

# Chapter 5

## LINE, SURFACE, AND VOLUME INTEGRALS AND RELATED INTEGRAL THEOREMS

### INTRODUCTION

So far, we have dealt with derivative operations on vector fields. In this chapter, we shall define line integrals, surface integrals, and volume integrals and consider some important applications of these integrals. We shall see that a line integral is a natural generalization of the definite integral, the surface integral is a generalization of a double integral, and volume integral is a generalization of a triple integral.

Line integrals can be transformed into double integrals with the help of Green's theorem in the plane. With the help of Stokes' theorem, line integrals can be transformed into surface integrals, and conversely. Surface integrals can be transformed into triple integrals and conversely with the help of the divergence theorem. These transformations are of great practical importance. The corresponding theorems of Green's, Stokes', and Gauss serve as powerful tools in many practical as well as theoretical problems.

### TANGENTIAL LINE INTEGRAL

Let  $\vec{A}(x, y, z) = A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}$  be a vector function which is defined and continuous along the arc of the space curve  $C$ . Subdivide the arc  $AB$  into  $n$  parts by means of the points  $P_1, P_2, \dots, P_{n-1}$  chosen arbitrarily and write  $A = P_0$  and  $B = P_n$  as shown in Figure (5.1). Consider one such segment  $P_{k-1}P_k$  and let the length of this segment be  $\Delta s_k$ ,  $k = 1, 2, \dots, n$ . Let  $Q_k(x_k, y_k, z_k)$  be any point on the segment  $P_{k-1}P_k$ . Define  $\vec{A}(x_k, y_k, z_k) = \vec{A}_k$ . Let  $\hat{T}_k$  be unit tangent vector to  $C$  at  $Q_k$ .

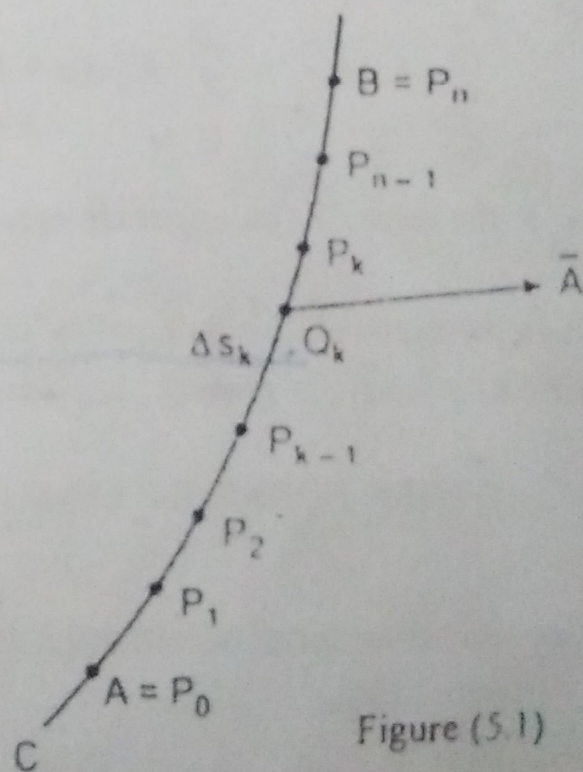


Figure (5.1)

Multiply the tangential component of  $\vec{A}$  at  $Q_k$  with the arc length  $\Delta s_k$  of the corresponding segment  $P_{k-1}P_k$  and form the sum

$$\sum_{k=1}^n \vec{A}_k \cdot \hat{T}_k \Delta s_k$$

Now take the limit of this sum as  $n \rightarrow \infty$  in such a way that the arc length of each segment  $\Delta s_k$

This limit, if it exists, is called the tangential line integral of  $\vec{A}$  along  $C$  from  $A$  to  $B$  and is denoted

$$\text{by } \int_A^B \vec{A} \cdot \hat{T} ds \quad \text{or} \quad \int_C \vec{A} \cdot \hat{T} ds$$

$$\text{i.e. } \lim_{n \rightarrow \infty} \sum_{k=1}^n \vec{A}_k \cdot \hat{T}_k \Delta s_k = \int_A^B \vec{A} \cdot \hat{T} ds$$

Since  $\hat{T} = \frac{d\vec{r}}{ds}$  where  $\vec{r}$  is the position vector of any point on  $C$ , it is usual to put  $\hat{T} ds = d\vec{r}$

$$\text{thus the line integral } \int_A^B \vec{A} \cdot \hat{T} ds = \int_A^B \vec{A} \cdot d\vec{r} = \int_C \vec{A} \cdot d\vec{r} = \int_C A_1 dx + A_2 dy + A_3 dz$$

where  $d\vec{r} = dx \hat{i} + dy \hat{j} + dz \hat{k}$  is called the differential displacement vector.

The line integral  $\int_C \vec{A} \cdot d\vec{r}$  is sometimes called a scalar line integral of a vector field  $\vec{A}$ .

If  $C$  is a closed curve which we shall suppose a simple closed curve (i.e. a curve which does not intersect itself anywhere), the line integral around  $C$  is often denoted by

$$\oint_C \vec{A} \cdot d\vec{r} = \oint_C A_1 dx + A_2 dy + A_3 dz$$

If  $\vec{A}$  is the force  $\vec{F}$  on a particle moving along  $C$ , this line integral represents the work done by a force

In fluid mechanics, this integral is called the circulation of  $\vec{A}$  around  $C$ , where  $\vec{A}$  represents velocity of a fluid. In general, any integral which is to be evaluated along a curve is called a line integral.

#### OTHER FORMS OF LINE INTEGRALS

The other forms of line integrals are  $\int_C \phi d\vec{r} = \hat{i} \int_C \phi dx + \hat{j} \int_C \phi dy + \hat{k} \int_C \phi dz$

$$\text{and } \int_C \vec{A} \times d\vec{r} = \int_C (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}) \times (dx \hat{i} + dy \hat{j} + dz \hat{k})$$

$$= \hat{i} \int_C (A_2 dz - A_3 dy) + \hat{j} \int_C (A_3 dx - A_1 dz) + \hat{k} \int_C (A_1 dy - A_2 dx)$$

# GENERAL PROPERTIES OF LINE INTEGRALS

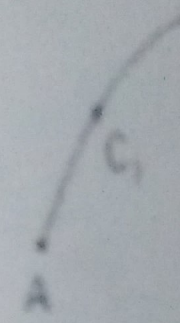
The following

the properties of line integrals that are useful in computation

(i) 
$$\int_C K \vec{A} \cdot d\vec{r} = K \int_C \vec{A} \cdot d\vec{r} \quad (K \text{ any real constant})$$

(ii) 
$$\int_C (\vec{A} + \vec{B}) \cdot d\vec{r} = \int_C \vec{A} \cdot d\vec{r} + \int_C \vec{B} \cdot d\vec{r}$$

(iii) 
$$\int_C \vec{A} \cdot d\vec{r} = \int_{C_1} \vec{A} \cdot d\vec{r} + \int_{C_2} \vec{A} \cdot d\vec{r}$$



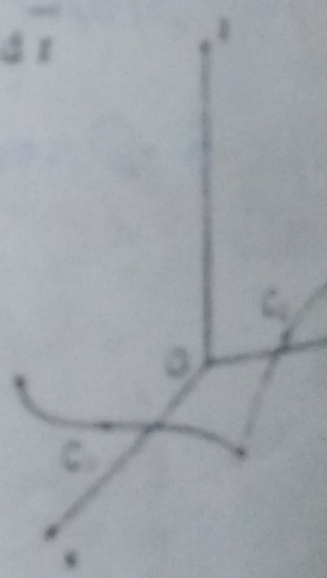
where the path  $C$  is subdivided into two arcs  $C_1$  and  $C_2$  that have the same orientation as in figure (5.2). If the sense of orientation along  $C$  is reversed, the value of the integral is

(iv) If  $C$  is piecewise smooth, consisting of smooth curves  $C_1, C_2, \dots, C_n$

(figure 5.3), the line integral of  $\vec{A}$  over  $C$  is defined as the sum of the line integrals over the smooth curves making up  $C$ :

$$\int_C \vec{A} \cdot d\vec{r} = \int_{C_1} \vec{A} \cdot d\vec{r} + \int_{C_2} \vec{A} \cdot d\vec{r} + \dots + \int_{C_n} \vec{A} \cdot d\vec{r}$$

In this sum, the orientation along  $C$  must be maintained over the curves  $C_1, C_2, \dots, C_n$ . That is, the initial point of  $C_j$  is the terminal point of  $C_{j-1}$ . This requirement is indicated by the arrows as shown in figure (5.3).



EXAMPLE (1): If  $\vec{A} = 3xy \hat{i} - y^2 \hat{j}$ , evaluate  $\int_C \vec{A} \cdot d\vec{r}$  where  $C$  is a curve in the  $xy$ -plane,  $y = 2x^2$ , from  $(0, 0)$  to  $(1, 2)$

SOLUTION: The curve  $C$  defined by  $y = 2x^2$  in the  $xy$ -plane is shown in figure (5.4). Since the integration is performed in the  $xy$ -plane ( $z = 0$ ), we can take

$$\vec{r} = x \hat{i} + y \hat{j}, \text{ therefore } d\vec{r} = dx \hat{i} + dy \hat{j}$$

Thus 
$$\int_C \vec{A} \cdot d\vec{r} = \int_C (3xy \hat{i} - y^2 \hat{j}) \cdot (dx \hat{i} + dy \hat{j})$$

then  $dy = 4x dx$ . Also  $x$  varies from 0 to 1.

$$\begin{aligned} \bar{A} \cdot d\bar{r} &= \int_{x=0}^1 3x(2x^2) dx - 4x^4(4x) dx \\ &= \int_0^1 (6x^3 - 16x^4) dx = \left[ \frac{3}{2}x^4 - \frac{8}{3}x^5 \right]_0^1 = \frac{3}{2} - \frac{8}{3} = -\frac{7}{6} \end{aligned}$$

(2): If  $\bar{A} = (2x + y)\hat{i} + (3y - x)\hat{j}$ , evaluate  $\int_C \bar{A} \cdot d\bar{r}$  where  $C$  is the curve in the  $xy$ -plane consisting of the line segment  $C_1$  from  $(0, 0)$  to  $(2, 0)$  and then the line segment  $C_2$  from  $(2, 0)$  to  $(3, 2)$ .

The path  $C$  consisting of line segments  $C_1$  and  $C_2$  is shown in figure (5.5).

Integration is performed in the  $xy$ -plane, therefore  $\bar{r} = x\hat{i} + y\hat{j}$  and so  $d\bar{r} = dx\hat{i} + dy\hat{j}$ .

$$\begin{aligned} \bar{A} \cdot d\bar{r} &= \int_C [(2x + y)\hat{i} + (3y - x)\hat{j}] \cdot [dx\hat{i} + dy\hat{j}] \\ &= \int_C (2x + y) dx + (3y - x) dy \quad (1) \end{aligned}$$

consisting of the line segments  $C_1$  and  $C_2$ , we have

$$\bar{A} \cdot d\bar{r} = \int_{C_1} \bar{A} \cdot d\bar{r} + \int_{C_2} \bar{A} \cdot d\bar{r} \quad (2)$$

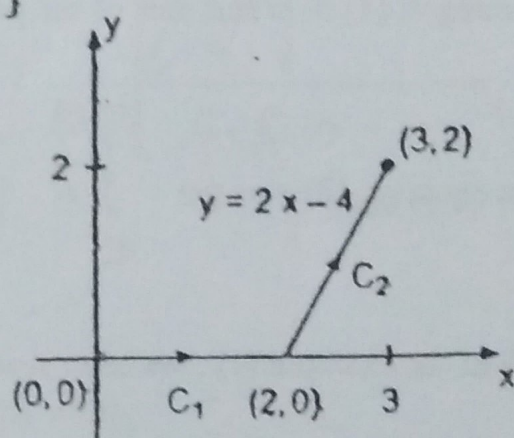


Figure (5.5)

segment  $C_1$  from  $(0, 0)$  to  $(2, 0)$ ,  $y = 0$  and so  $dy = 0$ , while  $x$  varies from 0 to 2.

Integral (1) over this part of the path is

$$\int_{C_1} \bar{A} \cdot d\bar{r} = \int_{x=0}^2 2x dx = \left[ x^2 \right]_0^2 = 4$$

segment  $C_2$  from  $(2, 0)$  to  $(3, 2)$ , the equation is  $y = 2x - 4$  and so  $dy = 2 dx$ ,  $x$  varies from 2 to 3. The integral (1) over this part of the path is

$$\begin{aligned} \int_{C_2} \bar{A} \cdot d\bar{r} &= \int_{x=2}^3 [2x + (2x - 4)] dx + [3(2x - 4) - x] 2 dx \\ &= \int_2^3 (14x - 28) dx = \left[ 7x^2 - 28x \right]_2^3 = (63 - 84) - (28 - 56) = 7 \end{aligned}$$

From equation (2) we get

$$\int_C \bar{A} \cdot d\bar{r} = 4 + 7 = 11$$

EXAMPLE (3): If  $\bar{A} = (x - 3y)\hat{i} + (y - 2x)\hat{j}$ , evaluate  $\oint_C \bar{A} \cdot d\bar{r}$  where  $C$  is an ellipse

$\frac{x^2}{9} + \frac{y^2}{4} = 1$  in the  $xy$ -plane traversed in the positive (counterclockwise) direction.

SOLUTION: The curve  $C$  which is an ellipse with semi-major axis as 3 and semi-minor axis as 2 is shown in figure (5.6). Since the integration is performed in the  $xy$ -plane, we take  $d\bar{r} = dx\hat{i} + dy\hat{j}$

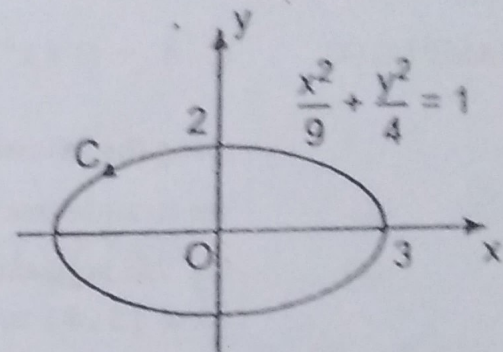


Figure (5.6)

$$\text{Thus } \oint_C \bar{A} \cdot d\bar{r} = \oint_C (x - 3y)dx + (y - 2x)dy \quad (1)$$

The parametric equations of this ellipse are  $x = 3 \cos t$ ,  $y = 2 \sin t$ ,  $0 \leq t \leq 2\pi$  therefore,  $dx = -3 \sin t dt$ ,  $dy = 2 \cos t dt$ . Hence from equation (1), we get

$$\begin{aligned} \oint_C \bar{A} \cdot d\bar{r} &= \int_{t=0}^{2\pi} (3 \cos t - 6 \sin t)(-3 \sin t dt) + (2 \sin t - 6 \cos t)(2 \cos t dt) \\ &= \int_0^{2\pi} (-5 \sin t \cos t + 18 \sin^2 t - 12 \cos^2 t) dt \\ &= \int_0^{2\pi} \left[ -\frac{5}{2} \sin 2t + 9(1 - \cos 2t) - 6(1 + \cos 2t) \right] dt \\ &= \left[ \frac{5}{4} \cos 2t + 9 \left( t - \frac{\sin 2t}{2} \right) - 6 \left( t + \frac{\sin 2t}{2} \right) \right]_0^{2\pi} \\ &= \left[ \frac{5}{4} \cos 2t + 3t - \frac{15}{2} \sin 2t \right]_0^{2\pi} \\ &= \left( \frac{5}{4} \cos 4\pi + 6\pi \right) - \left( \frac{5}{4} \cos 0 \right) \\ &= \frac{5}{4} + 6\pi - \frac{5}{4} = 6\pi \end{aligned}$$