' and 'y' is known as motion in two dimension.

A foot ball kicked off by a player.

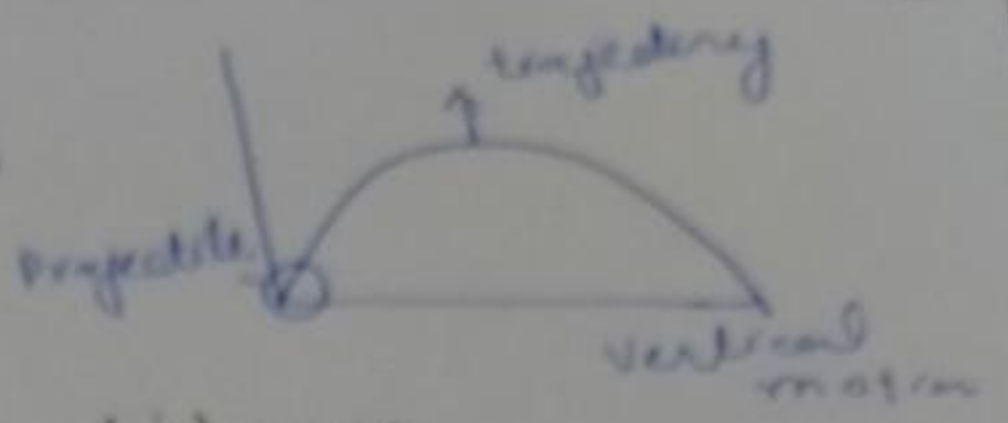
A stone thrown in air

A missile launched by launching pad.

Ball thrown by cricketer.

factors effect projectile motion.

- (i) air friction
- (ii) acceleration due to force of gravity



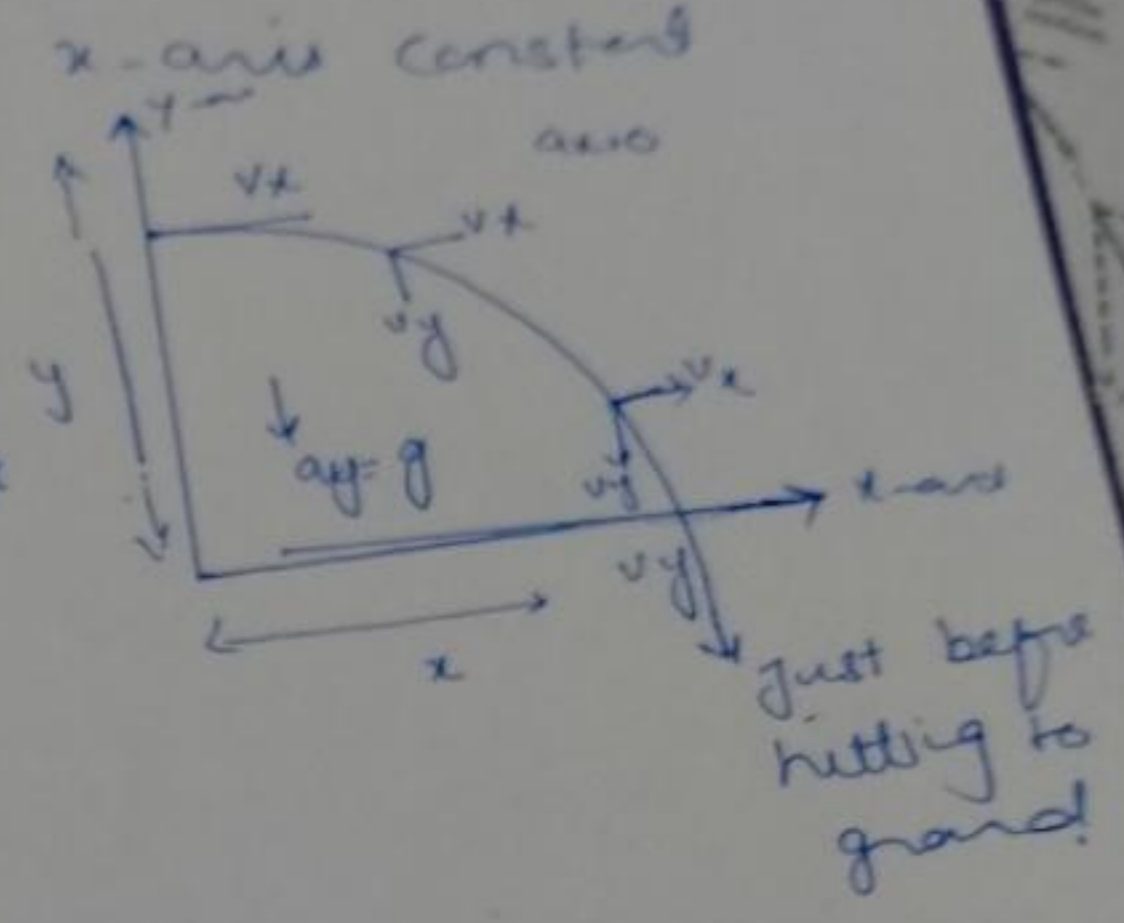
→ Horizontal and vertical distances:-

• Horizontal distance:-

velocity of projectile along x-axis constant

$S = vt \rightarrow (i)$

$V_{av} = \frac{V_i + V_f}{2}$



As velocity remains constant

along horizontal $V_i = V_f = V_x$

$V_{av} = \frac{V_x + V_x}{2} = \frac{2V_x}{2}$

$V_{av} = V_x$

Using (i)

$S = V_x t$

but $S = X$

$X = V_x t$

---→ (a)
distance:

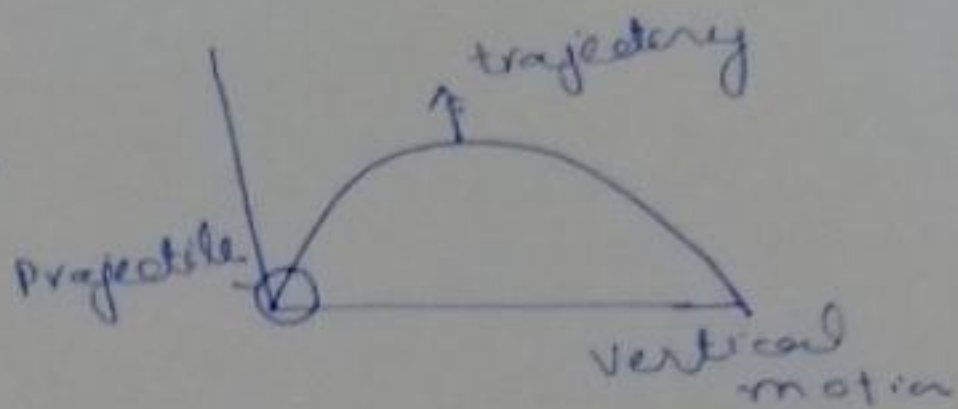
vertical

As we know

$S = vit + \frac{1}{2} at^2$

→ Factors effect projectile motion:

- (i) air friction.
- (ii) acceleration due to force of gravity.



→ Horizontal and vertical distance:-

• Horizontal distance:-

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Using (i)

$$S = V_x t$$

but $S = X$

$$\boxed{X = V_x t}$$

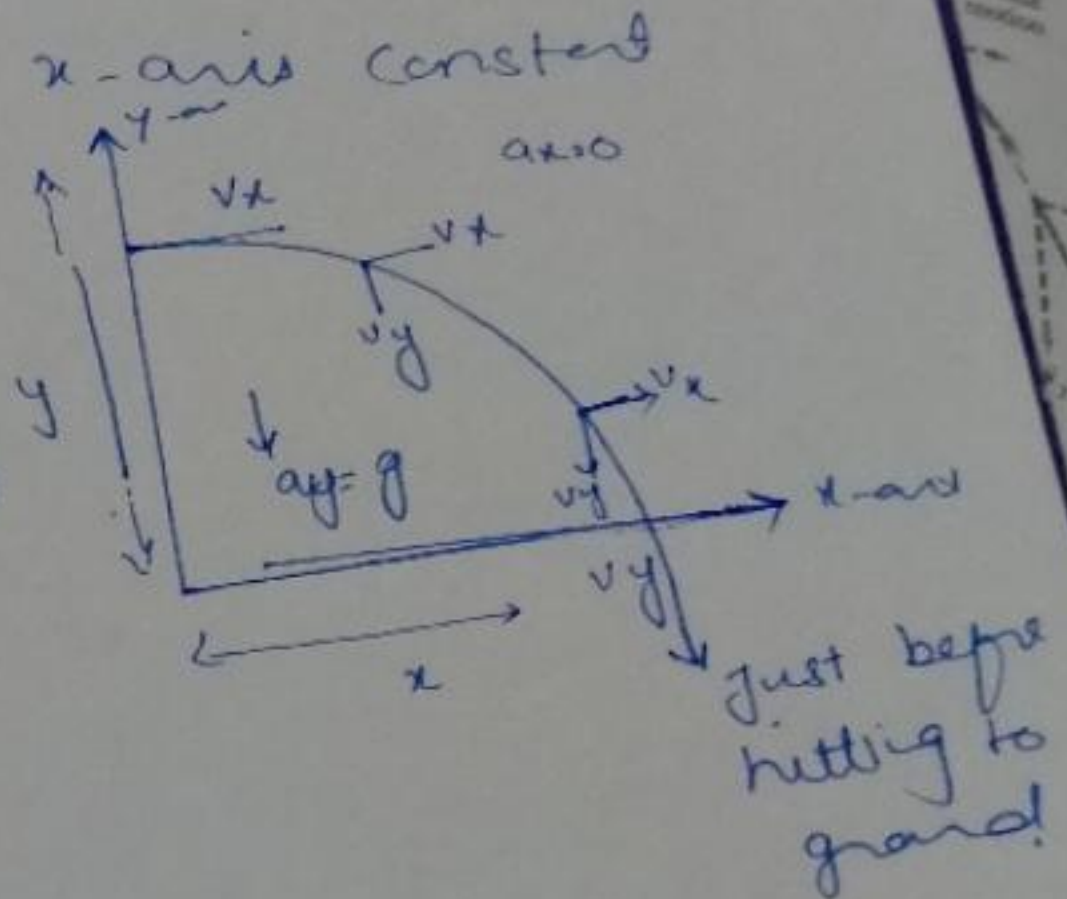
---→ (a)

distance:

vertical

As we know

$$S = vit + \frac{1}{2} at^2$$



• for vertical motion

(4)

$$S_y = v_{iy}t + \frac{1}{2} a_y t^2 \quad \because a = g$$

initially $v_{iy} = 0$

$$y = 0(t) + \frac{1}{2} a_y t^2$$

$$\boxed{y = \frac{1}{2} g t^2} \rightarrow \textcircled{b}$$

velocity of projectile at any instant: -

known v_i and θ . find velocity at time t magnitude and direction

Horizontal component of velocity: -

$$v_{ix} = v_i \cos \theta$$

By first Eq of motion horizontal motion

$$v_{fx} = v_{ix} + a_x t$$

$$a_x = 0$$

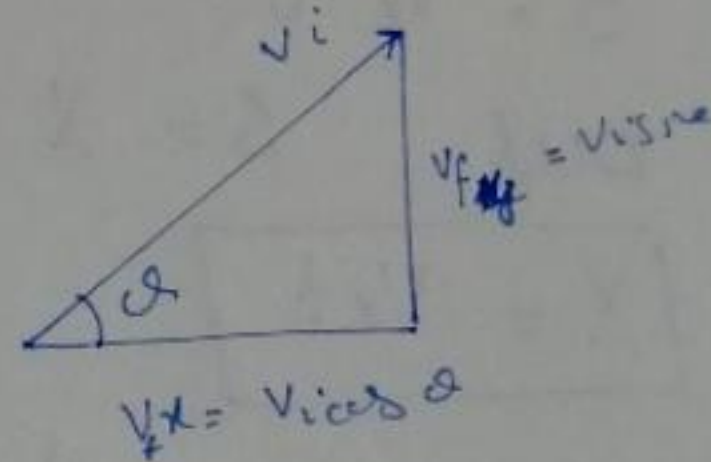
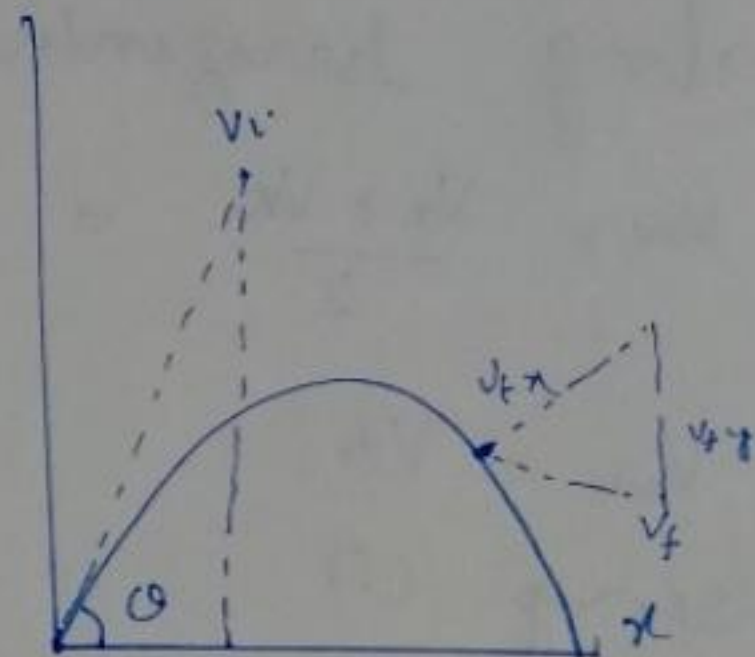
$$v_{fx} = v_{ix} + 0$$

$$v_{fx} = v_{ix}$$

$$\boxed{v_{fx} = v_i \cos \theta}$$

\because Newton first law
no acceleration in
horizontal $a_x = 0$

$$\boxed{v_{fx} = v_{ix} = v_i \cos \theta}$$



Now vertical components of velocity: -
Whereas the vertical components of velocity decreases as body moves up and it become zero at highest point. 'A'

The vertical component of velocity

(5)

$$v_{iy} = v_i \sin \alpha$$

$$v_{fy} = v_{iy} + a_y t$$

$$v_{fy} = v_i \sin \alpha + a_y t$$

$a_y = -g$ for upward motion

$$v_{zy} = v_{iy} - gt \Rightarrow \boxed{v_{zy} = v_i \sin \alpha - gt}$$

for downward motion

$$\boxed{v_{zy} = v_{iy} + gt}$$

The magnitude of velocity will be

$$v = \sqrt{v_{fx}^2 + v_{fy}^2} = \sqrt{(v_i \cos \alpha)^2 + (v_i \sin \alpha - gt)^2}$$

$$v = \sqrt{v_i^2 \cos^2 \alpha + v_i^2 \sin^2 \alpha + g^2 t^2 - 2v_i \sin \alpha gt}$$

$$v = \sqrt{v_i^2 (\underbrace{\cos^2 \alpha + \sin^2 \alpha}_{=1}) + g^2 t^2 - 2v_i \sin \alpha gt}$$

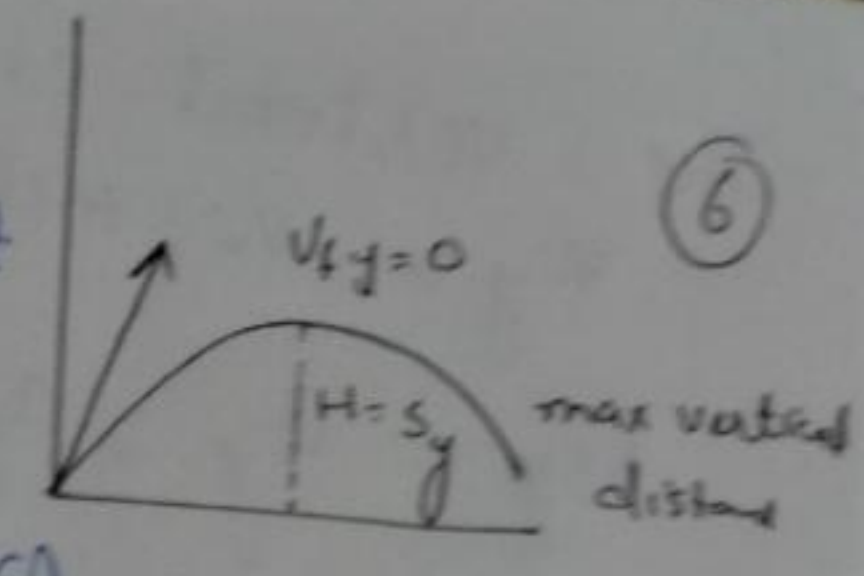
$$v = \sqrt{v_i^2 + g^2 t^2 - 2v_i \sin \alpha gt}$$

Now

$$\tan \phi = \frac{v_{zy}}{v_{zx}} = \left(\frac{v_i \sin \alpha - gt}{v_i \cos \alpha} \right)$$

Height of Projectile:

Vertical distance displacement travels by the projectile in its flight as height of



we use Eq of motion

$$2as = v_f^2 - v_i^2$$

$$s = h$$

$$a = -g$$

$$v_{iy} = v_i \sin \theta$$

$$v_{fy} = 0$$

$$2a_y s_y = v_{fy}^2 - v_{iy}^2$$

$$(2(-g)(h)) = 0 - v_i^2 \sin^2 \theta$$

$$2gh = v_i^2 \sin^2 \theta$$

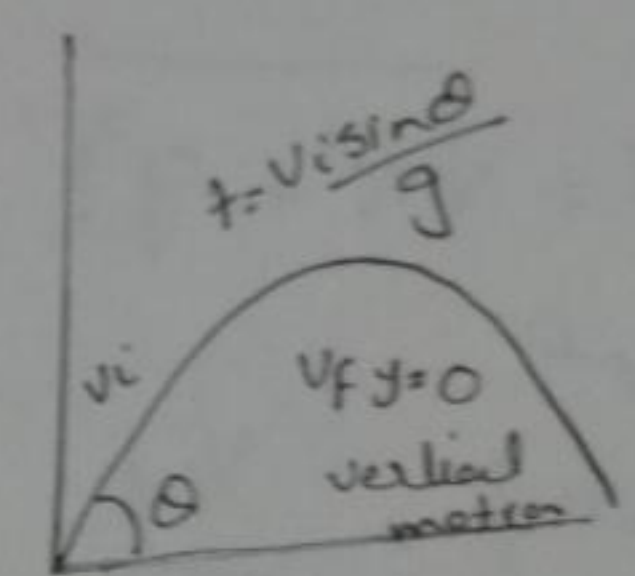
$$h = \frac{v_i^2 \sin^2 \theta}{2g}$$

Time of Flight:

is the time taken by projectile reach at

Time taken by

projectile to move from its point of projection to point



• GT is the total time for which (7)

Projectile remains in air

$$v_y = v \sin \theta, \quad a_y = -g$$

$$s = 0$$

$$t = T$$

Using second eq of motion

$$s = v_i t + \frac{1}{2} a t^2$$

$$h = v_y t + \frac{1}{2} (-g) t^2$$

$$0 = v \sin \theta T + \frac{1}{2} (-g) T^2$$

$$\frac{1}{2} g T^2 = v \sin \theta T$$

$$T = \frac{2 v \sin \theta}{g}$$

Range of Projectile:

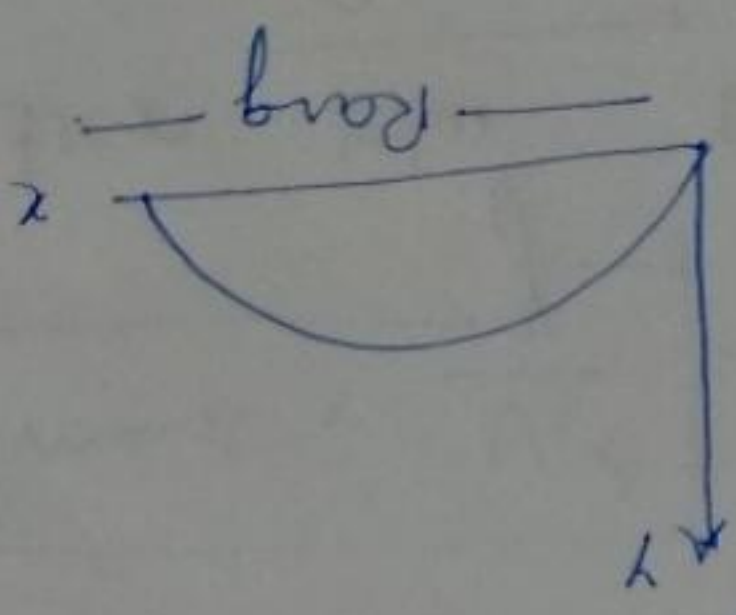
GT is the maximum horizontal

distance covered by projectile

Time of flight

$$v_x = v \cos \theta$$

$$t = T = \frac{2 v \sin \theta}{g}$$



$$s = vt$$

$$R = vt$$

$$= v \cos \theta \cdot 2v \sin \theta$$

$$R = \frac{2v^2 \sin \theta \cos \theta}{g}$$

$$2 \sin \theta \cos \theta = \sin 2\theta$$

$$R = \frac{v^2 \sin 2\theta}{g}$$

$$v^2 = \text{constant}$$

$$R \propto \sin 2\theta$$

$$\sin 2\theta = \sin^{-1}(1)$$

$$2\theta = 90^\circ$$

$$R = v^2 \sin \theta$$

$$R_{\text{max}} = \frac{v^2 \sin 2(45^\circ)}{g}$$

$$R_{\text{max}} = \frac{v^2}{g}$$

Relation b/w

$$R = 4h$$

Range and height is

\therefore maximum range of projection must be equal to $4h$