

## Canonical ~~Momentum~~ Transformation:

As we know

Hamilton's eq. is given by

$$\dot{q}_s = \frac{\partial H}{\partial p_s}$$

$$\dot{p}_s = - \frac{\partial H}{\partial q_s}$$

Transformation from  $(q_s, p_s, t)$  to  $(Q_s, P_s, t)$  is called canonical or contact transformation if  $\exists$  some fun.

$$K(Q_s, P_s, t) \text{ s.t.}$$

$$\dot{Q}_s = \frac{\partial K}{\partial P_s}$$

$$\dot{P}_s = - \frac{\partial K}{\partial Q_s}$$

Here 'K' is called Hamiltonian. K plays the role of Hamiltonian in the new variables  $Q_s, P_s$ . As Hamilton's variational principle

$$\delta \int L dt = 0$$

$$\delta \int (p_i \dot{q}_i - H) dt = 0$$

In terms of new co-ordinates,

$$\delta \int (P_i \dot{Q}_i - K) dt = 0$$

The integrands are differ by total time derivative of some fun (generating fun. F)

$$(p_i \dot{q}_i - H) - (P_i \dot{Q}_i - K) = \frac{dF}{dt} \quad (1)$$

be a fun. of old and new variables called generating function.

It has four types.

$$F_1(q, Q, t) \quad , \quad F_2(q, P, t)$$

$$F_3(p, Q, t) \quad , \quad F_4(p, P, t)$$

Let  $F = F_1(q, Q, t)$

eq. (1) becomes

$$(P_i \dot{q}_i - H) - (P_i \dot{Q}_i - K) = \frac{dF_1(q_i, Q_i, t)}{dt} \quad \text{--- (i)}$$

$$= \frac{\partial F_1}{\partial q_i} \dot{q}_i + \frac{\partial F_1}{\partial Q_i} \dot{Q}_i + \frac{\partial F_1}{\partial t} \left( \frac{dt}{dt} \right)$$

On comparing,

$$P_i = \frac{\partial F_1}{\partial q_i} \quad ; \quad -P_i = \frac{\partial F_1}{\partial Q_i}$$

$$K - H = \frac{\partial F_1}{\partial t}$$

$$\Rightarrow K = H + \frac{\partial F_1}{\partial t}$$

Using

$$\frac{\partial F_1}{\partial Q_i} = -P_i$$

$$\int \frac{\partial F_1}{\partial Q_i} dQ_i = -P_i \int dQ_i$$

$$F_1 = -P_i Q_i$$

$$F_1 + P_i Q_i = F_2 \quad \text{(say)}$$

$$F_1 = F_2 - P_i Q_i$$

Use in eq. (2)

$$(P_i \dot{q}_i - H) - (P_i \dot{Q}_i - K) = \frac{d}{dt} [F_2 - P_i Q_i]$$

$$= \frac{\partial F_2}{\partial q_i} \dot{q}_i + \frac{\partial F_2}{\partial P_i} \dot{P}_i + \frac{\partial F_2}{\partial t} - P_i \dot{Q}_i - \dot{P}_i Q_i$$

On comparing!

$$p_i = \frac{\partial F_2}{\partial \dot{q}_i} \quad ; \quad Q_i = \frac{\partial F_2}{\partial P_i}$$

we, using  $K - H = \frac{\partial F_2}{\partial t}$   
$$p_i = \frac{\partial F_1}{\partial \dot{q}_i}$$

$$\int \frac{\partial F_2}{\partial \dot{q}_i} d\dot{q}_i = \int p_i d\dot{q}_i \quad \text{or}$$
$$F_1 = p_i \dot{q}_i$$

$$F_1 - p_i \dot{q}_i = F_3 \quad (\text{say})$$

$$\frac{\partial F_1}{\partial \dot{q}_i} - p_i = 0 = \frac{\partial F_3}{\partial \dot{q}_i}$$

$$\Rightarrow F_1 - p_i \dot{q}_i = F_3 \quad ]$$

$$F_1 = F_3 + p_i \dot{q}_i$$

Use in eq (2),

$$p_i \dot{q}_i - H - (P_i Q_i - K) = \frac{d}{dt} [F_3 + p_i \dot{q}_i]$$

$$-\frac{\partial F_3}{\partial p_i} p_i + \frac{\partial F_3}{\partial Q_i} Q_i + \frac{\partial F_3}{\partial t} + \dot{p}_i \dot{q}_i + p_i \ddot{q}_i$$

comparing!

$$-P_i = \frac{\partial F_3}{\partial Q_i} \quad \& \quad -\frac{\partial F_3}{\partial P_i} = \dot{q}_i$$

$$K - H = \frac{\partial F_3}{\partial t} \Rightarrow K = H + \frac{\partial F_3}{\partial t}$$

we, using

generating functions  $F_4$  is a double Legendre transform of  $F_1$ , thus say

$$F_3 = -P_i Q_i \Rightarrow F_1 - p_i \dot{q}_i + P_i Q_i = F_4$$

$$0, \frac{\partial F_1}{\partial Q_i} = -P_i \Rightarrow F_1 = -Q_i P_i \Rightarrow F_1 + P_i Q_i = 0 \quad (\text{say})$$

$$\Rightarrow F_1 - P_i Q_i + Q_i P_i = F_4$$

$$F_4(p, P; t) = F_1(q, Q; t) - P_i q_i + P_i Q_i$$

the transformation eqs. are

$$\frac{\partial F_4}{\partial p_i} = -q_i$$

$$\frac{\partial F_4}{\partial P_i} = Q_i$$

&

$$K = H + \frac{\partial F_4}{\partial t}$$

in all these transformations, time remains untransformed quantity.

example:  $F = \sum q_i P_i$

Solve it in the form of canonical form?

1. Here  $F = F_2$

so  $p_k = \frac{\partial F_2}{\partial q_k} = \frac{\partial}{\partial q_k} (\sum q_i P_i)$

$$= \frac{\partial q_i}{\partial q_k} P_i + 0 = \delta_{ik} P_i$$

so  $p_k = P_k$

Also,  $Q_k = \frac{\partial F_2}{\partial P_k} = \frac{\partial}{\partial P_k} (\sum q_i P_i)$

$$= q_i \frac{\partial P_i}{\partial P_k} = q_i \delta_{ik}$$

so  $Q_k = q_k$

Conclusion: