## Legendre Polynomials, Associated Legendre Functions and Spherical Harmonics

## A.1. LEGENDRE POLYNOMIALS

Let $x$ be a real variable such that $-1 \leq x \leq 1$. We may also set $x=\cos \theta$, where $\theta$ is a real number. The polynomials of degree $l$

$$
\begin{equation*}
P_{l}(x)=\frac{1}{2^{l} l!} \frac{d^{l}}{d x^{l}}\left(x^{2}-1\right)^{l}, \quad l=0,1,2, \ldots \tag{A.1}
\end{equation*}
$$

are known as the Legendre polynomials. An equivalent definition of $P_{l}(x)$ can be given in terms of a generating function, namely

$$
\begin{equation*}
\left(1-2 x s+s^{2}\right)^{-1 / 2}=\sum_{l=0}^{\infty} P_{l}(x) s^{l}, \quad|s|<1 \tag{A.2}
\end{equation*}
$$

The Legendre polynomials satisfy the differential equation

$$
\begin{equation*}
\left[\left(1-x^{2}\right) \frac{d^{2}}{d x^{2}}-2 x \frac{d}{d x}+l(l+1)\right] P_{l}(x)=0 \tag{A.3}
\end{equation*}
$$

We have the recurrence relations

$$
\begin{align*}
& (2 l+1) x P_{l}-(l+1) P_{l+1}-l P_{l-1}=0  \tag{A.4a}\\
& \left(x^{2}-1\right) \frac{d P_{l}}{d x}=l\left(x P_{l}-P_{l-1}\right)=\frac{l(l+1)}{2 l+1}\left(P_{l+1}-P_{l-1}\right) \tag{A.4b}
\end{align*}
$$

which are also valid for the case $l=0$ if one defines $P_{-1}=0$.
The orthogonality relations are

$$
\begin{equation*}
\int_{-1}^{+1} P_{l}(x) P_{l^{\prime}}(x) d x=\frac{2}{2 l+1} \delta_{l l^{\prime}} \tag{A.5}
\end{equation*}
$$

and the closure relation is given by

$$
\begin{equation*}
\frac{1}{2} \sum_{l=0}^{\infty}(2 l+1) P_{l}(x) P_{l}\left(x^{\prime}\right)=\delta\left(x-x^{\prime}\right) \tag{A.6}
\end{equation*}
$$

The Legendre polynomial $P_{l}(x)$ has the parity $(-)^{l}$ and has $l$ zeros in the interval $(-1,+1)$. Furthermore,

$$
\begin{equation*}
P_{l}(1)=1, \quad P_{l}(-1)=(-1)^{l} \tag{A.7}
\end{equation*}
$$

For the lowest values of $l$ the Legendre polynomials are given explicitly by

$$
\begin{align*}
& P_{0}(x)=1 \\
& P_{1}(x)=x \\
& P_{2}(x)=\frac{1}{2}\left(3 x^{2}-1\right) \\
& P_{3}(x)=\frac{1}{2}\left(5 x^{3}-3 x\right)  \tag{A.8}\\
& P_{4}(x)=\frac{1}{8}\left(35 x^{4}-30 x^{2}+3\right) \\
& P_{5}(x)=\frac{1}{8}\left(63 x^{5}-70 x^{3}+15 x\right)
\end{align*}
$$

## A.2. ASSOCIATED LEGENDRE FUNCTIONS

The associated Legendre functions $P_{l}^{m}(x)$ are defined by the relations

$$
\begin{equation*}
P_{l}^{m}(x)=\left(1-x^{2}\right)^{m / 2} \frac{d^{m}}{d x^{m}} P_{l}(x), \quad m=0,1,2, \ldots, l \tag{A.9}
\end{equation*}
$$

They are the product of the function $\left(1-x^{2}\right)^{m / 2}$ and of a polynomial of degree $(l-m)$ and parity $(-)^{l-m}$, having $(l-m)$ zeros in the interval $(-1,+1)$. The functions $P_{l}^{m}(x)$ can also be obtained from a generating function, namely

$$
\begin{aligned}
& (2 m-1)!!\left(1-x^{2}\right)^{m / 2} s^{m}\left(1-2 x s+s^{2}\right)^{-m-1 / 2}=\sum_{l=m}^{\infty} P_{l}^{m}(x) s^{l} \\
& |s|<1
\end{aligned}
$$

with

$$
\begin{align*}
(2 m-1)!! & =1.3 .5 \ldots(2 m-1), \quad m=1,2, \ldots  \tag{A.11}\\
& =1, \quad m=0
\end{align*}
$$

In particular, we have

$$
\begin{align*}
P_{l}^{0}(x) & =P_{l}(x)  \tag{A.12}\\
P_{l}^{l}(x) & =(2 l-1)!!\left(1-x^{2}\right)^{l / 2} \tag{A.13}
\end{align*}
$$

The associated Legendre functions satisfy the differential equation

$$
\begin{equation*}
\left[\left(1-x^{2}\right) \frac{d^{2}}{d x^{2}}-2 x \frac{d}{d x}+l(l+1)-\frac{m^{2}}{1-x^{2}}\right] P_{l}^{m}(x)=0 \tag{A.14}
\end{equation*}
$$

We also have the recurrence relations

$$
\left.\begin{array}{l}
(2 l+1) x P_{l}^{m}-(l-m+1) P_{l+1}^{m}-(l+m) P_{l-1}^{m}=0 \\
\left(x^{2}-1\right) \frac{d P_{l}^{m}}{d x}=-(l+1) x P_{l}^{m}+(l-m+1) P_{l+1}^{m} \\
=
\end{array} \begin{array}{l}
l x P_{l}^{m}-(l+m) P_{l-1}^{m}, \quad 0 \leq m \leq l-1
\end{array}, \begin{array}{r}
P_{l}^{m+2}-2(m+1) \frac{x}{\left(1-x^{2}\right)^{1 / 2}} P_{l}^{m+1}+(l-m)(l+m+1) P_{l}^{m}=0 \\
0 \leq m \leq l-2,
\end{array}\right\}
$$

and the orthogonality relations

$$
\begin{equation*}
\int_{-1}^{+1} P_{l}^{m}(x) P_{l^{\prime}}^{m}(x) d x=\frac{2}{2 l+1} \frac{(l+m)!}{(l-m)!} \delta_{l l^{\prime}} . \tag{A.19}
\end{equation*}
$$

Important particular values are

$$
\begin{equation*}
P_{l}^{m}(1)=P_{l}^{m}(-1)=0, \quad m \neq 0 \tag{A.20}
\end{equation*}
$$

[for $m=0$, see eq. (A.7)] and

$$
\begin{align*}
P_{l}^{m}(0) & =(-)^{s} \frac{(2 s+2 m)!}{2^{l} s!(s+m)!}, & & l-m=2 s  \tag{A.21}\\
& =0, & & l-m=2 s+1 .
\end{align*}
$$

The first few associated Legendre functions are given by

$$
\begin{align*}
& P_{1}^{1}(x)=\left(1-x^{2}\right)^{1 / 2} \\
& P_{2}^{1}(x)=3\left(1-x^{2}\right)^{1 / 2} x \\
& P_{2}^{2}(x)=3\left(1-x^{2}\right) \\
& P_{3}^{1}(x)=\frac{3}{2}\left(1-x^{2}\right)^{1 / 2}\left(5 x^{2}-1\right),  \tag{A.22}\\
& P_{3}^{2}(x)=15 x\left(1-x^{2}\right) \\
& P_{3}^{3}(x)=15\left(1-x^{2}\right)^{3 / 2}
\end{align*}
$$

## A.3. ORBITAL ANGULAR MOMENTUM AND SPHERICAL HARMONICS

In classical mechanics the orbital angular momentum of a particle is given by

$$
\begin{equation*}
l=\mathbf{r} \times \mathbf{p} \tag{A.23}
\end{equation*}
$$

where $\mathbf{r}$ and $\mathbf{p}$ are the position and momentum vectors of the particle, respectively. In wave mechanics $\mathbf{p}$ is represented by the operator $-i \boldsymbol{\nabla}$ (with $\hbar=1$ ) so that $l$ is represented by the operator $-i(\mathbf{r} \times \boldsymbol{\nabla})$. The Cartesian components of $l$ are therefore given by

$$
\begin{align*}
& l_{x}=y p_{z}-z p_{y}=-i\left(y \frac{\partial}{\partial z}-z \frac{\partial}{\partial y}\right) \\
& l_{y}=z p_{x}-x p_{z}=-i\left(z \frac{\partial}{\partial x}-x \frac{\partial}{\partial z}\right)  \tag{A.24}\\
& l_{z}=x p_{y}-y p_{x}=-i\left(x \frac{\partial}{\partial y}-y \frac{\partial}{\partial x}\right)
\end{align*}
$$

Using the rules of commutator algebra, together with the basic commutation relations

$$
\begin{equation*}
\left[x, p_{x}\right]=\left[y, p_{y}\right]=\left[z, p_{z}\right]=i \tag{A.25}
\end{equation*}
$$

we find that the operators $l_{x}, l_{y}$ and $l_{z}$ satisfy the characteristic commutation relations of angular momenta, namely

$$
\begin{equation*}
\left[l_{x}, l_{y}\right]=i l_{z}, \quad\left[l_{y}, l_{z}\right]=i l_{x}, \quad\left[l_{z}, l_{x}\right]=i l_{y} \tag{A.26}
\end{equation*}
$$

Thus the three operators $l_{x}, l_{y}, l_{z}$ do not mutually commute. However, if we consider the operator

$$
\begin{equation*}
l^{2}=l_{x}^{2}+l_{y}^{2}+l_{z}^{2} \tag{A.27}
\end{equation*}
$$

we readily find that each of the operators $l_{x}, l_{y}$ and $l_{z}$ commutes with $l^{2}$,

$$
\begin{equation*}
\left[l_{x}, l^{2}\right]=\left[l_{y}, l^{2}\right]=\left[l_{z}, l^{2}\right]=0 \tag{A.28}
\end{equation*}
$$

As a result, it is always possible to construct simultaneous eigenfunctions of $\boldsymbol{l}^{2}$ and one component of $l$, which we shall choose to be $l_{z}$.

Let us use spherical polar coordinates $(r, \theta, \phi)$, with

$$
\begin{align*}
& x=r \sin \theta \cos \phi, \\
& y=r \sin \theta \sin \phi,  \tag{A.29}\\
& z=r \cos \theta
\end{align*}
$$

We then have

$$
\begin{align*}
& l_{x}=i\left(\sin \phi \frac{\partial}{\partial \theta}+\cot \theta \cos \phi \frac{\partial}{\partial \phi}\right)  \tag{A.30a}\\
& l_{y}=i\left(-\cos \phi \frac{\partial}{\partial \theta}+\cot \theta \sin \phi \frac{\partial}{\partial \phi}\right)  \tag{A.30b}\\
& l_{z}=-i \frac{\partial}{\partial \phi} \tag{A.30c}
\end{align*}
$$

and

$$
\begin{equation*}
\boldsymbol{l}^{2}=-\left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta}\left(\sin \theta \frac{\partial}{\partial \theta}\right)+\frac{1}{\sin ^{2} \theta} \frac{\partial^{2}}{\partial \phi^{2}}\right] \tag{A.31}
\end{equation*}
$$

The spherical harmonics $Y_{l m}(\theta, \phi)$ are simultaneous eigenfunctions of the operators $l^{2}$ and $l_{z}$. That is (with $\hbar=1$ )

$$
\begin{align*}
& l^{2} Y_{l m}=l(l+1) Y_{l m}, \quad l=0,1,2, \ldots  \tag{A.32}\\
& l_{z} Y_{l m}=m Y_{l m}, \quad m=-l,-l+1, \ldots, l \tag{A.33}
\end{align*}
$$

They are given by

$$
\begin{aligned}
& Y_{l m}(\theta, \phi)=(-1)^{m}\left[\frac{(2 l+1)(l-m)!}{4 \pi(l+m)!}\right]^{1 / 2} P_{l}^{m}(\cos \theta) \exp (i m \phi) \\
& m \geq 0
\end{aligned}
$$

$$
\begin{equation*}
Y_{l,-m}(\theta, \phi)=(-1)^{m} Y_{l m}^{*}(\theta, \phi) \tag{A.34b}
\end{equation*}
$$

and have the parity $(-)^{l}$. Hence, in a reflection about the origin such that $(\theta, \phi) \rightarrow(\pi-\theta, \phi+\pi)$, we have

$$
\begin{equation*}
Y_{l m}(\pi-\theta, \phi+\pi)=(-1)^{l} Y_{l m}(\theta, \phi) \tag{A.35}
\end{equation*}
$$

The spherical harmonics satisfy the orthonormality relations

$$
\begin{align*}
\int Y_{l^{\prime} m^{\prime}}^{*}(\theta, \phi) Y_{l m}(\theta, \phi) d \Omega & \equiv \int_{0}^{2 \pi} d \phi \int_{0}^{\pi} d \theta \sin \theta Y_{l^{\prime} m^{\prime}}^{*}(\theta, \phi) Y_{l m}(\theta, \phi)  \tag{A.36}\\
& =\delta_{l l^{\prime}} \delta_{m m^{\prime}}
\end{align*}
$$

where we have written $d \Omega=\sin \theta d \theta d \phi$. The closure relation for the $Y_{l m}$ is

$$
\begin{equation*}
\sum_{l=0}^{\infty} \sum_{m=-l}^{+l} Y_{l m}^{*}(\theta, \phi) Y_{l m}\left(\theta^{\prime}, \phi^{\prime}\right)=\delta\left(\Omega-\Omega^{\prime}\right) \tag{A.37a}
\end{equation*}
$$

with

$$
\begin{equation*}
\delta\left(\Omega-\Omega^{\prime}\right)=\frac{\delta\left(\theta-\theta^{\prime}\right) \delta\left(\phi-\phi^{\prime}\right)}{\sin \theta} \tag{A.37b}
\end{equation*}
$$

The spherical harmonics constitute a complete orthonormal set of functions on the unit sphere.

The $Y_{l m}$ also satisfy recurrence relations. Introducing the operators

$$
\begin{equation*}
l_{ \pm}=l_{x} \pm i l_{y}=\exp ( \pm i \phi)\left( \pm \frac{\partial}{\partial \theta}+i \cot \theta \frac{\partial}{\partial \phi}\right) \tag{A.38}
\end{equation*}
$$

we have

$$
\begin{align*}
l_{ \pm} Y_{l m} & =[l(l+1)-m(m \pm 1)]^{1 / 2} Y_{l, m \pm 1}  \tag{A.39a}\\
& =[(l \mp m)(l+1 \pm m)]^{1 / 2} Y_{l, m \pm 1}  \tag{A.39b}\\
l_{+} Y_{l, l} & =0  \tag{A.39c}\\
l_{-} Y_{l,-l} & =0 \tag{A.39d}
\end{align*}
$$

and also

$$
\begin{align*}
\cos \theta Y_{l m} & =\left[\frac{(l+1+m)(l+1-m)}{(2 l+1)(2 l+3)}\right]^{1 / 2} Y_{l+1, m} \\
& +\left[\frac{(l+m)(l-m)}{(2 l+1)(2 l-1)}\right]^{1 / 2} Y_{l-1, m} \tag{A.40}
\end{align*}
$$

For $m=0$ and $m=l$ the spherical harmonics are given by the simple expressions

$$
\begin{equation*}
Y_{l, 0}(\theta, \phi)=\left(\frac{2 l+1}{4 \pi}\right)^{1 / 2} P_{l}(\cos \theta) \tag{A.41}
\end{equation*}
$$

and

$$
\begin{equation*}
Y_{l, l}(\theta, \phi)=(-1)^{l}\left[\frac{2 l+1}{4 \pi} \frac{(2 l)!}{2^{2 l}(l!)^{2}}\right]^{1 / 2} \sin ^{l} \theta \exp (i l \phi) \tag{A.42}
\end{equation*}
$$

It should be noted that the equations (A.32),(A.33) and (A.36) determine the functions $Y_{l m}(\theta, \phi)$ only up to a phase. Since different phase factor conventions exist in the literature, it is important to carefully check this point in dealing with the functions $Y_{l m}$ used by various authors. The phase of the $Y_{l m}$ is chosen here so that:

1) the functions $Y_{l m}$ verify the recurrence relations (A.39)
2) $Y_{l, 0}(\theta=0)$ is real and positive.

The first few spherical harmonics are given by

$$
\begin{align*}
& Y_{00}=(4 \pi)^{-1 / 2} \\
& Y_{1,0}=\left(\frac{3}{4 \pi}\right)^{1 / 2} \cos \theta, \\
& Y_{1, \pm 1}=\mp\left(\frac{3}{8 \pi}\right)^{1 / 2} \sin \theta \exp ( \pm i \phi), \\
& Y_{2,0}=\left(\frac{5}{16 \pi}\right)^{1 / 2}\left(3 \cos ^{2} \theta-1\right) \\
& Y_{2, \pm 1}=\mp\left(\frac{15}{8 \pi}\right)^{1 / 2} \sin \theta \cos \theta \exp ( \pm i \phi), \\
& Y_{2, \pm 2}=\left(\frac{15}{32 \pi}\right)^{1 / 2} \sin ^{2} \theta \exp ( \pm 2 i \phi)  \tag{A.43}\\
& Y_{3,0}=\left(\frac{7}{16 \pi}\right)^{1 / 2}\left(5 \cos ^{3} \theta-3 \cos \theta\right) \\
& Y_{3, \pm 1}=\mp\left(\frac{21}{64 \pi}\right)^{1 / 2} \sin ^{1 / 2} \theta\left(5 \cos { }^{2} \theta-1\right) \exp ( \pm i \phi), \\
& Y_{3, \pm 2}=\left(\frac{105}{32 \pi}\right)^{1 / 2} \sin ^{2} \theta \cos \theta \exp ( \pm 2 i \phi), \\
& Y_{3, \pm 3}=\mp\left(\frac{35}{64 \pi}\right)^{1 / 2} \sin ^{3} \theta \exp ( \pm 3 i \phi)
\end{align*}
$$

## A.4. USEFUL FORMULAE

Let $\mathbf{r}_{1}$ and $\mathbf{r}_{2}$ be two vectors having polar angles $\left(\theta_{1}, \phi_{1}\right)$ and $\left(\theta_{2}, \phi_{2}\right)$, respectively, and let $\theta$ be the angle between them. The "addition (or biaxial) theorem" of the spherical harmonics states that

$$
\begin{equation*}
P_{l}(\cos \theta)=\frac{4 \pi}{2 l+1} \sum_{m=-l}^{+l} Y_{l m}^{*}\left(\theta_{1}, \phi_{1}\right) Y_{l m}\left(\theta_{2}, \phi_{2}\right) \tag{A.44a}
\end{equation*}
$$

or

$$
\begin{equation*}
P_{l}(\cos \theta)=\frac{4 \pi}{2 l+1} \sum_{m=-l}^{+l} Y_{l m}^{*}\left(\hat{\mathbf{r}}_{1}\right) Y_{l m}\left(\hat{\mathbf{r}}_{2}\right) \tag{A.44b}
\end{equation*}
$$

where $\hat{\mathbf{x}}$ denotes the polar angles of a vector $\mathbf{x}$.

Using the generating function of the Legendre polynomials [see eq. (A.2)] we also see that

$$
\begin{equation*}
\frac{1}{\left|\mathbf{r}_{1}-\mathbf{r}_{2}\right|}=\sum_{l=0}^{\infty} \frac{\left(r_{<}\right)^{l}}{\left(r_{>}\right)^{l+1}} P_{l}(\cos \theta) \tag{A.45}
\end{equation*}
$$

where $r_{<}$is the smaller and $r_{>}$the larger of $r_{1}$ and $r_{2}$. This result may also be written with the help of eq. (A.44b) as

$$
\begin{equation*}
\frac{1}{\left|\mathbf{r}_{1}-\mathbf{r}_{2}\right|}=\sum_{l=0}^{\infty} \sum_{m=-l}^{+l} \frac{4 \pi}{2 l+1} \frac{\left(r_{<}\right)^{l}}{\left(r_{>}\right)^{l+1}} Y_{l m}^{*}\left(\hat{\mathbf{r}}_{1}\right) Y_{l m}\left(\hat{\mathbf{r}}_{2}\right) . \tag{A.46}
\end{equation*}
$$

We also have

$$
\begin{align*}
& \frac{\exp \left(i k\left|\mathbf{r}_{1}-\mathbf{r}_{2}\right|\right)}{\left|\mathbf{r}_{1}-\mathbf{r}_{2}\right|}=i k \sum_{l=0}^{\infty}(2 l+1) j_{l}\left(k r_{<}\right) h_{l}^{(1)}\left(k r_{>}\right) P_{l}(\cos \theta)  \tag{A.47a}\\
& =4 \pi i k \sum_{l=0}^{\infty} \sum_{m=-l}^{+l} j_{l}\left(k r_{<}\right) h_{l}^{(1)}\left(k r_{>}\right) Y_{l m}^{*}\left(\hat{\mathbf{r}}_{1}\right) Y_{l m}\left(\hat{\mathbf{r}}_{2}\right) \tag{A.47b}
\end{align*}
$$

where $j_{l}$ and $h_{l}^{(1)}$ are respectively a spherical Bessel function and a spherical Hankel function of the first kind (see Appendix B).

The development in spherical harmonics of a plane wave $\exp (i \mathbf{k} . \mathbf{r})$ is given by

$$
\begin{equation*}
\exp (i \mathbf{k} \cdot \mathbf{r})=4 \pi \sum_{l=0}^{\infty} \sum_{m=-l}^{+l} i^{l} j_{l}(k r) Y_{l m}^{*}(\hat{\mathbf{k}}) Y_{l m}(\hat{\mathbf{r}}) \tag{A.48}
\end{equation*}
$$

Using the addition theorem (A.44), we may also write

$$
\begin{equation*}
\exp (i \mathbf{k} . \mathbf{r})=\sum_{l=0}^{\infty}(2 l+1) i^{l} j_{l}(k r) P_{l}(\cos \theta) \tag{A.49}
\end{equation*}
$$

where $\theta$ is the angle between the vectors $\mathbf{k}$ and $\mathbf{r}$. In particular, if we choose the z -axis to coincide with the direction of k , we have

$$
\begin{equation*}
\exp (i \mathbf{k} . \mathbf{r})=\exp (i k z)=\sum_{l=0}^{\infty}(2 l+1) i^{l} j_{l}(k r) P_{l}(\cos \theta) \tag{A.50}
\end{equation*}
$$

It may also be shown (see for example Edmonds, 1957) that

$$
\begin{align*}
& \int Y_{l_{1} m_{1}}(\theta, \phi) Y_{l_{2} m_{2}}(\theta, \phi) Y_{l_{3} m_{3}}(\theta, \phi) d \Omega \\
& =\left[\frac{\left(2 l_{1}+1\right)\left(2 l_{2}+1\right)\left(2 l_{3}+1\right)}{4 \pi}\right]^{1 / 2}  \tag{A.51}\\
& \times\left(\begin{array}{ccc}
l_{1} & l_{2} & l_{3} \\
0 & 0 & 0
\end{array}\right)\left(\begin{array}{ccc}
l_{1} & l_{2} & l_{3} \\
m_{1} & m_{2} & m_{3}
\end{array}\right)
\end{align*}
$$

where we have introduced the Wigner $3-j$ symbols (see Appendix E). From eq. (A.51) we find that

$$
\begin{align*}
& Y_{l_{1} m_{1}}(\theta, \phi) Y_{l_{2} m_{2}}(\theta, \phi)=\sum_{L=\left|l_{1}-l_{2}\right|}^{l_{1}+l_{2}} \sum_{M=-L}^{+L}(-1)^{M} \\
& \times\left[\frac{\left(2 l_{1}+1\right)\left(2 l_{2}+1\right)(2 L+1)}{4 \pi}\right]^{1 / 2}  \tag{A.52}\\
& \times\left(\begin{array}{ccc}
l_{1} & l_{2} & L \\
0 & 0 & 0
\end{array}\right)\left(\begin{array}{ccc}
l_{1} & l_{2} & L \\
m_{1} & m_{2} & M
\end{array}\right) Y_{L,-M}(\theta, \phi)
\end{align*}
$$

This last equation may also be written in terms of vector addition (or ClebschGordan) coefficients (see Appendix E) as

$$
\begin{align*}
& Y_{l_{1} m_{1}}(\theta, \phi) Y_{l_{2} m_{2}}(\theta, \phi)=\sum_{L=\left|l_{1}-l_{2}\right|}^{l_{1}+l_{2}} \sum_{M=-L}^{+L}\left[\frac{\left(2 l_{1}+1\right)\left(2 l_{2}+1\right)}{4 \pi(2 L+1)}\right]^{1 / 2}  \tag{А.53}\\
& \times\left(l_{1} 0 l_{2} 0 \mid L 0\right)\left(l_{1} m_{1} l_{2} m_{2} \mid L M\right) Y_{L M}(\theta, \phi)
\end{align*}
$$

We remark that in eqs. (A.52) and (A.53), the summation over $M$ reduces to one term with $M=m_{1}+m_{2}$.

Additional useful formulae may be found for example in Abramowitz and Stegun (1964, Chapter 8), Rose (1957) and Edmonds (1957).

## AppendixB

## Bessel Functions, Modified Bessel Functions, Spherical Bessel Functions and Related Functions

## B.1. BESSEL FUNCTIONS

Let us consider the differential equation

$$
\begin{equation*}
z^{2} \frac{d^{2} w}{d z^{2}}+z \frac{d w}{d z}+\left(z^{2}-\nu^{2}\right) w=0 \tag{B.1}
\end{equation*}
$$

where $\nu$ is a parameter which is assumed to be real. The so-called cylindrical functions are solutions of this equation. Special cylindrical functions are the Bessel functions $J_{\nu}(z)$ [also called Bessel functions of the first kind], the Neumann functions $N_{\nu}(z)$ [also called Bessel functions of the second kind and sometimes denoted $Y_{\nu}(z)$ ] and the Hankel functions $H_{\nu}^{(1)}(z), H_{\nu}^{(2)}(z)$ [also called Bessel functions of the third kind]. These functions may be defined by the following relations (Abramowitz and Stegun, 1964, Chapter 9; Watson, 1966)

$$
\begin{equation*}
J_{\nu}(z)=(z / 2)^{\nu} \sum_{k=0}^{\infty} \frac{\left(-z^{2} / 4\right)^{k}}{k!\Gamma(\nu+k+1)}, \quad|\arg z|<\pi \tag{B.2}
\end{equation*}
$$

where $\Gamma$ is the Gamma-function,

$$
\begin{align*}
& N_{\nu}(z)=\frac{1}{\sin (\nu \pi)}\left[\cos (\nu \pi) J_{\nu}(z)-J_{-\nu}(z)\right], \nu \neq 0, \pm 1, \pm 2, \ldots \\
& |\arg z|<\pi  \tag{B.3}\\
& N_{n}(z)=\lim _{\nu \rightarrow n} N_{\nu}(z), \quad n=0, \pm 1, \pm 2, \ldots ;|\arg z|<\pi  \tag{B.4}\\
& J_{-n}(z)=(-1)^{n} J_{n}(z) ; N_{-n}(z)=(-1)^{n} N_{n}(z), n=0,1,2, \ldots,  \tag{B.5}\\
& H_{\nu}^{(1)}(z)=J_{\nu}(z)+i N_{\nu}(z)  \tag{B.6}\\
& H_{\nu}^{(2)}(z)=J_{\nu}(z)-i N_{\nu}(z) \tag{B.7}
\end{align*}
$$

The functions pairs $\left\{J_{\nu}(z), N_{\nu}(z)\right\}$ and $\left\{H_{\nu}^{(1)}(z), H_{\nu}^{(2)}(z)\right\}$ are linearly independent solutions of eq. (B.1) for all values of $\nu$.

We also note the integral representations

$$
\begin{align*}
J_{\nu}(z)= & \frac{1}{\pi} \int_{0}^{\pi} \cos (z \sin \phi-\nu \phi) d \phi-\frac{\sin (\nu \pi)}{\pi} \int_{0}^{\infty} \exp (-z \sinh t-\nu t) d t \\
& |\arg z|<\pi / 2 \tag{B.8a}
\end{align*}
$$

$$
\begin{align*}
N_{\nu}(z) & =\frac{1}{\pi} \int_{0}^{\pi} \sin (z \sin \phi-\nu \phi) d \phi \\
& -\frac{1}{\pi} \int_{0}^{\infty}[\exp (\nu t)+\exp (-\nu t) \cos (\nu \pi)] \exp (-z \sinh t) d t  \tag{B.8b}\\
& |\arg z|<\pi / 2
\end{align*}
$$

and

$$
\begin{align*}
J_{n}(z) & =\frac{1}{\pi} \int_{0}^{\pi} \cos (z \sin \phi-n \phi) d \phi  \tag{B.8c}\\
& =\frac{i^{-n}}{\pi} \int_{0}^{\pi} \exp (i z \cos \phi) \cos (n \phi) d \phi, n=0,1,2, \ldots
\end{align*}
$$

If $C$ denotes $J, N, H^{(1)}, H^{(2)}$ or any linear combination of these functions (the coefficients of which are independent of $z$ and $\nu$ ) we have the recurrence relations

$$
\begin{align*}
& C_{\nu-1}(z)+C_{\nu+1}(z)=\frac{2 \nu}{z} C_{\nu}(z)  \tag{B.9a}\\
& C_{\nu-1}(z)-C_{\nu+1}(z)=2 \frac{d C_{\nu}(z)}{d z}  \tag{B.9b}\\
& \frac{d C_{\nu}(z)}{d z}=C_{\nu-1}(z)-\frac{\nu}{z} C_{\nu}(z)  \tag{B.9c}\\
& \frac{d C_{\nu}(z)}{d z}=-C_{\nu+1}(z)-\frac{\nu}{z} C_{\nu}(z) \tag{B.9d}
\end{align*}
$$

We also have

$$
\begin{equation*}
\frac{d J_{0}(z)}{d z}=-J_{1}(z) ; \quad \frac{d N_{0}(z)}{d z}=-N_{1}(z) \tag{B.9e}
\end{equation*}
$$

A generating function for the Bessel functions is given by

$$
\begin{equation*}
\exp \left[\frac{z}{2}\left(t-\frac{1}{t}\right)\right]=\sum_{k=-\infty}^{+\infty} t^{k} J_{k}(z), \quad t \neq 0 . \tag{B.10}
\end{equation*}
$$

When $\nu$ is fixed and $z \rightarrow 0$, we have

$$
\begin{align*}
& J_{\nu}(z) \underset{z \rightarrow 0}{\rightarrow} \frac{(z / 2)^{\nu}}{\Gamma(\nu+1)} \quad(\nu \neq-1,-2,-3, \ldots)  \tag{B.11a}\\
& N_{0}(z) \underset{z \rightarrow 0}{\rightarrow} \frac{2}{\pi} \ln z  \tag{B.11b}\\
& N_{\nu}(z) \underset{z \rightarrow 0}{\rightarrow}-\frac{\Gamma(\nu)}{\pi}(z / 2)^{-\nu}, \quad \operatorname{Re} \nu>0 . \tag{B.11c}
\end{align*}
$$

For $\nu$ fixed and $|z| \rightarrow \infty$ we have the asymptotic expressions

$$
\begin{align*}
& J_{\nu}(z) \underset{|z| \rightarrow \infty}{\rightarrow}\left(\frac{2}{\pi z}\right)^{1 / 2} \cos \left(z-\frac{\nu \pi}{2}-\frac{\pi}{4}\right), \quad|\arg z|<\pi,  \tag{B.12a}\\
& N_{\nu}(z) \underset{|z| \rightarrow \infty}{\rightarrow}\left(\frac{2}{\pi z}\right)^{1 / 2} \sin \left(z-\frac{\nu \pi}{2}-\frac{\pi}{4}\right), \quad|\arg z|<\pi,  \tag{B.12b}\\
& H_{\nu}^{(1)}(z) \underset{|z| \rightarrow \infty}{\rightarrow}\left(\frac{2}{\pi z}\right)^{1 / 2} \exp \left[i\left(z-\frac{\nu \pi}{2}-\frac{\pi}{4}\right)\right],-\pi<\arg z<2 \pi,  \tag{B.12c}\\
& H_{\nu}^{(2)}(z) \underset{|z| \rightarrow \infty}{\rightarrow}\left(\frac{2}{\pi z}\right)^{1 / 2} \exp \left[-i\left(z-\frac{\nu \pi}{2}-\frac{\pi}{4}\right)\right],-2 \pi<\arg z<\pi \text {. } \tag{B.12d}
\end{align*}
$$

## B.2. MODIFIED BESSEL FUNCTIONS

Let us now consider the differential equation

$$
\begin{equation*}
z^{2} \frac{d^{2} w}{d z^{2}}+z \frac{d w}{d z}-\left(z^{2}+\nu^{2}\right) w=0 \tag{B.13}
\end{equation*}
$$

The modified cylindrical functions are solutions of this equation. Particular modified cylindrical functions are the modified Bessel functions $I_{\nu}(z)$ and $K_{\nu}(z)$ such that

$$
\begin{align*}
I_{\nu}(z) & =\exp (-\nu \pi i / 2) J_{\nu}[z \exp (i \pi / 2)], \quad-\pi<\arg z \leq \frac{\pi}{2}  \tag{B.14a}\\
& =\exp (3 \nu \pi i / 2) J_{\nu}[z \exp (-3 i \pi / 2)], \quad \frac{\pi}{2}<\arg z \leq \pi \tag{B.14b}
\end{align*}
$$

and

$$
\begin{aligned}
& K_{\nu}(z)=\frac{\pi i}{2} \exp (\nu \pi i / 2) H_{\nu}^{(1)}[z \exp (i \pi / 2)], \quad-\pi<\arg z \leq \frac{\pi}{2} \text { (B.15a) } \\
& =-\frac{\pi i}{2} \exp (-\nu \pi i / 2) H_{\nu}^{(2)}[z \exp (-i \pi / 2)], \quad-\frac{\pi}{2}<\arg z \leq \pi .(\mathrm{B} .15 \mathrm{~b})
\end{aligned}
$$

We also have

$$
\begin{align*}
I_{\nu}(z) & =(z / 2)^{\nu} \sum_{k=0}^{\infty} \frac{\left(z^{2} / 4\right)^{k}}{k!\Gamma(\nu+k+1)}  \tag{B.16}\\
K_{\nu}(z) & =\frac{\pi}{2 \sin (\nu \pi)}\left[I_{-\nu}(z)-I_{\nu}(z)\right], \quad \nu \neq 0, \pm 1, \pm 2, \ldots  \tag{B.17}\\
K_{n}(z) & =\lim _{\nu \rightarrow n} K_{\nu}(z), \quad n=0, \pm 1, \pm 2, \ldots  \tag{B.18}\\
K_{0}(z) & =-\{\ln (z / 2)+\gamma\} I_{0}(z)+\frac{z^{2} / 4}{(1!)^{2}} \\
& +\left(1+\frac{1}{2}\right) \frac{\left(z^{2} / 4\right)^{2}}{(2!)^{2}}+\left(1+\frac{1}{2}+\frac{1}{3}\right) \frac{\left(z^{2} / 4\right)^{3}}{(3!)^{2}}+\ldots \tag{B.19}
\end{align*}
$$

where $\gamma=0.5772156649 \ldots$ is Euler's constant,

$$
\begin{align*}
I_{-n}(z) & =I_{n}(z), \quad n=0,1,2, \ldots  \tag{B.20}\\
K_{-\nu}(z) & =K_{\nu}(z) \tag{B.21}
\end{align*}
$$

We also note the integral representations

$$
\begin{gather*}
I_{\nu}=\frac{1}{\pi} \int_{0}^{\pi} \exp (z \cos \phi) \cos (\nu \phi) d \phi-\frac{\sin (\nu \pi)}{\pi} \int_{0}^{\infty} \exp (-z \cosh t-\nu t) d t \\
|\arg z|<\frac{\pi}{2}  \tag{B.22a}\\
K_{\nu}(z)=\int_{0}^{\pi} \exp (-z \cosh t) \cosh (\nu t) d t, \quad|\arg z|<\frac{\pi}{2},  \tag{B.22b}\\
K_{\nu}(z)=\frac{\pi^{1 / 2}(z / 2)^{\nu}}{\Gamma\left(\nu+\frac{1}{2}\right)} \int_{1}^{\infty} \frac{\exp (-z t)}{\left(t^{2}-1\right)^{1 / 2-\nu}} d t  \tag{B.22c}\\
\operatorname{Re} \nu>-\frac{1}{2},|\arg z|<\frac{\pi}{2} .
\end{gather*}
$$

In particular,

$$
\begin{align*}
K_{0}(z)= & \int_{1}^{\infty} \frac{\exp (-z t)}{\left(t^{2}-1\right)^{1 / 2}} d t=\int_{0}^{\infty} \frac{\exp \left[-z\left(u^{2}+1\right)^{1 / 2}\right]}{\left(u^{2}+1\right)^{1 / 2}} d u  \tag{B.22d}\\
& |\arg z|<\frac{\pi}{2}
\end{align*}
$$

If $Z$ denotes $I_{\nu}, \exp (\nu \pi i) K_{\nu}$ or any linear combination of these functions (the coefficients of which are independent of $z$ and $\nu$ ), we have the recurrence relations

$$
\begin{align*}
& Z_{\nu-1}(z)-Z_{\nu+1}(z)=\frac{2 \nu}{z} Z_{\nu}(z)  \tag{B.23a}\\
& \frac{d Z_{\nu}(z)}{d z}=Z_{\nu-1}(z)-\frac{\nu}{z} Z_{\nu}(z)  \tag{B.23b}\\
& Z_{\nu-1}(z)+Z_{\nu+1}(z)=2 \frac{d Z_{\nu}(z)}{d z}  \tag{B.23c}\\
& \frac{d Z_{\nu}(z)}{d z}=Z_{\nu+1}(z)+\frac{\nu}{z} Z_{\nu}(z) \tag{B.23d}
\end{align*}
$$

We also have

$$
\begin{equation*}
\frac{d I_{0}(z)}{d z}=I_{1}(z) ; \quad \frac{d K_{0}(z)}{d z}=-K_{1}(z) \tag{B.23e}
\end{equation*}
$$

When $\nu$ is fixed and $z \rightarrow 0$,

$$
\begin{align*}
& I_{\nu}(z) \underset{z \rightarrow 0}{\rightarrow} \frac{(z / 2)^{\nu}}{\Gamma(\nu+1)} \quad(\nu \neq-1,-2,-3, \ldots)  \tag{B.24a}\\
& K_{0}(z) \underset{z \rightarrow 0}{\rightarrow}-\ln z  \tag{B.24b}\\
& K_{\nu}(z) \underset{z \rightarrow 0}{\rightarrow} \frac{1}{2} \Gamma(\nu)(z / 2)^{-\nu} \quad \operatorname{Re} \nu>0 . \tag{B.24c}
\end{align*}
$$

## B.3. SPHERICAL BESSEL FUNCTIONS

Let us consider the differential equation

$$
\begin{equation*}
\frac{d^{2} w}{d z^{2}}+\frac{2}{z} \frac{d w}{d z}+\left[1-\frac{l(l+1)}{z^{2}}\right] w=0 \tag{B.25}
\end{equation*}
$$

with $l=0,1,2, \ldots$ Particular solutions of this equation are the spherical Bessel functions (or spherical Bessel functions of the first kind)

$$
\begin{equation*}
j_{l}(z)=\left(\frac{\pi}{2 z}\right)^{1 / 2} J_{l+1 / 2}(z) \tag{B.26}
\end{equation*}
$$

the spherical Neumann functions (or spherical Bessel functions of the second kind)

$$
\begin{align*}
n_{l}(z) & =(-1)^{l+1}\left(\frac{\pi}{2 z}\right)^{1 / 2} J_{-l-1 / 2}(z)  \tag{B.27}\\
& =\left(\frac{\pi}{2 z}\right)^{1 / 2} N_{l+1 / 2}(z)
\end{align*}
$$

and the spherical Hankel functions of the first and second kind

$$
\begin{align*}
h_{l}^{(1)}(z) & =j_{l}(z)+i n_{l}(z) \\
& =\left(\frac{\pi}{2 z}\right)^{1 / 2} H_{l+1 / 2}^{(1)}(z)  \tag{B.28}\\
h_{l}^{(2)}(z) & =j_{l}(z)-i n_{l}(z) \\
& =\left(\frac{\pi}{2 z}\right)^{1 / 2} H_{l+1 / 2}^{(2)}(z) \tag{B.29}
\end{align*}
$$

The functions $j_{l}(z)$ are regular while the functions $n_{l}(z), h_{l}^{(1)}(z)$ and $h_{l}^{(2)}(z)$ are irregular at the origin. The functions pairs $\left\{j_{l}(z), n_{l}(z)\right\}$ and $\left\{h_{l}^{(1)}(z), h_{l}^{(2)}(z)\right\}$ are linearly independent solutions of eq. (B.25) for every $l$.

The first three functions $j_{l}(z)$ and $n_{l}(z)$ are given explicitly by

$$
\begin{align*}
& j_{0}(z)=\frac{\sin z}{z} \\
& j_{1}(z)=\frac{\sin z}{z^{2}}-\frac{\cos z}{z}  \tag{B.30a}\\
& j_{2}(z)=\left(\frac{3}{z^{3}}-\frac{1}{z}\right) \sin z-\frac{3}{z^{2}} \cos z
\end{align*}
$$

and

$$
\begin{align*}
& n_{0}(z)=-\frac{\cos z}{z} \\
& n_{1}(z)=-\frac{\cos z}{z^{2}}-\frac{\sin z}{z}  \tag{B.30b}\\
& n_{2}(z)=-\left(\frac{3}{z^{3}}+\frac{1}{z}\right) \cos z-\frac{3}{z^{2}} \sin z
\end{align*}
$$

The functions $j_{l}(z)$ and $n_{l}(z)$ may be represented by the ascending series

$$
\begin{align*}
j_{l}(z) & =\frac{z^{l}}{(2 l+1)!!} \\
& \times\left[1-\frac{z^{2} / 2}{1!(2 l+3)}+\frac{\left(z^{2} / 2\right)^{2}}{2!(2 l+3)(2 l+5)}-\ldots\right]  \tag{B.31a}\\
n_{l}(z) & =-\frac{(2 l-1)!!}{z^{l+1}} \\
& \times\left[1-\frac{z^{2} / 2}{1!(1-2 l)}+\frac{\left(z^{2} / 2\right)^{2}}{2!(1-2 l)(3-2 l)}-\ldots\right] \tag{B.31b}
\end{align*}
$$

and for $l$ fixed and $z \rightarrow 0$ we see that

$$
\begin{align*}
& j_{l}(z) \underset{z \rightarrow 0}{\rightarrow} \frac{z^{l}}{(2 l+1)!!},  \tag{B.32a}\\
& n_{l}(z) \underset{z \rightarrow 0}{\rightarrow}-\frac{(2 l-1)!!}{z^{l+1}} . \tag{B.32b}
\end{align*}
$$

For $l$ fixed and real $x \rightarrow \infty$ [in fact for $x$ somewhat larger than $l(l+1) / 2$ ] we have the asymptotic formulae

$$
\begin{gather*}
j_{l}(x) \underset{x \rightarrow \infty}{\rightarrow} \frac{1}{x} \sin \left(x-\frac{l \pi}{2}\right),  \tag{B.33a}\\
n_{l}(x) \underset{x \rightarrow \infty}{\rightarrow}-\frac{1}{x} \cos \left(x-\frac{l \pi}{\pi}\right),  \tag{B.33b}\\
h_{l}^{(1)}(x) \underset{x \rightarrow \infty}{\rightarrow}-i \frac{\exp [i(x-l \pi / 2)]}{x},  \tag{B.33c}\\
h_{l}^{(2)}(x) \underset{x \rightarrow \infty}{\rightarrow} i \frac{\exp [-i(x-l \pi / 2)]}{x} . \tag{B.33d}
\end{gather*}
$$

If $f_{l}$ denotes $j_{l}, n_{l}, h_{l}^{(1)}$ or $h_{l}^{(2)}$, we have the recurrence relations (with $l>0$ )

$$
\begin{align*}
& f_{l-1}(z)+f_{l+1}(z)=(2 l+1) z^{-1} f_{l}(z)  \tag{B.34a}\\
& l f_{l-1}(z)-(l+1) f_{l+1}(z)=(2 l+1) \frac{d}{d z} f_{l}(z)  \tag{B.34b}\\
& \frac{l+1}{z} f_{l}(z)+\frac{d}{d z} f_{l}(z)=f_{l-1}(z)  \tag{B.34c}\\
& \frac{l}{z} f_{l}(z)-\frac{d}{d z} f_{l}(z)=f_{l+1}(z) \tag{B.34d}
\end{align*}
$$

We also have the differentiation formulae (with $m=1,2,3, \ldots$ )

$$
\begin{align*}
\left(\frac{1}{z} \frac{d}{d z}\right)^{m}\left[z^{l+1} f_{l}(z)\right] & =z^{l-m+1} f_{l-m}(z)  \tag{B.35a}\\
\left(\frac{1}{z} \frac{d}{d z}\right)^{m}\left[z^{-l} f_{l}(z)\right] & =(-1)^{m} z^{-l-m} f_{l+m}(z) \tag{B.35b}
\end{align*}
$$

and the additional useful relations

$$
\begin{align*}
j_{l}(z) n_{l-1}(z)-j_{l-1}(z) n_{l}(z) & =z^{-2}, \quad l>0  \tag{B.36a}\\
j_{l}(z) \frac{d}{d z} n_{l}(z)-n_{l}(z) \frac{d}{d z} j_{l}(z) & =z^{-2} \tag{B.36b}
\end{align*}
$$

We also quote the following indefinite integrals

$$
\begin{align*}
\int j_{0}^{2}(x) x^{2} d x & =\frac{1}{2} x^{3}\left[j_{0}^{2}(x)+n_{0}(x) j_{1}(x)\right]  \tag{B.37a}\\
\int n_{0}^{2}(x) x^{2} d x & =\frac{1}{2} x^{3}\left[n_{0}^{2}(x)-j_{0}(x) n_{1}(x)\right]  \tag{B.37b}\\
\int j_{1}(x) d x & =-j_{0}(x)  \tag{B.37c}\\
\int j_{0}(x) x^{2} d x & =x^{2} j_{1}(x)  \tag{B.37d}\\
\int j_{l}^{2}(x) x^{2} d x & =\frac{1}{2} x^{3}\left[j_{l}^{2}(x)-j_{l-1}(x) j_{l+1}(x)\right], \quad l>0 \tag{B.37e}
\end{align*}
$$

The following definite integrals involving the functions $j_{l}$ often appear in electron-atom scattering calculations:

$$
\begin{align*}
& \int_{0}^{\infty} \exp (-a x) j_{l}(b x) x^{\mu-1} d x \\
& =\frac{\pi^{1 / 2} b l \Gamma(\mu+l)}{2^{l+1} a^{\mu+l} \Gamma(l+3 / 2)}{ }_{2} F_{1}\left(\frac{\mu+l}{2}, \frac{\mu+l+1}{2} ; l+\frac{3}{2} ;-\frac{b^{2}}{a^{2}}\right)  \tag{B.38a}\\
& \operatorname{Re}(a+i b)>0, \operatorname{Re}(a-i b)>0, \operatorname{Re}(\mu+l)>0
\end{align*}
$$

where

$$
\begin{equation*}
{ }_{2} F_{1}(a, b ; c ; z)=1+\frac{a b}{c} \frac{z}{1!}+\frac{a(a+1) b(b+1)}{c(c+1)} \frac{z^{2}}{2!}+\ldots \tag{B.38b}
\end{equation*}
$$

is the hypergeometric function,

$$
\begin{align*}
& \int_{0}^{\infty} \exp (-a x) j_{l}(b x) x^{l+1} d x=\frac{(2 b)^{l} \Gamma(l+1)}{\left(a^{2}+b^{2}\right)^{l+1}}, \quad \operatorname{Re} a>|\operatorname{Im} b|,  \tag{B.38c}\\
& \int_{0}^{\infty} \exp (-a x) j_{l}(b x) x^{l+2} d x=\frac{2 a(2 b)^{l} \Gamma(l+2)}{\left(a^{2}+b^{2}\right)^{l+2}}, \quad \operatorname{Re} a>|\operatorname{Im} b| . \tag{B.38d}
\end{align*}
$$

Similar integrals involving higher powers of $x$ may be obtained by differentiation with respect to the quantity $a$.

Finally, we remark that

$$
\begin{equation*}
\int_{0}^{\infty} j_{l}(k r) j_{l}\left(k^{\prime} r\right) r^{2} d r=\frac{\pi}{2 k^{2}} \delta\left(k-k^{\prime}\right) \tag{B.39}
\end{equation*}
$$

Additional useful formulae are given for example in Abramowitz and Stegun (1964, Chapters 9 and 10) and Watson (1966).

## Appendix C

## DaLITZ InTEGRALS

In this appendix we shall study integrals of the type (Dalitz, 1951, Joachain, 1983)

$$
\begin{align*}
& I_{m, n}\left(\alpha, \beta ; \mathbf{k}_{i}, \mathbf{k}_{f} ; \bar{k}\right) \\
& =\int d \mathbf{q} \frac{1}{q^{2}-\bar{k}^{2}-i \epsilon} \frac{1}{\left[\alpha^{2}+\left(\mathbf{q}-\mathbf{k}_{i}\right)^{2}\right]^{m}} \frac{1}{\left[\beta^{2}+\left(\mathbf{q}-\mathbf{k}_{f}\right)^{2}\right]^{n}} \tag{C.1}
\end{align*}
$$

with $\epsilon \rightarrow 0^{+}$. Following Feynman (1949), we first set

$$
\begin{align*}
a & =\alpha^{2}+\left(\mathbf{q}-\mathbf{k}_{i}\right)^{2} \\
b & =\beta^{2}+\left(\mathbf{q}-\mathbf{k}_{f}\right)^{2} \tag{C.2}
\end{align*}
$$

and use the integral representation

$$
\begin{equation*}
\frac{1}{a b}=\int_{0}^{1} \frac{d t}{[a t+b(1-t)]^{2}} \tag{C.3a}
\end{equation*}
$$

By differentiating both sides of eq. (C.3a) with respect to $a$ or (and) $b$, we also have

$$
\begin{align*}
\frac{1}{a^{2} b} & =2 \int_{0}^{1} \frac{t}{[a t+b(1-t)]^{3}} d t  \tag{C.3b}\\
\frac{1}{a b^{2}} & =2 \int_{0}^{1} \frac{1-t}{[a t+b(1-t)]^{3}} d t,  \tag{C.3c}\\
& \vdots \\
\frac{1}{a^{m} b^{n}} & =\frac{(m+n-1)!}{(m-1)!(n-1)!} \int_{0}^{1} \frac{t^{m-1}(1-t)^{n-1}}{[a t+b(1-t)]^{m+n}} d t \tag{C.3d}
\end{align*}
$$

so that we may rewrite eq. (C.1) as

$$
\begin{align*}
& I_{m, n}\left(\alpha, \beta ; \mathbf{k}_{i}, \mathbf{k}_{f} ; \bar{k}\right)=\frac{(m+n-1)!}{(m-1)!(n-1)!} \int_{0}^{1} d t t^{m-1}(1-t)^{n-1} \\
& \times \int d \mathbf{q} \frac{1}{q^{2}-\bar{k}^{2}-i \epsilon}  \tag{C.4}\\
& \times \frac{1}{\left[\alpha^{2} t+\left(\mathbf{q}-\mathbf{k}_{i}\right)^{2} t+\beta^{2}(1-t)+\left(\mathbf{q}-\mathbf{k}_{f}\right)^{2}(1-t)\right]^{m+n}}
\end{align*}
$$

We now observe that

$$
\begin{equation*}
\alpha^{2} t+\left(\mathbf{q}-\mathbf{k}_{i}\right)^{2} t+\beta^{2}(1-t)+\left(\mathbf{q}-\mathbf{k}_{f}\right)^{2}(1-t)=\Gamma^{2}+(\mathbf{q}-\boldsymbol{\Lambda})^{2} \tag{C.5}
\end{equation*}
$$

where

$$
\begin{align*}
\mathbf{\Lambda} & =t \mathbf{k}_{i}+(1-t) \mathbf{k}_{f},  \tag{C.6}\\
\Gamma^{2} & =\alpha^{2} t+\beta^{2}(1-t)+t(1-t)\left(\mathbf{k}_{i}-\mathbf{k}_{f}\right)^{2} \\
& =\alpha^{2} t+\beta^{2}(1-t)+t(1-t) \Delta^{2} \tag{C.7}
\end{align*}
$$

and we recall that $\Delta=\mathbf{k}_{i}-\mathbf{k}_{f}$ is the momentum transfer.
Apart from a one-dimensional integral on the $t$ variable, the calculation of $I_{m, n}\left(\alpha, \beta ; \mathbf{k}_{i}, \mathbf{k}_{f} ; \bar{k}\right)$ therefore reduces to the evaluation of integrals of the type

$$
\begin{equation*}
L_{S}=\int d \mathbf{q} \frac{1}{q^{2}-\bar{k}^{2}-i \epsilon} \frac{1}{\left[\Gamma^{2}+(\mathbf{q}-\mathbf{\Lambda})^{2}\right]^{S}} \tag{C.8}
\end{equation*}
$$

Let us begin by considering the case $S=1$. Using spherical coordinates $\left(q, \theta_{q}, \phi_{q}\right)$ in $\mathbf{q}$ space, taking the z -axis along the vector $\boldsymbol{\Lambda}$ and performing the integration over the azimuthal angle $\phi_{q}$, we find that

$$
\begin{align*}
L_{1} & =2 \pi \int_{0}^{\pi} d \theta_{q} \sin \theta_{q} \int_{0}^{+\infty} d q q^{2}  \tag{C.9}\\
& \frac{1}{q^{2}-\bar{k}^{2}-i \epsilon} \times \frac{1}{\Gamma^{2}+q^{2}+\Lambda^{2}-2 q \Lambda \cos \theta_{q}}
\end{align*}
$$

Upon changing the integration variables in this equation to $q^{\prime}=-q$ and $\theta_{q^{\prime}}=$ $\pi-\theta_{q}$, we can also write

$$
\begin{align*}
L_{1} & =2 \pi \int_{0}^{\pi} d \theta_{q^{\prime}} \sin \theta_{q^{\prime}} \int_{-\infty}^{0} d q^{\prime} q^{\prime 2}  \tag{C.10}\\
& \times \frac{1}{q^{\prime 2}-\bar{k}^{2}-i \epsilon} \frac{1}{\Gamma^{2}+q^{\prime 2}+\Lambda^{2}-2 q^{\prime} \Lambda \cos \theta_{q^{\prime}}}
\end{align*}
$$

so that, by comparing eqs. (C.9) and (C.10), we have

$$
\begin{align*}
L_{1} & =\pi \int_{0}^{\pi} d \theta_{q} \sin \theta_{q} \int_{-\infty}^{+\infty} d q q^{2}  \tag{C.11}\\
& \times \frac{1}{q^{2}-\bar{k}^{2}-i \epsilon} \frac{1}{\Gamma^{2}+q^{2}+\Lambda^{2}-2 q \Lambda \cos \theta_{q}}
\end{align*}
$$

The integral on the $q$ variable may be performed by considering $q$ as a complex variable and closing the contour with a semi-circle of infinite radius in the upper-half complex $q$-plane. The poles of the denominator in this upper-half $q$-plane are located at $q_{1}$ and $q_{2}$, with

$$
\begin{equation*}
q_{1}=\bar{k}+i \epsilon, \quad q_{2}=\Lambda \cos \theta_{q}+i\left(\Gamma^{2}+\Lambda^{2} \sin ^{2} \theta_{q}\right)^{1 / 2} \tag{C.12}
\end{equation*}
$$

Hence, using the residue theorem, we have

$$
\begin{equation*}
L_{1}=\pi^{2} i \bar{k} \int_{-1}^{+1} \frac{d \omega}{\Gamma^{2}+\bar{k}^{2}+\Lambda^{2}-2 \bar{k} \Lambda \omega}+\frac{\pi^{2} i}{\Lambda} \int_{i \Gamma-\Lambda}^{i \Gamma+\Lambda} \frac{q_{2}}{q_{2}^{2}-\bar{k}^{2}-i \epsilon} d q_{2} \tag{C.13}
\end{equation*}
$$

where we have set $\omega=\cos \theta_{q}$ in the first integral. Performing the integrals in eq. (C.13), we obtain

$$
\begin{equation*}
L_{1}(\bar{k}, \Gamma, \Lambda)=\frac{\pi^{2} i}{\Lambda} \ln \left(\frac{\bar{k}+\Lambda+i \Gamma}{\bar{k}-\Lambda+i \Gamma}\right) \tag{C.14}
\end{equation*}
$$

The integrals $L_{S}$ for $S=2,3, \ldots$ may be readily obtained from $L_{1}$ by successive differentiations with respect to $\Gamma$. Thus we have

$$
\begin{align*}
L_{2}(\bar{k}, \Gamma, \Lambda) & =-\frac{1}{2 \Gamma} \frac{\partial}{\partial \Gamma} L_{1}(\bar{k}, \Gamma, \Lambda) \\
& =-\frac{\pi^{2}}{\Gamma\left(\bar{k}^{2}-\Gamma^{2}-\Lambda^{2}+2 i \bar{k} \Gamma\right)}  \tag{C.15a}\\
& \vdots  \tag{C.15b}\\
L_{S}(\bar{k}, \Gamma, \Lambda) & =-\frac{1}{2(S-1) \Gamma} \frac{\partial}{\partial \Gamma} L_{S-1}(\bar{k}, \Gamma, \Lambda)
\end{align*}
$$

Let us now return to the expression for $I_{m, n}\left(\alpha, \beta ; \mathbf{k}_{i}, \mathbf{k}_{f} ; \bar{k}\right)$ given by eq. (C.4). In certain cases simple closed form expressions may be obtained for the integration on the variable $t$. For example, when $m=n=1$ we have (Lewis, 1956)

$$
\begin{equation*}
I_{1,1}\left(\alpha, \beta ; \mathbf{k}_{i}, \mathbf{k}_{f} ; \bar{k}\right)=\pi^{2}\left(A^{2}-B\right)^{-1 / 2} \ln \left[\frac{A+\left(A^{2}-B\right)^{1 / 2}}{A-\left(A^{2}-B\right)^{1 / 2}}\right] \tag{C.16a}
\end{equation*}
$$

where

$$
\begin{equation*}
A=-i \bar{k}\left[\Delta^{2}+(\alpha+\beta)^{2}\right]+\alpha\left(k_{f}^{2}+\beta^{2}-\bar{k}^{2}\right)+\beta\left(k_{i}^{2}+\alpha^{2}-\bar{k}^{2}\right) \tag{C.16b}
\end{equation*}
$$

and

$$
\begin{equation*}
B=\left[\Delta^{2}+(\alpha+\beta)^{2}\right]\left[k_{i}^{2}+(\alpha-i \bar{k})^{2}\right]\left[k_{f}^{2}+(\beta-i \bar{k})^{2}\right] \tag{C.16c}
\end{equation*}
$$

It should be noted that the function on the right of eq. (C.16a) is single valued, even when we cross a branch cut of $\left(A^{2}-B\right)^{1 / 2}$, i.e. either square root can be chosen. This function is therefore analytic, the only problem being the specification of the branch of the logarithm; examination shows that we must take the arguments of numerator and denominator from $-\pi$ to $+\pi$.

Let us look in more detail at the particular case for which $\alpha=\beta \neq 0$ and $k_{i}=k_{f}=\bar{k}=k$. Using eqs. (C.16), we find that

$$
\begin{align*}
I_{1,1}\left(\alpha, \alpha ; \mathbf{k}_{i}, \mathbf{k}_{f} ; k\right) & =\frac{2 \pi^{2}}{\Delta\left[\alpha^{4}+4 k^{2} \alpha^{2}+k^{2} \Delta^{2}\right]^{1 / 2}} \\
& \times\left\{\tan ^{-1} \frac{\alpha \Delta}{2\left[\alpha^{4}+4 k^{2} \alpha^{2}+k^{2} \Delta^{2}\right]^{1 / 2}}\right.  \tag{C.17}\\
& \left.+\frac{1}{2} i \ln \left[\frac{\left(\alpha^{4}+4 k^{2} \alpha^{2}+k^{2} \Delta^{2}\right)^{1 / 2}+k \Delta}{\left(\alpha^{4}+4 k^{2} \alpha^{2}+k^{2} \Delta^{2}\right)^{1 / 2}-k \Delta}\right]\right\}
\end{align*}
$$

We remark that this result may also be obtained by using eqs. (C.4), (C.15a) and the fact that we have here $\Gamma^{2}+\Lambda^{2}=k^{2}+\alpha^{2}$. Thus we may write

$$
\begin{equation*}
I_{1,1}\left(\alpha, \alpha ; \mathbf{k}_{i}, \mathbf{k}_{f} ; k\right)=\pi^{2} \int_{0}^{1} \frac{d t}{\Gamma\left(\alpha^{2}-2 i k \Gamma\right)} \tag{C.18}
\end{equation*}
$$

with $\Gamma=\left(\alpha^{2}+t(1-t) \Delta^{2}\right)^{1 / 2}$. The integral (C.18) is then readily performed in closed form to yield the expression given by eq. (C.17). Substitution of the result (C.17) in eq. (2.37) yields the second Born term (2.38) corresponding to scattering by the Yukawa potential (2.26).

## Appendix D

## The Density Matrix

A quantum system is said to be in a pure state when it is completely specified by a single state vector, which is fully determined apart from a constant phase factor. Quantum systems in pure states are prepared by performing a "maximal measurement" or "complete experiment" in which all values of a complete set of commuting observables are determined. Hence pure states represent the ultimate limit of precise observation as allowed by the uncertainty principle; for this reason they are also called states of "maximum knowledge".

In many cases, however, the measurement made on the system is not maximal. For instance, a beam of particles may be prepared in such a way that certain quantum numbers (e.g. the spin orientation) are only known through a probability distribution. Such systems, which cannot be described by a single state vector, are said to be in mixed states. The study of these systems can conveniently be made using the density matrix formalism (von Neumann, 1927; Fano, 1957; ter Haar, 1961; Blum, 1981). This method also presents the advantage of treating pure and mixed systems on the same footing. In this appendix we shall briefly discuss the general properties of the density matrix.

Let us consider a system consisting of an ensemble of $N$ subsystems $\alpha=$ $1,2, \ldots, N$. We suppose that each of these subsystems is in a pure state and is therefore characterized by a distinct state vector $\Psi^{(\alpha)}$, which we denote by $|\alpha\rangle$ in the Dirac notation. The state vectors $|\alpha\rangle$ are assumed to be normalized, but need not be orthogonal to each other.

Next, we choose a complete set of basis states $|n\rangle$, namely orthonormal eigenvectors of some complete set of operators. Since these basis states are orthonormal,

$$
\begin{equation*}
\left\langle n^{\prime} \mid n\right\rangle=\delta_{n^{\prime} n} \text { or } \delta\left(n^{\prime}-n\right) \tag{D.1}
\end{equation*}
$$

and because they are complete

$$
\begin{equation*}
\sum_{n}|n\rangle\langle n|=1 . \tag{D.2}
\end{equation*}
$$

Let us expand the pure state $|\alpha\rangle$ in the basis states $|n\rangle$. We have

$$
\begin{equation*}
|\alpha\rangle=\sum_{n} c_{n}^{(\alpha)}|n\rangle \tag{D.3}
\end{equation*}
$$

with

$$
\begin{equation*}
c_{n}^{(\alpha)}=\langle n \mid \alpha\rangle \tag{D.4}
\end{equation*}
$$

and

$$
\begin{equation*}
\sum_{n}\left|c_{n}^{(\alpha)}\right|^{2}=1 \tag{D.5}
\end{equation*}
$$

Consider now an observable represented by an operator $A$. The expectation value of this operator in the pure state $|\alpha\rangle$ is

$$
\begin{align*}
\langle A\rangle_{\alpha} & =\langle\alpha| A|\alpha\rangle=\sum_{n} \sum_{n^{\prime}} c_{n^{\prime}}^{(\alpha) *} c_{n}^{(\alpha)}\left\langle n^{\prime}\right| A|n\rangle \\
& =\sum_{n} \sum_{n^{\prime}}\langle n \mid \alpha\rangle\left\langle\alpha \mid n^{\prime}\right\rangle\left\langle n^{\prime}\right| A|n\rangle \tag{D.6}
\end{align*}
$$

The average value of $A$ over the ensemble is therefore given by

$$
\begin{equation*}
\langle A\rangle=\sum_{\alpha=1}^{N} W_{\alpha}\langle A\rangle_{\alpha} \tag{D.7}
\end{equation*}
$$

where $W_{\alpha}$ is the statistical weight of the subsystem $\alpha$, namely the probability of obtaining this subsystem among the ensemble. The statistical weights $W_{\alpha}$ must obviously be such that

$$
\begin{equation*}
0 \leq W_{\alpha} \leq 1 \tag{D.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\sum_{\alpha=1}^{N} W_{\alpha}=1 \tag{D.9}
\end{equation*}
$$

Using the result (D.6), we may write eq. (D.7) explicitly as

$$
\begin{align*}
\langle A\rangle & =\sum_{\alpha=1}^{N} W_{\alpha} \sum_{n} \sum_{n^{\prime}} c_{n^{\prime}}^{(\alpha) *} c_{n}^{(\alpha)}\left\langle n^{\prime}\right| A|n\rangle  \tag{D.10}\\
& =\sum_{\alpha=1}^{N} \sum_{n} \sum_{n^{\prime}}\langle n \mid \alpha\rangle W_{\alpha}\left\langle\alpha \mid n^{\prime}\right\rangle\left\langle n^{\prime}\right| A|n\rangle .
\end{align*}
$$

Let us now introduce the density operator (or statistical operator) which is defined as

$$
\begin{equation*}
\rho=\sum_{\alpha=1}^{N}|\alpha\rangle W_{\alpha}\langle\alpha| \tag{D.11}
\end{equation*}
$$

Taking matrix elements of the density operator between the basis states $|n\rangle$, we obtain the elements of the density matrix in the $\{|n\rangle\}$ representation, namely

$$
\begin{align*}
\rho_{n n^{\prime}} \equiv\langle n| \rho\left|n^{\prime}\right\rangle & =\sum_{\alpha=1}^{N}\langle n \mid \alpha\rangle W_{\alpha}\left\langle\alpha \mid n^{\prime}\right\rangle \\
& =\sum_{\alpha=1}^{N} W_{\alpha} c_{n^{\prime}}^{(\alpha) *} c_{n}^{(\alpha)} \tag{D.12}
\end{align*}
$$

Returning to eq. (D.10), we see that

$$
\begin{align*}
\langle A\rangle & =\sum_{n} \sum_{n^{\prime}}\langle n| \rho\left|n^{\prime}\right\rangle\left\langle n^{\prime}\right| A|n\rangle \\
& =\sum_{n}\langle n| \rho A|n\rangle  \tag{D.13}\\
& =\operatorname{Tr}(\rho A)
\end{align*}
$$

where the symbol $\operatorname{Tr}$ denotes the trace. Hence the knowledge of $\rho$ enables us to obtain the statistical average of $A$. We also remark that if we take $A$ to be the identity operator, we obtain the normalization condition

$$
\begin{equation*}
\operatorname{Tr} \rho=1 \tag{D.14}
\end{equation*}
$$

As seen from its definition (D.11), the density operator $\rho$ is Hermitian, namely

$$
\begin{equation*}
\rho=\rho^{\dagger} \tag{D.15}
\end{equation*}
$$

or

$$
\begin{equation*}
\langle n| \rho\left|n^{\prime}\right\rangle=\left\langle n^{\prime}\right| \rho|n\rangle^{*} . \tag{D.16}
\end{equation*}
$$

As a result, the density matrix may always be diagonalized by means of a unitary transformation.

The diagonal elements of the density matrix,

$$
\begin{equation*}
\rho_{n n}=\langle n| \rho|n\rangle=\sum_{\alpha=1}^{N} W_{\alpha}\left|c_{n}^{(\alpha)}\right|^{2} \tag{D.17}
\end{equation*}
$$

have a simple physical interpretation. Indeed, the probability of finding the system in the pure state $|\alpha\rangle$ is $W_{\alpha}$ and the probability that $|\alpha\rangle$ is to be found in the state $|n\rangle$ is $\left|c_{n}^{(\alpha)}\right|^{2}$. Thus the diagonal element $\rho_{n n}$ gives the probability of finding a member of the ensemble in the state $n$. We also note from eqs. (D.8) and (D.17) that

$$
\begin{equation*}
\rho_{n n} \geq 0 \tag{D.18}
\end{equation*}
$$

so that $\rho$ is a positive semi-definite operator. Moreover, combining the above result with eq. (D.14), we see that all diagonal elements of the density matrix must be such that

$$
\begin{equation*}
0 \leq \rho_{n n} \leq 1 \tag{D.19}
\end{equation*}
$$

Let us choose a representation $\{k\}$ in which the density matrix is diagonal. In that representation, we clearly have

$$
\begin{equation*}
\rho_{k k^{\prime}}=\rho_{k k} \delta_{k k^{\prime}} \tag{D.20}
\end{equation*}
$$

where $\rho_{k k}$ is the fraction of the members of the ensemble in the state $|k\rangle$. Moreover, using eqs (D.14) and (D.19), we have

$$
\begin{equation*}
\operatorname{Tr}\left(\rho^{2}\right) \leq \operatorname{Tr} \rho=1 \tag{D.21}
\end{equation*}
$$

This relation remains valid in any representation since the trace is invariant under a unitary transformation. It is worth noting that because the density matrix is Hermitian the result (D.21) may also be written in the form

$$
\begin{equation*}
\sum_{n} \sum_{n^{\prime}}\left|\rho_{n n^{\prime}}\right|^{2} \leq 1 \tag{D.22}
\end{equation*}
$$

Let us now consider the particular case such that the system is in a pure state $|\lambda\rangle$. Then $W_{\alpha}=\delta_{\alpha \lambda}$ and we see from eq. (D.11) that the density operator is just

$$
\begin{equation*}
\rho^{\lambda}=|\lambda\rangle\langle\lambda| \tag{D.23}
\end{equation*}
$$

This is a projection operator onto the state $|\lambda\rangle$, with

$$
\begin{equation*}
\left(\rho^{\lambda}\right)^{2}=\rho^{\lambda} . \tag{D.24}
\end{equation*}
$$

Hence, in this case the relation (D.21) becomes

$$
\begin{equation*}
\operatorname{Tr}\left(\rho^{\lambda}\right)^{2}=\operatorname{Tr} \rho^{\lambda}=1 \tag{D.25}
\end{equation*}
$$

and eqs. (D.10) and (D.13) reduce to

$$
\begin{equation*}
\langle A\rangle=\operatorname{Tr}\left(\rho^{\lambda} A\right)=\langle\lambda| A|\lambda\rangle \tag{D.26}
\end{equation*}
$$

It is worth noting that the equation $\operatorname{Tr}\left(\rho^{\lambda}\right)^{2}=1$ gives us a criterion for deciding whether a state is pure or not that is invariant under all unitary transformations.

If we choose to work in a representation $\{k\}$ such that $\rho^{\lambda}$ is diagonal, we see that

$$
\begin{equation*}
\rho_{k k^{\prime}}^{\lambda}=\delta_{k \lambda} \delta_{k^{\prime} \lambda} \tag{D.27}
\end{equation*}
$$

and therefore the only non-vanishing matrix element of $\rho^{\lambda}$ is the diagonal element in the $\lambda$ th row and column, which is equal to one. As a result, all the eigenvalues of the pure state density operator $\rho^{\lambda}$ are equal to zero, except one which is equal to unity. This last property is independent of the choice of the representation, and may therefore be used to characterize the density matrix of a pure state.

Let us return to the general density operator (D.11) and density matrix (D.12). Until now we have assumed that the pure states $|\alpha\rangle$ were normalized to unity. If this requirement is dropped, then $0<\operatorname{Tr} \rho \neq 1$ and the basic result (D.13) is replaced by

$$
\begin{equation*}
\langle A\rangle=\frac{\operatorname{Tr}(\rho A)}{\operatorname{Tr} \rho} . \tag{D.28}
\end{equation*}
$$

In the above discussion we have labelled the rows and columns of the density matrix $\rho_{n n^{\prime}}$ by simple indices $n$ and $n^{\prime}$. In general, of course, the symbol $n$ refers to a collection of indices, some of which taking on discrete values while others vary continuously. In many cases, however, we are interested in some particular property of the system (for example the spin). We then omit the dependence on all other variables, keep only the relevant indices and define in that way a reduced density matrix. This is the case for example in Chapter 4, where we discuss the density matrix for a spin $-1 / 2$ system.

## Appendix E

## Clebsch-Gordan and Racah Coefficients

In this appendix we summarize the formulae describing the coupling of two or more angular momenta. This leads to the introduction of Clebsch-Gordan and Racah coefficients as well as higher order $3 n-j$ symbols. For a complete discussion of these topics reference should be made to specialized monographs on angular momentum such as those by Rose (1957) and by Edmonds (1957).

## E.1. CLEBSCH-GORDAN COEFFICIENTS

Let us first consider two independent quantum systems, or parts of a single system, having angular momenta $\mathbf{j}_{1}$ and $\mathbf{j}_{2}$ respectively. We denote by $\psi_{j_{1} m_{1}}(1)$ and $\psi_{j_{2} m_{2}}(2)$ the angular momentum eigenfunctions of these systems which diagonalize the square and the $z$ component of the angular momentum. Thus (with $\hbar=1$ )

$$
\begin{align*}
\mathbf{j}_{1}^{2} \psi_{j_{1} m_{1}}(1) & =j_{1}\left(j_{1}+1\right) \psi_{j_{1} m_{1}}(1)  \tag{E.1}\\
j_{1 z} \psi_{j_{1} m_{1}}(1) & =m_{1} \psi_{j_{1} m_{1}}(1)
\end{align*}
$$

where

$$
\begin{equation*}
m_{1}=-j_{1},-j_{1}+1, \ldots, j_{1} \tag{E.2}
\end{equation*}
$$

and

$$
\begin{align*}
\mathbf{j}_{2}^{2} \psi_{j_{2} m_{2}}(2) & =j_{2}\left(j_{2}+1\right) \psi_{j_{2} m_{2}}(2),  \tag{E.3}\\
j_{2 z} \psi_{j_{2} m_{2}}(2) & =m_{2} \psi_{j_{2} m_{2}}(2)
\end{align*}
$$

where

$$
\begin{equation*}
m_{2}=-j_{2},-j_{2}+1, \ldots, j_{2} \tag{E.4}
\end{equation*}
$$

Here $j_{1 z}$ and $j_{2 z}$ are the $z$ components of $\mathbf{j}_{1}$ and $\mathbf{j}_{2}$ respectively. Simultaneous eigenfunctions of the operators $\mathbf{j}_{1}^{2}, j_{1 z}, \mathbf{j}_{2}^{2}$ and $j_{2 z}$ are then given by the tensor products $\psi_{j_{1} m_{1}}(1) \psi_{j_{2} m_{2}}(2)$.

We now define the total angular momentum $\mathbf{j}$ of the two systems by

$$
\begin{equation*}
\mathbf{j}=\mathbf{j}_{1}+\mathbf{j}_{2} \tag{E.5}
\end{equation*}
$$

and its $z$ component $j_{z}$ by

$$
\begin{equation*}
j_{z}=j_{1 z}+j_{2 z} \tag{E.6}
\end{equation*}
$$

The operators $\mathbf{j}_{1}^{2}, \mathbf{j}_{2}^{2}, \mathbf{j}^{2}$ and $j_{z}$ form a set of commuting operators. Let us denote by $\psi_{j_{1} j_{2} j m}(1,2)$ the coupled eigenfunctions common to the operators $\mathbf{j}_{1}^{2}, \mathbf{j}_{2}^{2}, \mathbf{j}^{2}$ and $j_{z}$. These coupled eigenfunctions satisfy

$$
\begin{align*}
& \mathbf{j}^{2} \psi_{j_{1} j_{2} j m}(1,2)=j(j+1) \psi_{j_{1} j_{2 j m}}(1,2) \\
& j_{z} \psi_{j_{1} j_{2} j m}(1,2)=m \psi_{j_{1} j_{2} j m}(1,2) \tag{E.7}
\end{align*}
$$

where

$$
\begin{equation*}
j=\left|j_{1}-j_{2}\right|, \quad\left|j_{1}-j_{2}\right|+1, \ldots, j_{1}+j_{2} \tag{E.8}
\end{equation*}
$$

and

$$
\begin{equation*}
m=-j,-j+1, \ldots, j \tag{E.9}
\end{equation*}
$$

The $\left(2 j_{1}+1\right)\left(2 j_{2}+1\right)$ coupled eigenfunctions $\psi_{j_{1} j_{2} j m}(1,2)$ common to the operators $\mathbf{j}_{1}^{2}, \mathbf{j}_{2}^{2}, \mathbf{j}^{2}$ and $j_{z}$ are related to the $\left(2 j_{1}+1\right)\left(2 j_{2}+1\right)$ eigenfunctions $\psi_{j_{1} m_{1}}(1) \psi_{j_{2} m_{2}}(2)$ common to the operators $\mathbf{j}_{1}^{2}, j_{1 z}, \mathbf{j}_{2}^{2}$ and $j_{2 z}$ by the unitarity transformation

$$
\begin{equation*}
\psi_{j_{1} j_{2} j m}(1,2)=\sum_{m_{1} m_{2}}\left(j_{1} m_{1} j_{2} m_{2} \mid j m\right) \psi_{j_{1} m_{1}}(1) \psi_{j_{2} m_{2}}(2) \tag{E.10}
\end{equation*}
$$

The coefficients $\left(j_{1} m_{1} j_{2} m_{2} \mid j m\right)$ of this transformation are called vector coupling or Clebsch-Gordan coefficients. These coefficients vanish unless eqs. (E.8) and (E.9) are satisfied and $m=m_{1}+m_{2}$. To define these coefficients unambiguously, the relative phases of the eigenfunctions $\psi_{j_{1} m_{1}}(1) \psi_{j_{2} m_{2}}(2)$ and $\psi_{j_{1} j_{2} j m}(1,2)$ must be specified. We shall adopt here the phase convention of Condon and Shortley (1935) where

$$
\begin{equation*}
\left(j_{1} j_{1} j_{2} j_{2} \mid j_{1}+j_{2} j_{1}+j_{2}\right)=1 \tag{E.11}
\end{equation*}
$$

With this choice of phase the Clebsch-Gordan coefficients are real and satisfy the orthogonality relations

$$
\begin{equation*}
\sum_{m_{1} m_{2}}\left(j_{1} m_{1} j_{2} m_{2} \mid j m\right)\left(j_{1} m_{1} j_{2} m_{2} \mid j^{\prime} m^{\prime}\right)=\delta_{j j^{\prime}} \delta_{m m^{\prime}} \tag{E.12}
\end{equation*}
$$

which reduces to a single summation since $m_{1}+m_{2}=m$, and

$$
\begin{equation*}
\sum_{j m}\left(j_{1} m_{1} j_{2} m_{2} \mid j m\right)\left(j_{1} m_{1}^{\prime} j_{2} m_{2}^{\prime} \mid j m\right)=\delta_{m_{1} m_{1}^{\prime}} \delta_{m_{2} m_{2}^{\prime}} \tag{E.13}
\end{equation*}
$$

Using eq. (E.13) we can invert eq. (E.10) to yield

$$
\begin{equation*}
\psi_{j_{1} m_{1}}(1) \psi_{j_{2} m_{2}}(2)=\sum_{j}\left(j_{1} m_{1} j_{2} m_{2} \mid j m\right) \psi_{j_{1} j_{2} j m}(1,2) \tag{E.14}
\end{equation*}
$$

The Clebsch-Gordan coefficients also satisfy the symmetry relations

$$
\begin{align*}
\left(j_{1} m_{1} j_{2} m_{2} \mid j m\right) & =(-1)^{j_{1}+j_{2}-j}\left(j_{1}-m_{1} j_{2}-m_{2} \mid j-m\right)  \tag{E.15a}\\
\left(j_{1} m_{1} j_{2} m_{2} \mid j m\right) & =(-1)^{j_{1}+j_{2}-j}\left(j_{2} m_{2} j_{1} m_{1} \mid j m\right)  \tag{E.15b}\\
\left(j_{1} m_{1} j_{2} m_{2} \mid j m\right) & =(-1)^{j_{2}+m_{2}}\left(\frac{2 j+1}{2 j_{1}+1}\right)^{1 / 2} \\
& \times\left(j-m j_{2} m_{2} \mid j_{1}-m_{1}\right)  \tag{E.15c}\\
\left(j_{1} m_{1} j_{2} m_{2} \mid j m\right) & =(-1)^{j_{1}-m_{1}}\left(\frac{2 j+1}{2 j_{2}+1}\right)^{1 / 2} \\
& \times\left(j_{1} m_{1} j-m \mid j_{2}-m_{2}\right) \tag{E.15d}
\end{align*}
$$

Further symmetry relations can be obtained by combining these equations.
These symmetry relations can be simplified by introducing the $3-j$ symbols defined by Wigner (1940). These are defined by

$$
\left(\begin{array}{ccc}
j_{1} & j_{2} & j_{3}  \tag{E.16}\\
m_{1} & m_{2} & m_{3}
\end{array}\right)=(-1)^{j_{1}-j_{2}-m_{3}}\left(2 j_{3}+1\right)^{-1 / 2}\left(j_{1} m_{1} j_{2} m_{2} \mid j_{3}-m_{3}\right)
$$

The $3-j$ symbols are invariant for even permutations of the columns and are multiplied by $(-1)^{j_{1}+j_{2}+j_{3}}$ for odd permutations or when the signs of $m_{1}, m_{2}$ and $m_{3}$ are changed. Thus

$$
\begin{align*}
\left(\begin{array}{ccc}
j_{1} & j_{2} & j_{3} \\
m_{1} & m_{2} & m_{3}
\end{array}\right) & =\left(\begin{array}{ccc}
j_{2} & j_{3} & j_{1} \\
m_{2} & m_{3} & m_{1}
\end{array}\right)=\left(\begin{array}{ccc}
j_{3} & j_{1} & j_{2} \\
m_{3} & m_{1} & m_{2}
\end{array}\right) \\
& =(-1)^{j_{1}+j_{2}+j_{3}}\left(\begin{array}{ccc}
j_{1} & j_{3} & j_{2} \\
m_{1} & m_{3} & m_{2}
\end{array}\right) \tag{E.17}
\end{align*}
$$

and

$$
\left(\begin{array}{ccc}
j_{1} & j_{2} & j_{3}  \tag{E.18}\\
m_{1} & m_{2} & m_{3}
\end{array}\right)=(-1)^{j_{1}+j_{2}+j_{3}}\left(\begin{array}{ccc}
j_{1} & j_{2} & j_{3} \\
-m_{1} & -m_{2} & -m_{3}
\end{array}\right)
$$

The orthogonality relations satisfied by the $3-j$ symbols are

$$
\sum_{m_{1} m_{2}}\left(\begin{array}{ccc}
j_{1} & j_{2} & j_{3}  \tag{E.19}\\
m_{1} & m_{2} & m_{3}
\end{array}\right)\left(\begin{array}{ccc}
j_{1} & j_{2} & j_{3}^{\prime} \\
m_{1} & m_{2} & m_{3}^{\prime}
\end{array}\right)=\left(2 j_{3}+1\right)^{-1} \delta_{j_{3} j_{3}^{\prime}} \delta_{m_{3} m_{3}^{\prime}}
$$

and

$$
\sum_{j_{3} m_{3}}\left(2 j_{3}+1\right)\left(\begin{array}{ccc}
j_{1} & j_{2} & j_{3}  \tag{E.20}\\
m_{1} & m_{2} & m_{3}
\end{array}\right)\left(\begin{array}{ccc}
j_{1} & j_{2} & j_{3} \\
m_{1}^{\prime} & m_{2}^{\prime} & m_{3}
\end{array}\right)=\delta_{m_{1} m_{1}^{\prime}} \delta_{m_{2} m_{2}^{\prime}}
$$

TABLE E.1. Explicit values for the Clebsch-Gordan coefficients $\left(j_{1} m-m_{2}^{1 / 2} m_{2} \mid j m\right)$
$\left.\begin{array}{cc}\hline j & m_{2}=\frac{1}{2} \\ j_{1}+\frac{1}{2} & {\left[\frac{j_{1}+m+(1 / 2)}{2 j_{1}+1}\right]^{1 / 2}} \\ j_{1}-\frac{1}{2} & -\left[\frac{j_{1}-m+(1 / 2)}{2 j_{1}+1}\right]^{1 / 2} \\ \hline 2 j_{1}+1\end{array}\right]^{1 / 2} \quad\left[\frac{j_{1}+m+(1 / 2)}{2 j_{1}+1}\right]^{1 / 2}$

Returning to Clebsch-Gordan coefficients we have the following important relations

$$
\begin{equation*}
\left(j_{1} 0 j_{2} 0 \mid j 0\right)=0 \text { unless } j_{1}+j_{2}+j_{3} \text { is even } \tag{E.21}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(j_{1} m_{1} 00 \mid j m\right)=\delta_{j_{1} j} \delta_{m_{1} m} \tag{E.22}
\end{equation*}
$$

The Clebsch-Gordan coefficients can be calculated using the orthogonality and the symmetry relations which they satisfy (Edmonds, 1957). Since the general formula is quite complicated we limit ourselves here to giving their values in Tables E. 1 and E. 2 for the cases of most interest in this monograph when $j_{2}=$ $1 / 2$ and $j_{2}=1$.

## E.2. RACAH COEFFICIENTS

We now consider the addition of three angular momenta $\mathbf{j}_{1}, \mathbf{j}_{2}$ and $\mathbf{j}_{3}$ to form the total angular momentum $\mathbf{j}$ given by

$$
\begin{equation*}
\mathbf{j}=\mathbf{j}_{1}+\mathbf{j}_{2}+\mathbf{j}_{3} \tag{E.23}
\end{equation*}
$$

There is no unique way of carrying out this addition. We may first couple $\mathbf{j}_{1}$ and $\mathbf{j}_{2}$ to give the resultant $\mathbf{j}_{12}$ and then couple this to $\mathbf{j}_{3}$ to give $\mathbf{j}$. Alternatively, we may couple $\mathbf{j}_{1}$ to the resultant $\mathbf{j}_{23}$ of coupling $\mathbf{j}_{2}$ and $\mathbf{j}_{3}$ to give $\mathbf{j}$. Finally, we may couple $\mathbf{j}_{1}$ and $\mathbf{j}_{3}$ to give the resultant $\mathbf{j}_{13}$ which is then coupled with $\mathbf{j}_{2}$ to give $\mathbf{j}$. These three representations are related by unitary transformations which are expressed in terms of Racah coefficients introduced by Racah (1942, 1943).

Let us consider the connection between the first two representations described above which are characterized by the intermediate angular momenta

$$
\begin{equation*}
\mathbf{j}_{12}=\mathbf{j}_{1}+\mathbf{j}_{2} \text { and } \mathbf{j}_{23}=\mathbf{j}_{2}+\mathbf{j}_{3} \tag{E.24}
\end{equation*}
$$

where the corresponding eigenfunctions are denoted by

$$
\begin{equation*}
\psi_{j m}\left(j_{12}\right) \text { and } \psi_{j m}\left(j_{23}\right) \tag{E.25}
\end{equation*}
$$

TABLE E.2. Explicit values for the Clebsch-Gordan coefficients ( $\left.j_{1} m-m_{2} 1 m_{2} \mid j m\right)$

| $j$ | $m_{2}=1$ | $m_{2}=0$ | $m_{2}=-1$ |
| :---: | :---: | :---: | :---: |
| $j_{1}+1$ | $\left[\frac{\left(j_{1}+m\right)\left(j_{1}+m+1\right)}{\left(2 j_{1}+1\right)\left(2 j_{1}+2\right)}\right]^{1 / 2}$ | $\left[\frac{\left(j_{1}-m+1\right)\left(j_{1}+m+1\right)}{\left(2 j_{1}+1\right)\left(j_{1}+1\right)}\right]^{1 / 2}$ | $\left[\frac{\left(j_{1}-m\right)\left(j_{1}-m+1\right)}{\left(2 j_{1}+1\right)\left(2 j_{1}+2\right)}\right]^{1 / 2}$ |
| $j_{1}$ | $-\left[\frac{\left(j_{1}+m\right)\left(j_{1}-m+1\right)}{2 j_{1}\left(j_{1}+1\right)}\right]^{1 / 2}$ | $\frac{m}{\left[j_{1}\left(j_{1}+1\right)\right]^{1 / 2}}$ | $\left[\frac{\left(j_{1}-m\right)\left(j_{1}+m+1\right)}{2 j_{1}\left(j_{1}+1\right)}\right]^{1 / 2}$ |
| $j_{1}-1$ | $\left[\frac{\left(j_{1}-m\right)\left(j_{1}-m+1\right)}{2 j_{1}\left(2 j_{1}+1\right)}\right]^{1 / 2}$ | $-\left[\frac{\left(j_{1}-m\right)\left(j_{1}+m\right)}{j_{1}\left(2 j_{1}+1\right)}\right]^{1 / 2}$ | $\left[\frac{\left(j_{1}+m+1\right)\left(j_{1}+m\right)}{2 j_{1}\left(2 j_{1}+1\right)}\right]^{1 / 2}$ |

respectively. These two representations are related by the transformation

$$
\begin{equation*}
\psi_{j m}\left(j_{12}\right)=\sum_{j_{23}} R\left(j_{23} j_{12}\right) \psi_{j m}\left(j_{23}\right) . \tag{E.26}
\end{equation*}
$$

The Racah coefficient $W$ is defined by the equation

$$
\begin{equation*}
R\left(j_{23} j_{12}\right)=\left[\left(2 j_{23}+1\right)\left(2 j_{12}+1\right)\right]^{1 / 2} W\left(j_{1} j_{2} j j_{3} ; j_{12} j_{23}\right) \tag{E.27}
\end{equation*}
$$

We can derive a relation between the Racah coefficients and the ClebschGordan coefficients by expressing $\psi_{j m}\left(j_{12}\right)$ and $\psi_{j m}\left(j_{23}\right)$ in terms of $\psi_{j_{1} m_{1}}$, $\psi_{j_{2} m_{2}}$ and $\psi_{j_{3} m_{3}}$ using eq. (E.10). We obtain

$$
\begin{align*}
\psi_{j m}\left(j_{12}\right)= & \sum_{m_{1} m_{12}}\left(j_{1} m_{1} j_{2} m_{12}-m_{1} \mid j_{12} m_{12}\right)  \tag{E.28}\\
& \times\left(j_{12} m_{12} j_{3} m-m_{12} \mid j m\right) \psi_{j_{1} m_{1}} \psi_{j_{2} m_{12}-m_{1}} \psi_{j_{3} m-m_{12}}
\end{align*}
$$

and

$$
\begin{align*}
\psi_{j m}\left(j_{23}\right)= & \sum_{m_{2} m_{23}}\left(j_{2} m_{2} j_{3} m_{23}-m_{2} \mid j_{23} m_{23}\right)  \tag{E.29}\\
& \times\left(j_{1} m-m_{23} j_{23} m_{23} \mid j m\right) \psi_{j_{1} m-m_{23}} \psi_{j_{2} m_{2}} \psi_{j_{3} m_{23}-m_{2}}
\end{align*}
$$

Substituting these results into eq. (E.26) and using eq. (E.27) gives

$$
\begin{align*}
& \sum_{f}[(2 e+1)(2 f+1)]^{1 / 2} W(a b c d ; e f)(b \beta d \delta \mid f \beta+\delta)(a \alpha f \beta+\delta \mid c \alpha+\beta+\delta) \\
&=(a \alpha b \beta \mid e \alpha+\beta)(e \alpha+\beta d \delta \mid c \alpha+\beta+\delta) \tag{E.30a}
\end{align*}
$$

Also, using the properties of the Clebsch-Gordan coefficients defined by eqs. (E.12) - (E.15) we obtain the following additional relations

$$
\begin{align*}
& {[(2 e+1)(2 f+1)]^{1 / 2} W(a b c d ; e f)(a \alpha f \beta+\delta \mid c \alpha+\beta+\delta)} \\
& \quad=\sum_{\beta}(a \alpha b \beta \mid e \alpha+\beta)(e \alpha+\beta d \delta \mid c \alpha+\beta+\delta)(b \beta d \delta \mid f \beta+\delta) \tag{E.30b}
\end{align*}
$$

where $\beta+\delta$ is a fixed parameter and

$$
\begin{align*}
& {[(2 e+1)(2 f+1)]^{1 / 2} W(a b c d ; e f)=\sum_{\alpha \beta}(a \alpha b \beta \mid e \alpha+\beta)}  \tag{E.30c}\\
& \times(e \alpha+\beta d \delta \mid c \alpha+\beta+\delta)(b \beta d \delta \mid f \beta+\delta)(a \alpha f \beta+\delta \mid c \alpha+\beta+\delta)
\end{align*}
$$

where $\alpha+\beta+\delta$ is a fixed parameter.


FIGURE E.1. The tetrahedron illustrating the triangular relations satisfied by the arguments of the Racah coefficient $W(a b c d ; e f)$.

It is clear from the above definitions that the six angular momenta in $W(a b c d ; e f)$ satisfy the four triangular relations

$$
\begin{equation*}
\Delta(a b e), \quad \Delta(c d e), \quad \Delta(a c f), \quad \Delta(b d f) \tag{E.31}
\end{equation*}
$$

where, for example, the notation $\Delta(a b e)$ means that the three angular momenta $a, b$ and $e$ form the sides of a triangle. These four triangular relations can be combined by representing the angular momenta by the sides of a tetrahedron as illustrated in figure E.1.

The Racah coefficients also satisfy certain symmetry relations under the twenty-four possible permutations of the six arguments which preserve the four triangular relations. These symmetry relations can be simplified using the $6-j$ symbol introduced by Wigner (1940), which is defined by

$$
\left\{\begin{array}{lll}
j_{1} & j_{2} & j_{3}  \tag{E.32}\\
j_{4} & j_{5} & j_{6}
\end{array}\right\}=(-1)^{j_{1}+j_{2}+j_{4}+j_{5}} W\left(j_{1} j_{2} j_{5} j_{4} ; j_{3} j_{6}\right)
$$

The $6-j$ symbol is left invariant under any permutations of the three columns. It is also invariant under interchange of the upper and lower arguments in any two columns, e.g.

$$
\left\{\begin{array}{lll}
j_{1} & j_{2} & j_{3}  \tag{E.33}\\
j_{4} & j_{5} & j_{6}
\end{array}\right\}=\left\{\begin{array}{lll}
j_{1} & j_{5} & j_{6} \\
j_{4} & j_{2} & j_{3}
\end{array}\right\} .
$$

Returning to the Racah coefficients, one can show that they satisfy the orthogonality relation

$$
\begin{equation*}
\sum_{e}(2 e+1)(2 f+1) W(a b c d ; e f) W(a b c d ; e g)=\delta_{f g} \tag{E.34}
\end{equation*}
$$

and the Racah sum rule

$$
\begin{equation*}
\sum_{e}(-1)^{a+b-e}(2 e+1) W(a b c d ; e f) W(b a c d ; e g)=W(a g f b ; d c) \tag{E.35}
\end{equation*}
$$

In addition

$$
\begin{equation*}
W(a b c d ; 0 f)=\frac{(-1)^{f-b-d} \delta_{a b} \delta_{c d}}{[(2 b+1)(2 d+1)]^{1 / 2}} \tag{E.36}
\end{equation*}
$$

The general closed expression for the Racah coefficient is too complicated to reproduce here but may be found for example in Rose (1957) or Edmonds (1957).

## E.3. $9-j$ SYMBOLS

In many applications, we are interested in determining the transformation between two coupling schemes of four angular momenta. This occurs for example in the transformation from $L S$ to $j j$ coupling for two particles possessing both orbital and spin angular momenta. The $9-j$ symbol introduced by Wigner (1940) is defined by the following relation

$$
\begin{align*}
& \left\langle\left(j_{1} j_{2}\right) j_{12},\left(j_{3} j_{4}\right) j_{34}, j m \mid\left(j_{1} j_{3}\right) j_{13},\left(j_{2} j_{4}\right) j_{24}, j m\right\rangle \\
& =\left[\left(2 j_{12}+1\right)\left(2 j_{34}+1\right)\left(2 j_{13}+1\right)\left(2 j_{24}+1\right)\right]^{1 / 2}\left\{\begin{array}{ccc}
j_{1} & j_{2} & j_{12} \\
j_{3} & j_{4} & j_{34} \\
j_{13} & j_{24} & j
\end{array}\right\} . \tag{E.37}
\end{align*}
$$

The $9-j$ symbol can be written as the sum over a product of three Racah coefficients by expressing the bra vector in eq. (E.37) in terms of the ket vector in eq. (E.37) by repeated use of the recoupling transformation defined by eqs. (E.26) and (E.27). We find that

$$
\begin{align*}
\left\{\begin{array}{lll}
j_{11} & j_{12} & j_{13} \\
j_{21} & j_{22} & j_{23} \\
j_{31} & j_{32} & j_{33}
\end{array}\right\} & =\sum_{\kappa}(-1)^{2 \kappa}(2 \kappa+1)\left\{\begin{array}{ccc}
j_{11} & j_{21} & j_{31} \\
j_{32} & j_{33} & \kappa
\end{array}\right\}  \tag{E.38}\\
& \times\left\{\begin{array}{ccc}
j_{12} & j_{22} & j_{32} \\
j_{21} & \kappa & j_{23}
\end{array}\right\}\left\{\begin{array}{ccc}
j_{13} & j_{23} & j_{33} \\
\kappa & j_{11} & j_{12}
\end{array}\right\}
\end{align*}
$$

An even permutation of the rows or columns of the $9-j$ symbol leaves the symbol unchanged as does the transposition obtained by interchanging rows and columns. An odd transposition of the rows or columns causes the symbol to be multiplied by the factor

$$
\begin{equation*}
(-1)^{j_{11}+j_{12}+j_{13}+j_{21}+j_{22}+j_{23}+j_{31}+j_{32}+j_{33}} . \tag{E.39}
\end{equation*}
$$

The $9-j$ symbols also satisfy the orthogonality relation

$$
\begin{align*}
& \sum_{j_{12} j_{34}}\left(2 j_{12}+1\right)\left(2 j_{34}+1\right)\left(2 j_{13}+1\right)\left(2 j_{24}+1\right) \\
& \quad \times\left\{\begin{array}{ccc}
j_{1} & j_{2} & j_{12} \\
j_{3} & j_{4} & j_{34} \\
j_{13} & j_{24} & j
\end{array}\right\}\left\{\begin{array}{ccc}
j_{1} & j_{2} & j_{12} \\
j_{3} & j_{4} & j_{34} \\
j_{13}^{\prime} & j_{24}^{\prime} & j
\end{array}\right\}=\delta_{j_{13} j_{13}^{\prime}} \delta_{j_{24} j_{24}^{\prime}} \tag{E.40}
\end{align*}
$$

and the sum rule

$$
\begin{align*}
& \sum_{j_{13} j_{24}}(-1)^{2 j_{2}+j_{24}+j_{23}-j_{34}\left(2 j_{13}+1\right)\left(2 j_{24}+1\right)} \\
& \times\left\{\begin{array}{ccc}
j_{1} & j_{2} & j_{12} \\
j_{3} & j_{4} & j_{34} \\
j_{13} & j_{24} & j
\end{array}\right\}\left\{\begin{array}{ccc}
j_{1} & j_{3} & j_{13} \\
j_{4} & j_{2} & j_{24} \\
j_{14} & j_{23} & j
\end{array}\right\}=\left\{\begin{array}{ccc}
j_{1} & j_{2} & j_{12} \\
j_{4} & j_{3} & j_{34} \\
j_{14} & j_{23} & j
\end{array}\right\} \tag{E.41}
\end{align*}
$$

When one argument of a $9-j$ symbol is zero it reduces to a $6-j$ symbol times a factor. As an example we have

$$
\left\{\begin{array}{lll}
a & b & e  \tag{E.42}\\
c & d & e \\
f & f & 0
\end{array}\right\}=\frac{(-1)^{b+c+e+f}}{[(2 e+1)(2 f+1)]^{1 / 2}}\left\{\begin{array}{lll}
a & b & e \\
d & c & f
\end{array}\right\}
$$

The corresponding results when the zero appears in one of the other positions can be obtained using the symmetry properties of the $9-j$ symbols discussed above.

## E.4. HIGHER ORDER $3 n-j$ SYMBOLS

In the theory of electron collisions with complex atoms, $3 n-j$ symbols with $n \geq 4$ often arise involving the recoupling of more than four angular momenta. These recoupling coefficients can be expressed as sums over products of Racah coefficients by repeated use of eqs. (E.26) and (E.27) in the same way as eq. (E.38) for the $9-j$ symbol was derived. We shall not discuss here the detailed properties of these higher order $3 n-j$ symbols. We remark, however, that a computer code NJSYM has been written by Burke (1970) which enables a general recoupling coefficient for an arbitrary number of angular momenta to be calculated. This code has been incorporated into a number of atomic structure and electron atom collision program packages.

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