# Electrodynamics-II 

Lecturer Muhammad Amer Mustafa
UOS, Sub Campus Bhakkar

### 5.4.2 Magnetostatics Boundary Conditions

We shall see boundary conditions for two components of Magnetic fields

- For Perpendicular components of magnetic field
- For Tangential/parallel components of magnetic field


## For perpendicular components of Magnetic

 Field$$
\oint \vec{B} \cdot d \vec{a}=\int \vec{\nabla} \cdot \vec{B} d \tau^{\prime}
$$

We have proved that $\vec{\nabla} \cdot \vec{B}=0$
So

$$
\begin{gathered}
\oint \vec{B} \cdot d \vec{a}=0 \\
\oint \vec{B} \cdot d \vec{a}=\int_{\text {Top }} \vec{B} \cdot d \vec{a}+\int_{\text {bottom }} \vec{B} \cdot d \vec{a}+\int_{\text {side walls }} \vec{B} \cdot d \vec{a}
\end{gathered}
$$

## Perpendicular Field Boundary Conditions

$$
\oint \vec{B} \cdot d \vec{a}=\int_{\text {Top }} \stackrel{\perp}{B_{\text {above }}} d a-\int_{\text {bottom }} \stackrel{\perp}{B_{\text {below }}} d a+\int_{\text {side walls }} \vec{B} \cdot d \vec{a}
$$

Integral of magnetic field due to side walls is zero because $\int d a \rightarrow 0$
So last term vanishes and we get

$$
\begin{gathered}
\oint \vec{B} \cdot d \vec{a}=\int_{\text {Top }}^{B_{\text {above }}^{\perp}} d a-\iint_{\text {bottom }}^{\perp} \stackrel{\perp}{B_{\text {below }}} d a \\
\oint \vec{B} \cdot d \vec{a}=\stackrel{\perp}{B_{\text {above }}^{\perp} \int d a-B_{\text {below }}^{\perp} \int d a=A\left(B_{\text {above }}^{\perp}-\stackrel{\perp}{B_{\text {below }}}\right)=0}
\end{gathered}
$$

## For perpendicular components of Magnetic

 Field$$
\oint \vec{B} \cdot d \vec{a}=B_{\text {above }}^{\perp} \int d a-B_{\text {below }}^{\perp} \int d a=A\left(B_{\text {above }}^{\perp}-B_{\text {below }}^{\perp}\right)=0
$$

Area cannot be equal to zero so

$$
\begin{gathered}
B_{\text {above }}^{\perp}-B_{\text {below }}^{\perp}=0 \\
B_{\text {above }}^{\perp}=B_{\text {below }}^{\perp}
\end{gathered}
$$

It is proved that perpendicular components of magnetic fields are continuous.

# Boundary conditions for parallel components components of Magnetic Field 



Figure 5.50

## Boundary conditions for parallel components components of Magnetic Field

Using the Ampere's Law

$$
\begin{gathered}
\oint \vec{B} \cdot d \vec{l}=\int_{\text {Below }} \vec{B} \cdot d \vec{l}+\int_{\text {Top }} \vec{B} \cdot d \vec{l}+\int_{\text {Height }} \vec{B} \cdot d \vec{l}=\mu_{0} I_{e n c} \\
\oint \vec{B} \cdot d \vec{a}=\int B_{\text {above }}^{\|} d l-\int B_{\text {below }} d l+\int \vec{B} \cdot d \vec{l}=\mu_{0} I_{e n c}
\end{gathered}
$$

Last term $\int \vec{B} . d \vec{l}$ goes to zero because height of amperian loop approaches to zero

$$
B_{\text {above }} \int d l-B_{\text {below }} \int d l=l\left(B_{\text {above }}^{\|}-B_{\text {below }}^{\|}\right)=\mu_{0} I_{\text {enc }}
$$

Where $I_{e n}=K L$ and L is length of Amperian loop

## Boundary conditions for parallel components components of Magnetic Field

$$
\begin{aligned}
l\left(B_{\text {above }}^{\|}-B_{\text {below }}^{\|}\right)= & \mu_{0} K l \\
& B_{\text {above }}^{\|}-B_{\text {below }}^{\|}=\mu_{0} K
\end{aligned} \quad \begin{aligned}
\left(B_{\text {above }}-B_{\text {below }}^{\|}\right)= & \mu_{0} K \\
& B_{\text {above }}-B_{\text {below }}=\mu_{0}(\vec{K} \times \hat{n})
\end{aligned}
$$

Where $\hat{n}$ is the unit vector perpendicular to the surface pointing upward.

## Multipole Expansion of the vector potential

- We want to find out the approximate formula for magnetic vector potential at very large distances $\vec{r}$ due to this current distribution.(fig.5.51)
- Inverse of Separation vector can be written in terms of Legendre Polynomials.
(see section 3.4.1)

$$
\begin{aligned}
\frac{1}{r} & =\frac{1}{\sqrt{r^{2}+\left(r^{\prime}\right)^{2}-2 r r^{\prime} \cos \theta^{\prime}}} \\
& =\frac{1}{r} \sum_{n=0}^{\infty}\left(\frac{r^{\prime}}{r}\right)^{n} P_{n} \cos \theta^{\prime}
\end{aligned}
$$



Figure 5.51

## Legendre Polynomial terms

$$
\begin{aligned}
& P_{0}(\cos \theta)=1 \\
& P_{1}(\cos \theta)=\cos \theta \\
& P_{2}(\cos \theta)=\frac{1}{4}(1+3 \cos 2 \theta) \\
& P_{3}(\cos \theta)=\frac{1}{8}(3 \cos \theta+5 \cos 3 \theta) \\
& P_{4}(\cos \theta)=\frac{1}{64}(9+20 \cos 2 \theta+35 \cos 4 \theta) \\
& P_{5}(\cos \theta)=\frac{1}{128}(30 \cos \theta+35 \cos 3 \theta+63 \cos 5 \theta) \\
& P_{6}(\cos \theta)=\frac{1}{512}(50+105 \cos 2 \theta+126 \cos 4 \theta+231 \cos 6 \theta) \\
& P_{7}(\cos \theta)=\frac{1}{1024}(175 \cos \theta+189 \cos 3 \theta+231 \cos 5 \theta+429 \cos 7 \theta)
\end{aligned}
$$

## Multipole Expansion of the vector potential

Accordingly, the vector potential of a current loop can be written

$$
\begin{equation*}
\mathbf{A}(\mathbf{r})=\frac{\mu_{0} I}{4 \pi} \oint \frac{1}{r} d \mathbf{l}^{\prime}=\frac{\mu_{0} I}{4 \pi} \sum_{n=0}^{\infty} \frac{1}{r^{n+1}} \oint\left(r^{\prime}\right)^{n} P_{n}\left(\cos \theta^{\prime}\right) d \mathbf{l}^{\prime}, \tag{5.78}
\end{equation*}
$$

or, more explicitly:

$$
\begin{align*}
\mathbf{A}(\mathbf{r})= & \frac{\mu_{0} I}{4 \pi}\left[\frac{1}{r} \oint d \mathbf{l}^{\prime}+\frac{1}{r^{2}} \oint r^{\prime} \cos \theta^{\prime} d \mathbf{l}^{\prime}\right. \\
& \left.+\frac{1}{r^{3}} \oint\left(r^{\prime}\right)^{2}\left(\frac{3}{2} \cos ^{2} \theta^{\prime}-\frac{1}{2}\right) d \mathbf{l}^{\prime}+\cdots\right] . \tag{5.79}
\end{align*}
$$

## Multipole Expansion of the vector potential

$$
\begin{gathered}
\mathbf{A}(\mathbf{r})=\frac{\mu_{0} I}{4 \pi} \frac{1}{r} \oint d \mathbf{l}^{\prime} \longrightarrow \text { Magnetic Mono Pole Term } \\
\mathbf{A}(\mathbf{r})=\frac{\mu_{0} I}{4 \pi} \frac{1}{r^{2}} \oint r^{\prime} \cos \theta^{\prime} d \mathbf{l}^{\prime} \longrightarrow \text { Magnetic Dipole Pole Term }
\end{gathered}
$$

As in the multipole expansion of $V$, we call the first term (which goes like $1 / r$ ) the monopole term, the second (which goes like $1 / r^{2}$ ) dipole, the third quadrupole, and so on.

## Mono Pole Term

Now, it happens that the magnetic monopole term is always zero, for the integral is just the total vector displacement around a closed loop:

$$
\begin{equation*}
\oint d \mathbf{l}^{\prime}=0 \tag{5.80}
\end{equation*}
$$

This reflects the fact that there are (apparently) no magnetic monopoles in nature (an assumption contained in Maxwell's equation $\nabla \cdot \mathbf{B}=0$, on which the entire theory of vector potential is predicated).

## Magnetic Moment and Magnetic Vector Potential

In the absence of any monopole contribution, the dominant term is the dipole (except in the rare case where it, too, vanishes):

$$
\begin{equation*}
\mathbf{A}_{\mathrm{dip}}(\mathbf{r})=\frac{\mu_{0} I}{4 \pi r^{2}} \oint r^{\prime} \cos \theta^{\prime} d \mathbf{l}^{\prime}=\frac{\mu_{0} I}{4 \pi r^{2}} \oint\left(\hat{\mathbf{r}} \cdot \mathbf{r}^{\prime}\right) d \mathbf{l}^{\prime} \tag{5.81}
\end{equation*}
$$

$$
\hat{r} \cdot \overrightarrow{r^{\prime}}=r^{\prime} \cos \theta^{\prime}
$$

This integral can be rewritten in a more illuminating way if we invoke Eq. 1.108, with $\mathbf{c}=\hat{\mathbf{r}}$ :

$$
\begin{equation*}
\oint\left(\hat{\mathbf{r}} \cdot \mathbf{r}^{\prime}\right) d \mathbf{l}^{\prime}=-\hat{\mathbf{r}} \times \int d \mathbf{a}^{\prime} \tag{5.82}
\end{equation*}
$$

$$
\oint(\mathbf{c} \cdot \mathbf{r}) d \mathbf{l}=\mathbf{a} \times \mathbf{c}
$$

Where
Then

$$
\begin{equation*}
\mathbf{A}_{\mathrm{dip}}(\mathbf{r})=\frac{\mu_{0}}{4 \pi} \frac{\overline{\mathbf{m} \times \hat{\mathbf{r}}}}{r^{2}} \tag{5.83}
\end{equation*}
$$

$$
\mathbf{a} \equiv \int_{\mathcal{S}} d \mathbf{a}
$$

Where a is vector

$$
\begin{equation*}
\mathbf{m} \equiv I \int d \mathbf{a}=I \mathbf{a} . \quad \text { area of loop. } \tag{5.84}
\end{equation*}
$$

