

$$\int d\phi = - \int \frac{-c \sec^2 \theta}{\sqrt{1 - c^2(1 + \cot^2 \theta)}} d\theta$$

$$= - \int \frac{-c \sec^2 \theta}{\sqrt{\left(\frac{1-c^2}{c^2}\right) - \cot^2 \theta}} d\theta$$

$$\phi = \sin^{-1} \left(\frac{c \cot \theta}{\sqrt{1-c^2}} \right) + \alpha \quad (\text{a const})$$

$$\phi = \sin^{-1}(k \cot \theta) + \alpha \quad \text{where } k = \frac{c}{\sqrt{1-c^2}}$$

$$\sin^{-1}(k \cot \theta) = \alpha - \phi$$

$$k \cot \theta = \sin(\alpha - \phi)$$

$$k \left(\frac{\cos \theta}{\sin \theta} \right) = \sin \alpha \cos \phi - \cos \alpha \sin \phi$$

$$k \cos \theta = \sin \theta \sin \alpha \cos \phi - \sin \theta \cos \alpha \sin \phi$$

$$k x \cos \theta = x \sin \theta \sin \alpha \cos \phi - x \sin \theta \cos \alpha \sin \phi \quad (2)$$

where $x = r \sin \theta \cos \phi$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

so eq. (2) becomes

$$zk = x \sin \alpha - y \cos \alpha$$

which is eq. of plane through the origin
 the surface of a sphere in a great
 circle plane

Milton's Equation: - like Lagrangian $L(q, \dot{q}, t)$,
 generalized momentum (momenta) is given by

$$p_j = \frac{\partial L}{\partial \dot{q}_j}$$

function is Hamiltonian / Hamilton
 $(q, p; t)$. It means there is a change
 from $(q, \dot{q}; t)$ set to $(q, p; t)$

The Hamilton function is defined as

$$H = \sum_j \dot{q}_j \frac{\partial L}{\partial \dot{q}_j} - L = \sum_j \dot{q}_j p_j - L \quad (1)$$

where g = Legendre's transformation

J = Jacobian Integral

is obtained from Lagrangian so called
 Legendre transformation

Physical Significance of H :

As we know that

$$H = \sum_j \dot{q}_j \frac{\partial L}{\partial \dot{q}_j} - L \quad (A)$$

$$L = T - V$$

$$= T(q, \dot{q}) - V(q)$$

T does not contain time so

$$T = T_1 + T_2 + T_3$$

$$= 0 + 0 + \frac{1}{2} a_{jk} \dot{q}_j \dot{q}_k$$

$$T = \frac{1}{2} a_{jk} \dot{q}_j \dot{q}_k \quad (2)$$

$$\frac{\partial L}{\partial \dot{q}_j} = \frac{\partial T}{\partial \dot{q}_j}$$

$$= \frac{1}{2} a_{jk} (\dot{q}_k + \dot{q}_j \delta_{kj})$$

$$= \frac{1}{2} a_{jk} (\dot{q}_k + \dot{q}_k)$$

$$= \frac{1}{2} a_{jk} (2 \dot{q}_k)$$

$$\frac{\partial L}{\partial \dot{q}_j} \dot{q}_j \frac{\partial L}{\partial \dot{q}_j} = a_{jk} \dot{q}_k \dot{q}_j$$

$$= 2T \quad \text{By (2),}$$

so eq (A) becomes

$$H = 2T - (T - V)$$

$$H_{\text{comonical}} = T + V \quad \text{As Req.}$$

Hamilton's Equations of Motion:

As Hamilton is a

function of generalized co-ordinates & generalized momenta, & time is given by

$$H = H(q_j, p_j, t)$$

The total differential of Hamilton is

$$dH = \frac{\partial H}{\partial q_j} dq_j + \frac{\partial H}{\partial p_j} dp_j + \frac{\partial H}{\partial t} dt \quad (1)$$

definition of Hamilton

$$H = \dot{q}_j p_j - L(q_j, \dot{q}_j, t)$$

its total differential is

$$dH = \dot{q}_j dp_j + p_j d\dot{q}_j - \left(\frac{\partial L}{\partial q_j} dq_j + \frac{\partial L}{\partial \dot{q}_j} d\dot{q}_j + \frac{\partial L}{\partial t} dt \right) \quad (2)$$

As $\frac{\partial L}{\partial \dot{q}_j} = p_j$

so

Using $\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_j} \right) - \frac{\partial L}{\partial q_j} = 0$

* (canonical) \Rightarrow Transformation
 * Time is invariant quantity

$$\frac{d}{dt} (p_j) = \frac{\partial L}{\partial v_j}$$

$$\dot{p}_j = \frac{\partial L}{\partial v_j}$$

which is known as ^{conjugate} generalized momentum.

eq. (2) becomes

$$dH = \dot{v}_j dp_j - \dot{p}_j dv_j - \frac{\partial L}{\partial t} dt \quad (3)$$

comparing eq. (1) & (3).

$$\frac{\partial H}{\partial p_j} = \dot{v}_j \quad ; \quad \frac{\partial H}{\partial v_j} = -\dot{p}_j \quad (4)$$

eq. (4) is known as "Hamilton's canonical eqs. of motion".

Example:-

Use Hamiltonian method, obtain the eq. of motion for harmonic oscillator (one dim.)

Solution:- The Hamiltonian

$$H = \dot{v}_j p_j - L \quad (1)$$

As $T = \frac{1}{2} m \dot{x}^2$

$V = \frac{1}{2} k x^2$, in case of mass attached with a spring

so $L = T - V$

$$= \frac{1}{2} m \dot{x}^2 - \frac{1}{2} k x^2$$

Let $q = x$ so $\dot{q} = \dot{x}$

$p = \frac{\partial L}{\partial \dot{v}} = \frac{\partial L}{\partial \dot{x}} = m \dot{x}$

$\Rightarrow \dot{x} = \frac{p}{m}$

So

$$V = \frac{1}{2} kx^2$$

eq. (1) becomes

$$H = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} kx^2$$

$$H = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} kx^2 = T + V$$

$$H = \frac{1}{2} m \left(\frac{p}{m} \right)^2 + \frac{1}{2} kx^2$$

$$H = \frac{1}{2} \frac{p^2}{m} + \frac{1}{2} kx^2 \quad \text{--- (2)}$$

Using canonical eq. of motion,

$$\frac{\partial H}{\partial p_j} = \dot{q}_j \quad ; \quad \frac{\partial H}{\partial q_j} = -\dot{p}_j$$

$$\text{ie, } \frac{\partial H}{\partial p} = \dot{x} \quad ; \quad \frac{\partial H}{\partial x} = -\dot{p} \quad \text{--- (3)}$$

From eq. (2),

$$\frac{\partial H}{\partial p} = \frac{p}{m} = \dot{x} \quad \Rightarrow \quad p = m\dot{x}$$
$$p \quad \frac{\partial H}{\partial x} = kx = -\dot{p}$$

$$\text{So as } p = m\dot{x}$$

$$\text{So } \dot{p} = m\ddot{x}$$

$$\text{As } -\dot{p} = kx$$

$$\Rightarrow m\ddot{x} = -kx$$

$$\Rightarrow F = -kx$$

Example: A mass 'm' is placed on a frictionless plane which is tangent to the surface of the earth. Determine the (Hamilton's) eq. of motion using Hamilton's method?