

CURL OF A VECTOR FUNCTION:

Let $\vec{A}(x, y, z)$ be a differentiable vector point function in a certain region of space. Then the curl or rotation of \vec{A} , written as $\nabla \times \vec{A}$ or $\text{Curl } \vec{A}$ is defined by

$\nabla \times \vec{A} =$	\hat{i}	\hat{j}	\hat{k}	where $\vec{A} = A_1\hat{i} + A_2\hat{j} + A_3\hat{k}$
	$\frac{\partial}{\partial x}$	$\frac{\partial}{\partial y}$	$\frac{\partial}{\partial z}$	
	A_1	A_2	A_3	

Note:

If \vec{A} is a constant vector, then $\nabla \times \vec{A} = \vec{0}$.

If $\nabla \times \vec{A} = \vec{0}$ in some R, then \vec{A} is called an irrotational vector point function in that region.

EXAMPLE 6:

$\vec{A} = xz^3\hat{i} - 2x^2yz\hat{j} + 2yz^4\hat{k}$ $\nabla \times \vec{A} = ?$ at $P(1, -1, 1)$.

$\nabla \times \vec{A} =$	\hat{i}	\hat{j}	\hat{k}
	$\frac{\partial}{\partial x}$	$\frac{\partial}{\partial y}$	$\frac{\partial}{\partial z}$
	xz^3	$-2x^2yz$	$2yz^4$

$$\nabla \times \vec{A} = \hat{i}(4xyz - 0) - \hat{j}(0 - 4xy^2z) + \hat{k}(4xy^2z - 0)$$

$$= -4xy^2z\hat{i} + 3xz^3\hat{j} - 4xy^2z\hat{k}$$

$$|\nabla \times \vec{A}|_P = -4(1)(-1)(1)\hat{i} + 3(1)(1)^3\hat{j} - 4(1)(-1)(1)\hat{k}$$

$$= 4\hat{i} + 3\hat{j} + 4\hat{k}$$

$\nabla \times \vec{A} = \hat{i}(2z^4 + 2x^2y) - \hat{j}(0 - 3xz^2) + \hat{k}(-4xyz - 0)$

$\nabla \times \vec{A} = \hat{i}(2z^4 + 2x^2y) + \hat{j}(3xz^2) - \hat{k}(4xyz)$

$$\nabla \times \vec{A} = (2z^4 + 2x^2y) \hat{i} + (3xz^2) \hat{j} - (4xy^3) \hat{k}$$

$$\nabla \times \vec{A} \Big|_P = [2(1) + 2(1)(-1)] \hat{i} + [3(1)(1)] \hat{j} - [4(1)(-1)(1)] \hat{k}$$

$$= 0 \hat{i} + 3 \hat{j} + 4 \hat{k}$$

$$\nabla \times \vec{A} \Big|_P = 3 \hat{j} + 4 \hat{k}$$

PROPERTIES OF THE CURL:

THEOREM 7: $\vec{A} = A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}$ $\vec{B} = B_1 \hat{i} + B_2 \hat{j} + B_3 \hat{k}$

(i) $\nabla \times (\vec{A} + \vec{B}) = \nabla \times \vec{A} + \nabla \times \vec{B}$

$$\nabla \times (\vec{A} + \vec{B}) = \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) \times \left((A_1 + B_1) \hat{i} + (A_2 + B_2) \hat{j} + (A_3 + B_3) \hat{k} \right)$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 + B_1 & A_2 + B_2 & A_3 + B_3 \end{vmatrix}$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix} + \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ B_1 & B_2 & B_3 \end{vmatrix}$$

$$= (\nabla \times \vec{A}) + (\nabla \times \vec{B})$$

$$\Rightarrow \nabla \times (\vec{A} + \vec{B}) = (\nabla \times \vec{A}) + (\nabla \times \vec{B})$$

(ii) $\nabla \times (\phi \vec{A}) = \phi (\nabla \times \vec{A}) + \nabla \phi \times \vec{A}$

$$\nabla \times \phi \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \phi A_1 & \phi A_2 & \phi A_3 \end{vmatrix}$$

$$= \left[\frac{\partial}{\partial y} (\phi A_3) - \frac{\partial}{\partial z} (\phi A_2) \right] \hat{i} - \left[\frac{\partial}{\partial x} (\phi A_3) - \frac{\partial}{\partial z} (\phi A_1) \right] \hat{j}$$

$$+ \left[\frac{\partial}{\partial x} (\phi A_2) - \frac{\partial}{\partial y} (\phi A_1) \right] \hat{k}$$

$$= \left[\phi \frac{\partial A_3}{\partial y} + A_3 \frac{\partial \phi}{\partial y} - \phi \frac{\partial A_2}{\partial z} - A_2 \frac{\partial \phi}{\partial z} \right] \hat{i}$$

$$+ \left[-\phi \frac{\partial A_3}{\partial x} - A_3 \frac{\partial \phi}{\partial x} + \phi \frac{\partial A_1}{\partial z} + A_1 \frac{\partial \phi}{\partial z} \right] \hat{j}$$

$$+ \left[\phi \frac{\partial A_2}{\partial x} + A_2 \frac{\partial \phi}{\partial x} - \phi \frac{\partial A_1}{\partial y} - A_1 \frac{\partial \phi}{\partial y} \right] \hat{k}$$

$$= \left[\phi \left[\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right] \hat{i} - \phi \left[\frac{\partial A_3}{\partial x} - \frac{\partial A_1}{\partial z} \right] \hat{j} + \phi \left[\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right] \hat{k} \right]$$

$$+ \left[A_3 \frac{\partial \phi}{\partial y} - A_2 \frac{\partial \phi}{\partial z} \right] \hat{i} - \left[A_3 \frac{\partial \phi}{\partial x} - A_1 \frac{\partial \phi}{\partial z} \right] \hat{j} + \left[A_2 \frac{\partial \phi}{\partial x} - A_1 \frac{\partial \phi}{\partial y} \right] \hat{k}$$

$$= \phi \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix} + \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix}$$

$$= \phi (\nabla \times \vec{A}) + (\nabla \phi) \times \vec{A}$$

$$\Rightarrow \nabla \times (\phi \vec{A}) = \phi (\nabla \times \vec{A}) + \nabla \phi \times \vec{A} \text{ Hence proved.}$$

(iii) $\nabla \times (\nabla \phi) = \vec{0}$ (curl grad $\phi = \vec{0}$)

$$\nabla \times \nabla \phi = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \end{vmatrix}$$

$$= \left[\frac{\partial^2 \phi}{\partial y \partial x} - \frac{\partial^2 \phi}{\partial x \partial y} \right] \hat{i} + \left[\frac{\partial^2 \phi}{\partial z \partial y} - \frac{\partial^2 \phi}{\partial y \partial z} \right] \hat{j} + \left[\frac{\partial^2 \phi}{\partial z \partial x} - \frac{\partial^2 \phi}{\partial x \partial z} \right] \hat{k}$$

$$= 0 \hat{i} + 0 \hat{j} + 0 \hat{k}$$

$$\Rightarrow \nabla \times (\nabla \phi) = \vec{0}$$

(iv) $\nabla \cdot (\nabla \times \vec{A}) = 0$ (div curl $\vec{A} = 0$)

$$\nabla \cdot (\nabla \times \vec{A}) = \nabla \cdot \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix}$$

$$\begin{aligned}
 &= \nabla \cdot \left[\left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \hat{i} + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \hat{j} + \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \hat{k} \right] \\
 &= \frac{\partial}{\partial x} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) + \frac{\partial}{\partial y} \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) + \frac{\partial}{\partial z} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \\
 &= \frac{\partial^2 A_3}{\partial x \partial y} - \frac{\partial^2 A_2}{\partial x \partial z} + \frac{\partial^2 A_1}{\partial y \partial z} - \frac{\partial^2 A_3}{\partial x \partial y} + \frac{\partial^2 A_2}{\partial y \partial x} - \frac{\partial^2 A_1}{\partial y \partial z} + \frac{\partial^2 A_3}{\partial z \partial x} - \frac{\partial^2 A_1}{\partial z \partial y} + \frac{\partial^2 A_2}{\partial z \partial x} - \frac{\partial^2 A_3}{\partial z \partial y}
 \end{aligned}$$

$$= 0$$

$$\Rightarrow \nabla \cdot (\nabla \times \vec{A}) = 0$$