## Differential Geometry

### Fall 2020

Topic:Curves in Plane

Lecture 1

Lecturer:Dr. Muhammad Yaseen

#### **Course Title: Differential Geometry**

# Course Code: MATH-303 (For BS) & MATH-601 (For MSc)

**Question:** What is a curve?

Answer: One can draw a variety of curves.



Figure 1: Various Curves

The curve in (i) is a smooth (sufficiently differentiable) curve. The curve in (ii) is also of a smooth curve, but now without endpoints, since traveling along the curve will bring you back to where you started. This type of curve is called a closed curve. In (iii), we have self intersections and we still regard it as a smooth closed curve. The curve in (iv) is a closed curve, but as it has sharp angles at particular points, it is not smooth at those points.

There are two ways to think of a curve:

# (a) The implicit function representation

In general, if we take a function F(x, y) of two variables and collect together all points in the plane satisfying F(x, y) = 0 to produce a curve C, we call this the implicit function representation for curve by F(x, y). So

$$C = \{(x, y) | F(x, y) = 0\}.$$

**Example 1.1** The following are examples of curves that are represented implicitly by the solution sets of the following four equations.

Ellipse: 
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - 1 = 0.$$







## (b) As path of a moving particle

If a particle is moving through the plane with respect to time variable t, then (x(t), y(t)) denotes the position of the particle at any time t, where x(t), y(t) are smooth functions of t. Then the trajectory of these points can be imagined as a curve. Here, t is called a parameter of the curve. This way of representing a curve is called a parametrization. Pairing up the two functions x(t), y(t) and naming the pair  $\gamma(t)$ , we have the curve

$$\gamma(t) = (x(t), y(t)).$$

**Remark 1.2** We are mostly interested in geometric shape of a curve as in (a) but (b) is more useful because we can bring in tools from calculus to describe the geometric behavior. It is like giving a coordinate system along a curve which allows calculations to be done.

**Definition 1.3** A parametrized curve in  $\mathbb{R}^3$  is a map  $\gamma : I \to \mathbb{R}^3$  given by  $\gamma(t) = (x(t), y(t), z(t))$ , where I is usually taken to be an open interval which is either bounded or unbounded.



Figure 3:

**Definition 1.4** If  $\gamma$  is a parametrizeed curve in  $\mathbb{R}^3$  given by  $\gamma(t) = (x(t), y(t), z(t))$ , then  $\dot{\gamma}(t) = (\dot{x}(t), \dot{y}(t), \dot{z}(t))$  is called the **tangent vector** of  $\gamma$  at the point  $\gamma(t)$ .



Figure 4:

**Definition 1.5** The trace of  $\gamma$  is defined as

$$Image(\gamma) = \gamma(I) \subset \mathbb{R}^3$$

**Definition 1.6** We say that  $\gamma : I \to \mathbb{R}^3$  is a plane curve if there exists a plane  $P \subset \mathbb{R}^3$  such that  $\gamma(I) \subset P$ .

Remark 1.7 The parametrization of a curve is not unique in general e.g. consider the parabola  $y = x^2$ . If we choose x = t, then  $y = t^2$  so that  $\gamma(t) = (t, t^2)$  is a parametrization of  $y = x^2$ . Another choice is  $\gamma(t) = (2t, 4t^2)$ . Yet another choice is  $\gamma(t) = (t^3, t^6)$  and so on.

Question: Find parametrization of the circle  $x^2 + y^2 = 1$ . Answer: If we chose x = t, then  $y = \pm \sqrt{1 - t^2}$ . So we have the following parametrizations:

$$egin{aligned} &\gamma(t)=(t,\sqrt{1-t^2}) & ( ext{Upper semi-circle}) \ &\gamma(t)=(t,-\sqrt{1-t^2}) & ( ext{Lower semi-circle}) \end{aligned}$$

To find parametrizions that cover the whole circle, we must find functions x(t), y(t), such that  $(x(t))^2 + (y(t))^2 = 1$ . One can obviously choose  $x(t) = \cos t$ ,  $y(t) = \sin t$  so that  $\gamma(t) = (\cos t, \sin t)$  parmetrizes the whole circle if  $t \in I$ , where I is an open interval whose length is greater than  $2\pi$ .