

# Linear Algebra

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Topic : Linear      Transformations

## LINEAR TRANSFORMATION:

DEF:

A linear transformation is a transformation  $T: R^n \rightarrow R^m$  satisfying

1.  $T(u + v) = T(u) + T(v)$
2.  $T(cu) = cT(u)$

For all vectors  $u, v$  in  $R^n$  and all scalar c

Or

$$T(ax + by) = T(ax) + T(by) = aT(x) + bT(y)$$

For all  $x, y$  in  $R^n$

## Properties of Linear Transformation

**Theorem:** Let  $V$  and  $W$  be two vector spaces. Suppose  $T: V \rightarrow W$  is a linear transformation. Then

1.  $T(0) = 0$
2.  $T(-v) = -T(v)$  for all  $v$  in  $V$
3.  $T(u - v) = T(u) - T(v)$ , for all  $u, v$  in  $V$
4. if  $v = c_1v_1 + c_2v_2 + \dots + c_nv_n$ , then

$$T(v) = T(c_1v_1 + c_2v_2 + \dots + c_nv_n) = c_1T(v_1) + c_2T(v_2) + c_3T(v_3) + \dots + c_nT(v_n)$$

## Example : 01 Matrix Transformation

$T : M_{22} \rightarrow R$

$$T \left( \begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = 3a - 4b + c - d$$

Sol

$$T(u - v) = T(u) - T(v)$$

$$T(v) = T \left( \begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = 3a - 4b + c - d$$

$$T(u) = T \left( \begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = 3a - 4b + c - d$$

$$T(u - v) = \begin{bmatrix} a & b \\ c & d \end{bmatrix} - \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = 30 - 40 + 0 - 0 = 0$$

Example : 02 Matrix Transformation

$T : M_{22} \rightarrow R$

$$T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = a^2 + b^2$$

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### EXAMPLE :03 The Zero Transformation

The Mapping  $T: V \rightarrow W$  is zero transformation such that  $T(v)=0$

Sol:

1.  $T(u + v) = T(u) + T(v) = 0 + 0 = 0$
2.  $T(k u) = kT(u) = k(0) = 0$

### Example 04: The Identity Operator

The Mapping  $I: V \rightarrow W$  is Identity Operator such as  $I(v) = v$

Sol:

$$\begin{aligned}T(u + v) &= T(u) + T(v) \\T(k u) &= kT(u)\end{aligned}$$

Example 05: A Linear Transformation from  $P_n$  to  $P_{n+1}$

Let  $p = p(x) = c_0 + c_1x + c_2x^2 + \cdots + c_nx^n$  and transformation is defined by

$$T(p(x)) = T(c_0 + c_1x + c_2x^2 + \cdots + c_nx^n) = xp(x)$$

Sol:

$$1. \quad T(p_1 + p_2) = T(p_1(x) + p_2(x)) = x(p_1(x) + p_2(x))$$

$$= x(p_1(x)) + x(p_2(x)) = T(p_1) + T(p_2)$$

$$2. \quad T(kp) = T(kp(x)) = x(kp(x)) = k(xp(x)) = kT(p)$$