# Electrodynamics-II

Lecturer Muhammad Amer Mustafa

UOS Sub Campus Bhakkar

# Content

- 6.2 The field of a magnetized object
  - 6.2.1 Bound Currents
- 6.3 The Auxiliary Field H
  - 6.3.1 Ampere's Law in a magnetized material
- 6.4 Linear and Non Linear Media
  - 6.4.1 Magnetic Susceptibility and Permeability

#### 6.2 ■ THE FIELD OF A MAGNETIZED OBJECT

#### 6.2.1 Bound Currents

Suppose we have a piece of magnetized material; the magnetic dipole moment per unit volume,  $\mathbf{M}$ , is given. What field does this object produce? Well, the vector potential of a single dipole  $\mathbf{m}$  is given by Eq. 5.85:

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \frac{\mathbf{m} \times \hat{\boldsymbol{\imath}}}{\boldsymbol{\imath}^2}.$$
 (6.10)

In the magnetized object, each volume element  $d\tau'$  carries a dipole moment  $\mathbf{M} d\tau'$ , so the total vector potential is (Fig. 6.11)

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \frac{\mathbf{M}(\mathbf{r}') \times \hat{\mathbf{i}}}{n^2} d\tau'.$$
(6.11)

That *does* it, in principle. But, as in the electrical case (Sect. 4.2.1), the integral can be cast in a more illuminating form by exploiting the identity

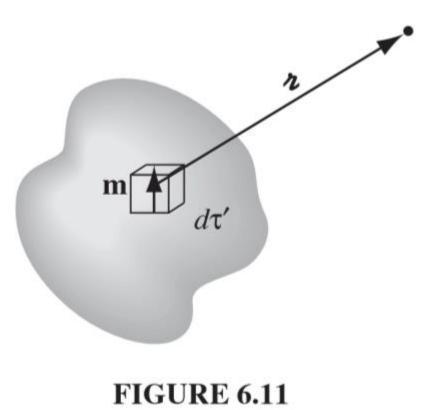
$$\boldsymbol{\nabla}'\frac{1}{\boldsymbol{n}} = \frac{\boldsymbol{\hat{n}}}{\boldsymbol{n}^2}.$$

With this,

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \left[ \mathbf{M}(\mathbf{r}') \times \left( \mathbf{\nabla}' \frac{1}{n} \right) \right] d\tau'.$$

Integrating by parts, using product rule 7, gives  $\nabla \times (f\mathbf{A}) = f(\nabla \times \mathbf{A}) - \mathbf{A} \times (\nabla f)$ ,

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \left\{ \int \frac{1}{n} \left[ \nabla' \times \mathbf{M}(\mathbf{r}') \right] d\tau' - \int \nabla' \times \left[ \frac{\mathbf{M}(\mathbf{r}')}{n} \right] d\tau' \right\}.$$



Problem 1.61(b) invites us to express the latter as a surface integral,

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int \frac{1}{n} [\nabla' \times \mathbf{M}(\mathbf{r}')] d\tau' + \frac{\mu_0}{4\pi} \oint \frac{1}{n} [\mathbf{M}(\mathbf{r}') \times d\mathbf{a}'].$$
(6.12)

The first term looks just like the potential of a volume current,

$$\mathbf{J}_b = \mathbf{\nabla} \times \mathbf{M},\tag{6.13}$$

while the second looks like the potential of a surface current,

$$\mathbf{K}_{b} = \mathbf{M} \times \mathbf{\hat{n}},\tag{6.14}$$

where  $\hat{\mathbf{n}}$  is the normal unit vector. With these definitions,

$$\mathbf{A}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int_{\mathcal{V}} \frac{\mathbf{J}_b(\mathbf{r}')}{\imath} \, d\tau' + \frac{\mu_0}{4\pi} \oint_{\mathcal{S}} \frac{\mathbf{K}_b(\mathbf{r}')}{\imath} \, da'. \tag{6.15}$$

What this means is that the potential (and hence also the field) of a magnetized object is the same as would be produced by a volume current  $\mathbf{J}_b = \nabla \times \mathbf{M}$ throughout the material, plus a surface current  $\mathbf{K}_{b} = \mathbf{M} \times \hat{\mathbf{n}}$ , on the boundary. Instead of integrating the contributions of all the infinitesimal dipoles, using Eq. 6.11, we first determine the **bound currents**, and then find the field *they* produce, in the same way we would calculate the field of any other volume and surface currents. Notice the striking parallel with the electrical case: there the field of a polarized object was the same as that of a bound volume charge  $\rho_b = -\nabla \cdot \mathbf{P}$ plus a bound surface charge  $\sigma_b = \mathbf{P} \cdot \hat{\mathbf{n}}$ .

#### 6.3 ■ THE AUXILIARY FIELD H

## 6.3.1 ■ Ampère's Law in Magnetized Materials

In Sect. 6.2, we found that the effect of magnetization is to establish bound currents  $\mathbf{J}_b = \nabla \times \mathbf{M}$  within the material and  $\mathbf{K}_b = \mathbf{M} \times \hat{\mathbf{n}}$  on the surface. The field due to magnetization of the medium is just the field produced by these bound currents. We are now ready to put everything together: the field attributable to bound currents, plus the field due to everything else—which I shall call the **free current**. The free current might flow through wires imbedded in the magnetized substance or, if the latter is a conductor, through the material itself. In any event, the total current can be written as

$$\mathbf{J} = \mathbf{J}_b + \mathbf{J}_f. \tag{6.17}$$

There is no new physics in Eq. 6.17; it is simply a *convenience* to separate the current into these two parts, because they got there by quite different means: the free current is there because somebody hooked up a wire to a battery—it involves actual transport of charge; the bound current is there because of magnetization—it results from the conspiracy of many aligned atomic dipoles.

In view of Eqs. 6.13 and 6.17, Ampère's law can be written

$$\frac{1}{\mu_0}(\boldsymbol{\nabla}\times\mathbf{B}) = \mathbf{J} = \mathbf{J}_f + \mathbf{J}_b = \mathbf{J}_f + (\boldsymbol{\nabla}\times\mathbf{M}),$$

or, collecting together the two curls:  $\frac{1}{\mu_0} (\vec{\nabla} \times \vec{B}) - \vec{\nabla} \times \vec{M} = \vec{J}_f$ 

$$\boldsymbol{\nabla} \times \left(\frac{1}{\mu_0} \mathbf{B} - \mathbf{M}\right) = \mathbf{J}_f.$$

The quantity in parentheses is designated by the letter **H**:

$$\mathbf{H} \equiv \frac{1}{\mu_0} \mathbf{B} - \mathbf{M}.$$
 (6.18)

In terms of **H**, then, Ampère's law reads

$$\nabla \times \mathbf{H} = \mathbf{J}_{f},$$
or, in integral form, Using the stokes theorem 
$$\int_{\mathcal{S}} (\nabla \times \mathbf{v}) \cdot d\mathbf{a} = \oint_{\mathcal{P}} \mathbf{v} \cdot d\mathbf{l}.$$

$$\oint \mathbf{H} \cdot d\mathbf{l} = I_{f_{enc}},$$
(6.20)

where  $I_{f_{enc}}$  is the total *free* current passing through the Amperian loop.

**H** plays a role in magnetostatics analogous to **D** in electrostatics: Just as **D** allowed us to write Gauss's law in terms of the free charge alone, H permits us to express Ampère's law in terms of the free current alone—and free current is what we control directly. Bound current, like bound charge, comes along for the ride the material gets magnetized, and this results in bound currents; we cannot turn them on or off independently, as we can free currents. In applying Eq. 6.20, all we need to worry about is the *free* current, which we know about because we *put* it there. In particular, when symmetry permits, we can calculate H immediately from Eq. 6.20 by the usual Ampère's law methods. (For example, Probs. 6.7 and 6.8 can be done in one line by noting that  $\mathbf{H} = \mathbf{0}$ .)

# 6.4 ■ LINEAR AND NONLINEAR MEDIA

### 6.4.1 Magnetic Susceptibility and Permeability

In paramagnetic and diamagnetic materials, the magnetization is sustained by the field; when **B** is removed, **M** disappears. In fact, for most substances the magnetization is *proportional* to the field, provided the field is not too strong. For notational consistency with the electrical case (Eq. 4.30), I *should* express the proportionality thus:

$$\mathbf{M} = \frac{1}{\mu_0} \chi_m \mathbf{B} \quad \text{(incorrect!)}. \tag{6.28}$$

But custom dictates that it be written in terms of **H**, instead of **B**:

$$\mathbf{M} = \chi_m \mathbf{H}. \tag{6.29}$$

The constant of proportionality  $\chi_m$  is called the **magnetic susceptibility**; it is a dimensionless quantity that varies from one substance to another—positive for paramagnets and negative for diamagnets. Typical values are around  $10^{-5}$  (see Table 6.1).

Materials that obey Eq. 6.29 are called linear media. In view of Eq. 6.18,

$$\mathbf{B} = \mu_0(\mathbf{H} + \mathbf{M}) = \mu_0(1 + \chi_m)\mathbf{H}, \tag{6.30}$$

for linear media. Thus **B** is *also* proportional to  $\mathbf{H}$ :<sup>8</sup>

$$\mathbf{B} = \mu \mathbf{H},\tag{6.31}$$

where

$$\mu \equiv \mu_0 (1 + \chi_m). \tag{6.32}$$

 $\mu$  is called the **permeability** of the material.<sup>9</sup> In a vacuum, where there is no matter to magnetize, the susceptibility  $\chi_m$  vanishes, and the permeability is  $\mu_0$ . That's why  $\mu_0$  is called the **permeability of free space**.

Material	Susceptibility	Material	Susceptibility
Diamagnetic:		Paramagnetic:	
Bismuth	$-1.7 \times 10^{-4}$	Oxygen (O <sub>2</sub> )	$1.7 \times 10^{-6}$
Gold	$-3.4 \times 10^{-5}$	Sodium	$8.5 \times 10^{-6}$
Silver	$-2.4 \times 10^{-5}$	Aluminum	$2.2 \times 10^{-5}$
Copper	$-9.7 \times 10^{-6}$	Tungsten	$7.0 \times 10^{-5}$
Water	$-9.0 \times 10^{-6}$	Platinum	$2.7 \times 10^{-4}$
Carbon Dioxide	$-1.1 \times 10^{-8}$	Liquid Oxygen	$3.9 \times 10^{-3}$
		(-200° C)	
Hydrogen (H <sub>2</sub> )	$-2.1 \times 10^{-9}$	Gadolinium	$4.8 \times 10^{-1}$

**TABLE 6.1** Magnetic Susceptibilities (unless otherwise specified, values are for 1 atm, 20° C). *Data from Handbook of Chemistry and Physics*, 91st ed. (Boca Raton: CRC Press, Inc., 2010) and other references.